

Tactile discrimination of surfaces:

Role of physicochemical, mechanical and morphological human finger properties on the in vivo friction behavior

PH Cornuault¹, MA Bueno², L Carpentier¹, G Monteil¹

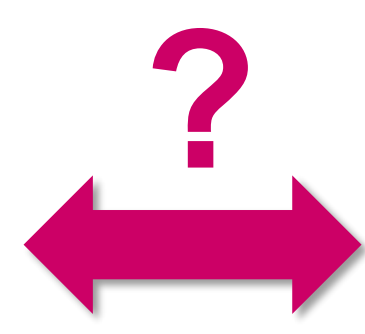
¹ Femto-ST, UMR CNRS 6174, Applied Mechanics Department, 24 rue de l'épitahe, Besançon, France
² Laboratoire de Physique et Mécanique Textile, EA CNRS 4365, 11 rue Alfred Werner, Mulhouse, France

Aim of this study

Development of tactile interfaces & stimulators → Friction forces modulation between the fingertip and an active counterpart

Problem: fingertip properties variability between individuals

- Fingertip roughness
- Skin mechanical properties
- Stratum Corneum chemistry



Friction behavior during touch

For 26 individuals (13 females and 13 males)

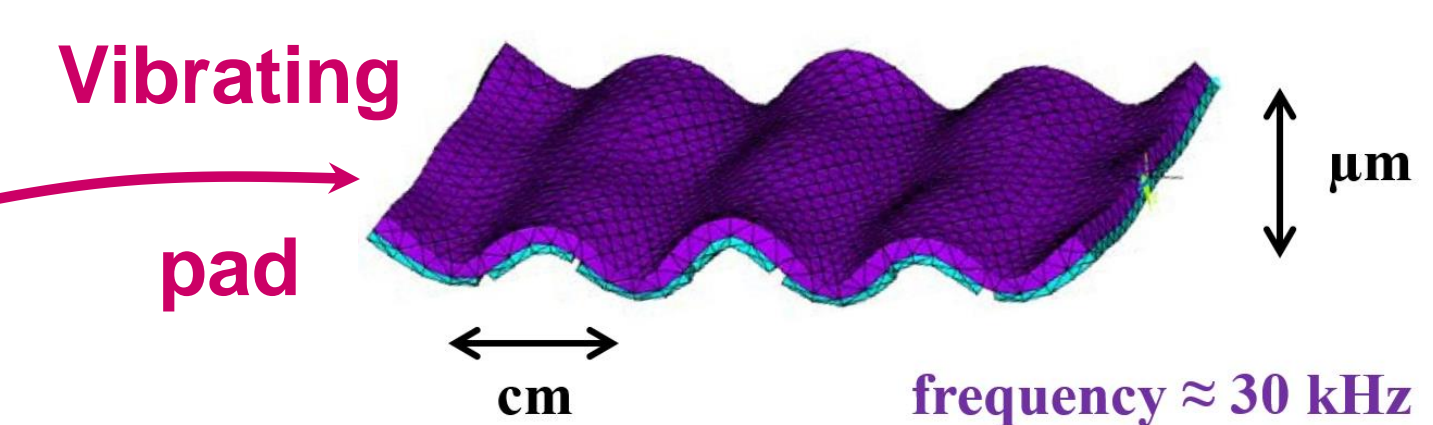
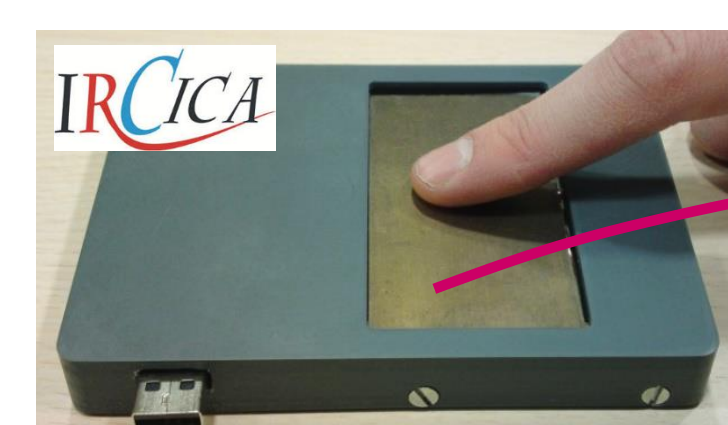
Surfaces scanned

Two sets of surfaces situated in the sticky / slippery psycho-perceptual dimension:

1. Real surfaces

| Sticky | Slippery |
|---|--------------------------------|
| Varnished ABS (R _a = 1.6 μm) | PTFE (R _a = 0.7 μm) |
| No vibration | Maximum amplitude |

2. Stimtac: Simulated surfaces

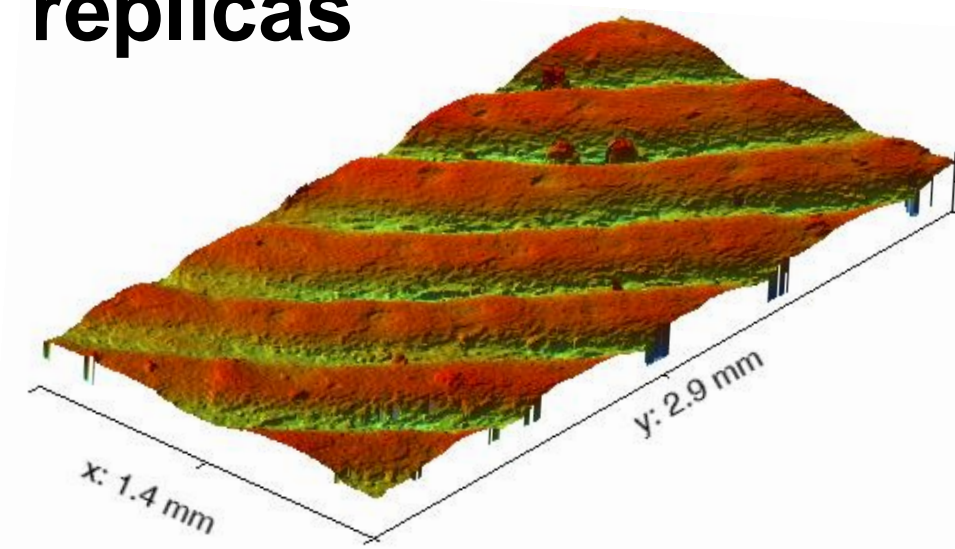


Squeeze film effect

Fingertip properties characterization

1. Roughness

3D analysis of finger replicas



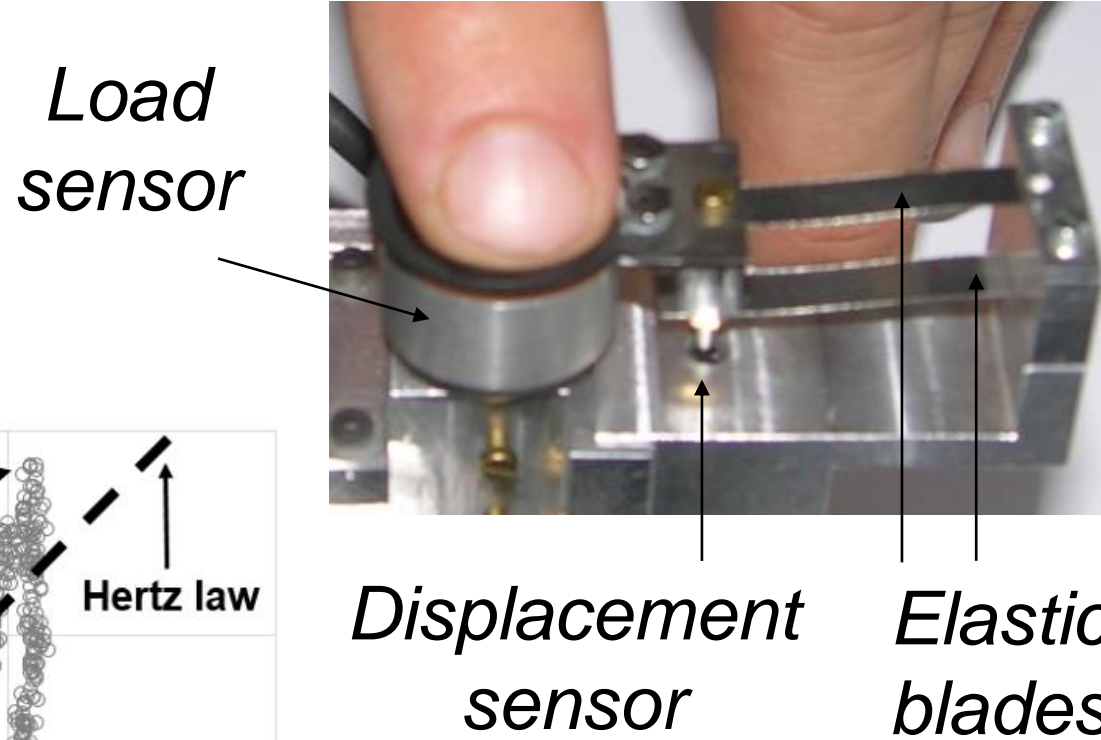
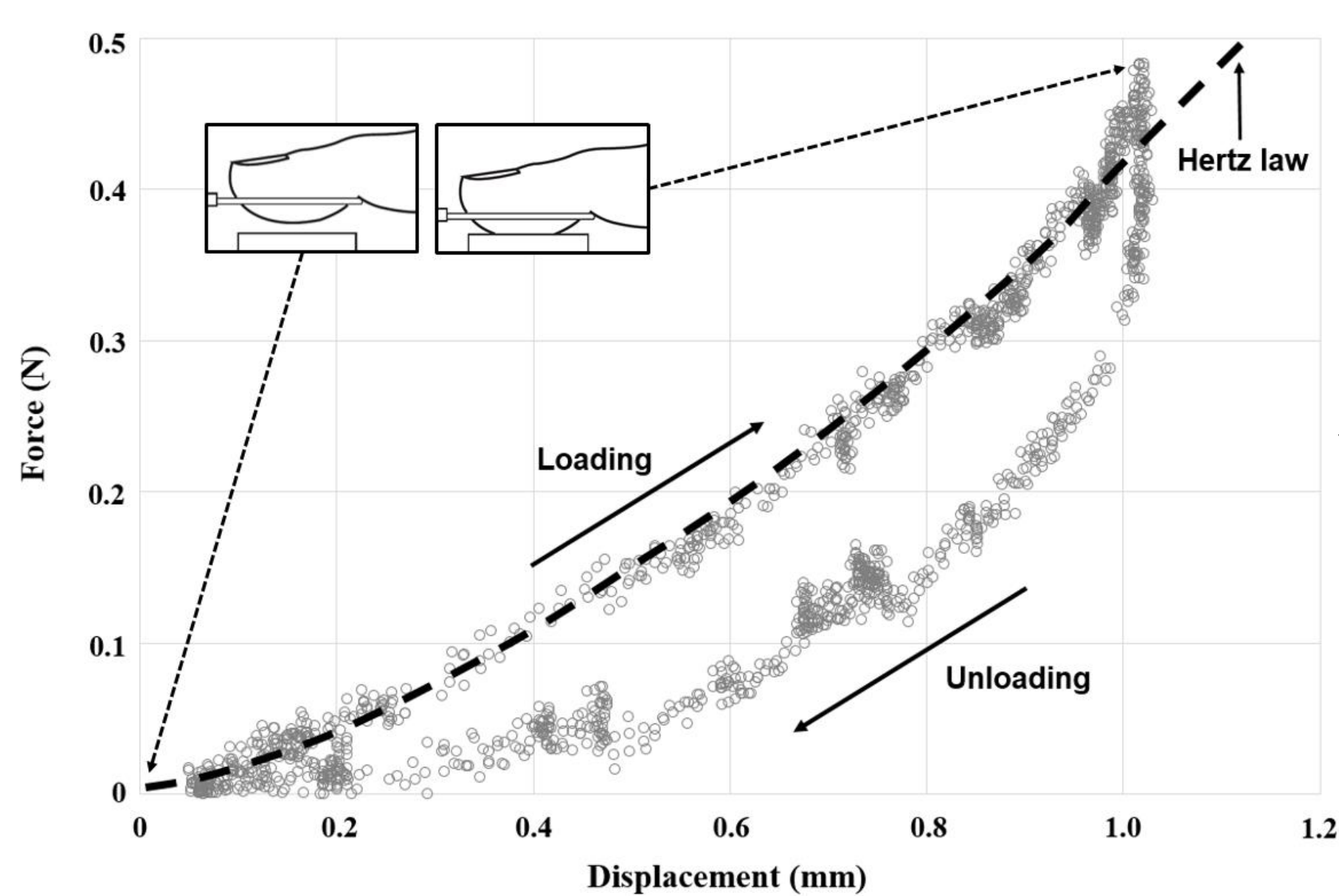
Spatial period Sp from 338 to 600 μm

Epidermal ridge: R_t from 60 to 160 μm

2. Mechanical properties

Specific indentation device

Maximal loading ≈ 0.5 N



Indentation curve fitting with Hertz law:

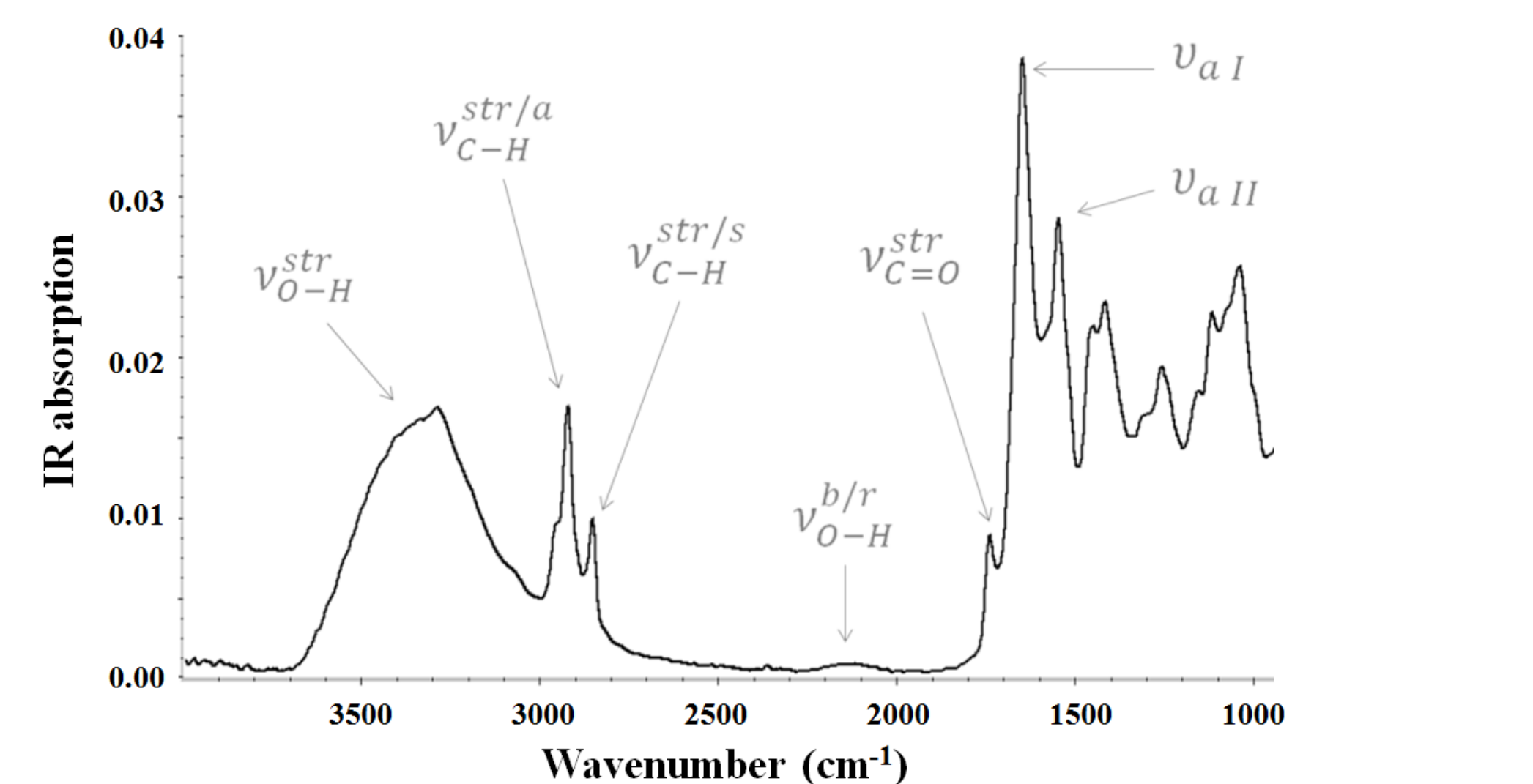
$$P = E^* \cdot \sqrt{R} \cdot h^{3/2}$$

E* from 35 to 120 kPa

3. Physicochemistry

In vivo ATR-FTIR spectrometry

Penetration depth < 1.2 μm

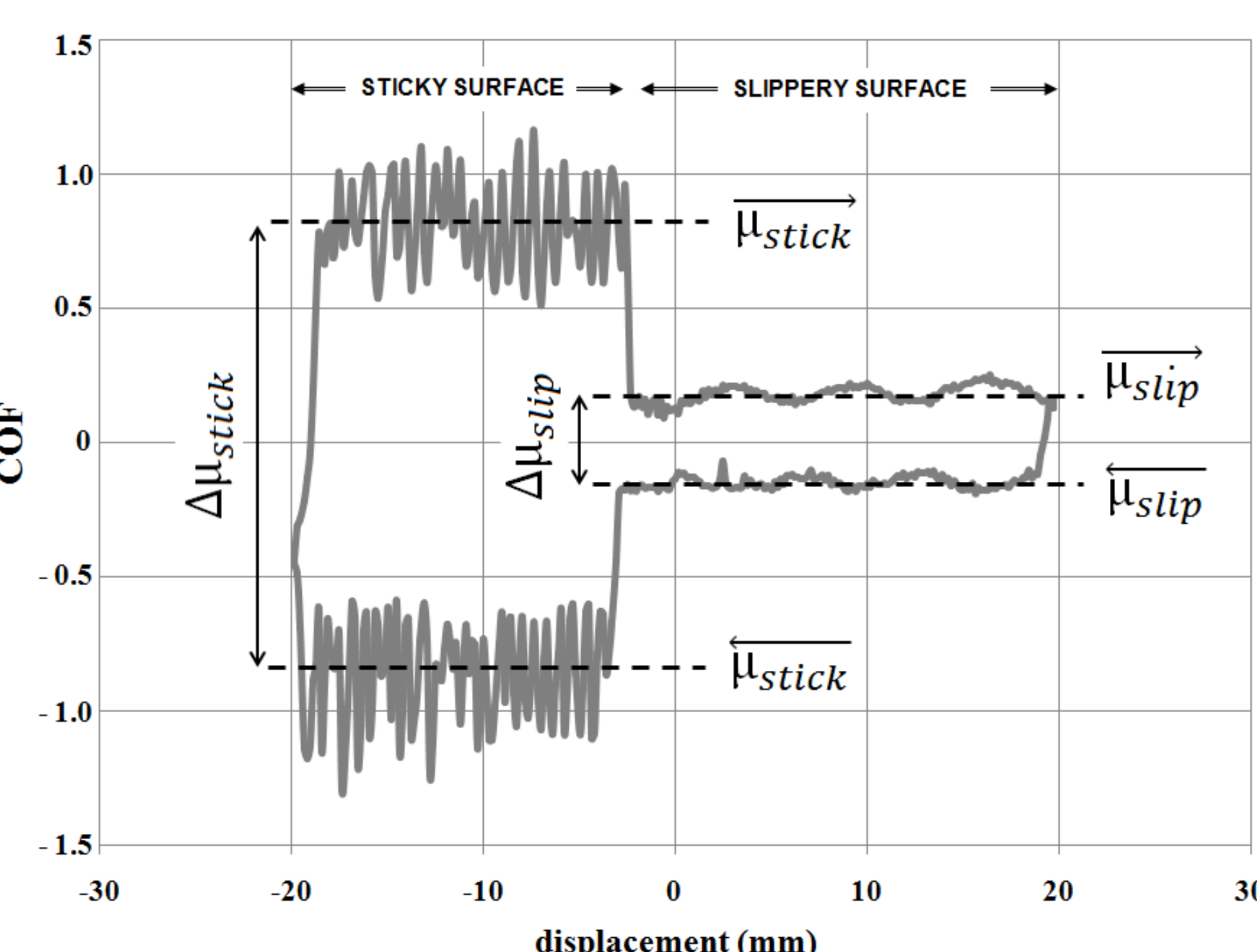
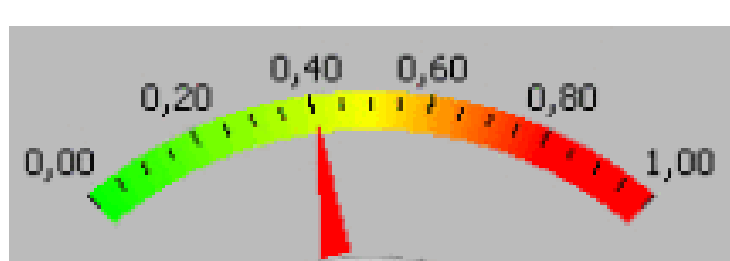
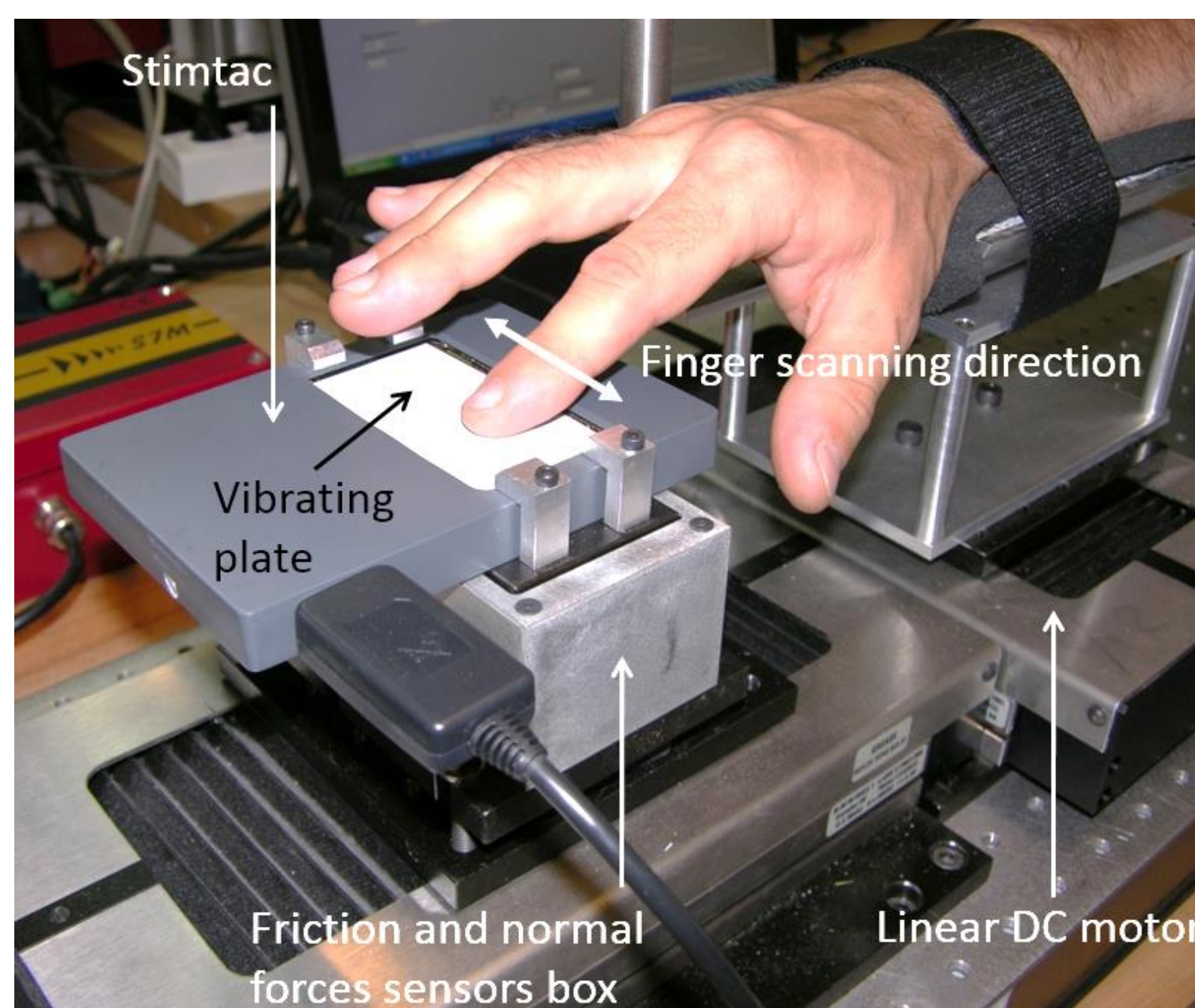


Lipids/water ratio: $D_{L/W} = I(\nu_{C-H}^{str/a}) / I(\nu_{O-H}^{str})$

Friction measurements

Linear reciprocating tribometer

- Tangential motion direction of the right forefinger of individuals
- 1 pass: sticky & slippery surfaces
- Scanning speed = 4 mm/s
- Sliding distance = 40 mm
- Measurement of F_N & F_T → COF
- Loading ≈ 0.5 N (controlled by individuals)



$$\mu_{stick} = \frac{|\mu_{stick}| + |\mu_{stick}|}{2}$$

$$\mu_{slip} = \frac{|\mu_{slip}| + |\mu_{slip}|}{2}$$

Frictional Contrast

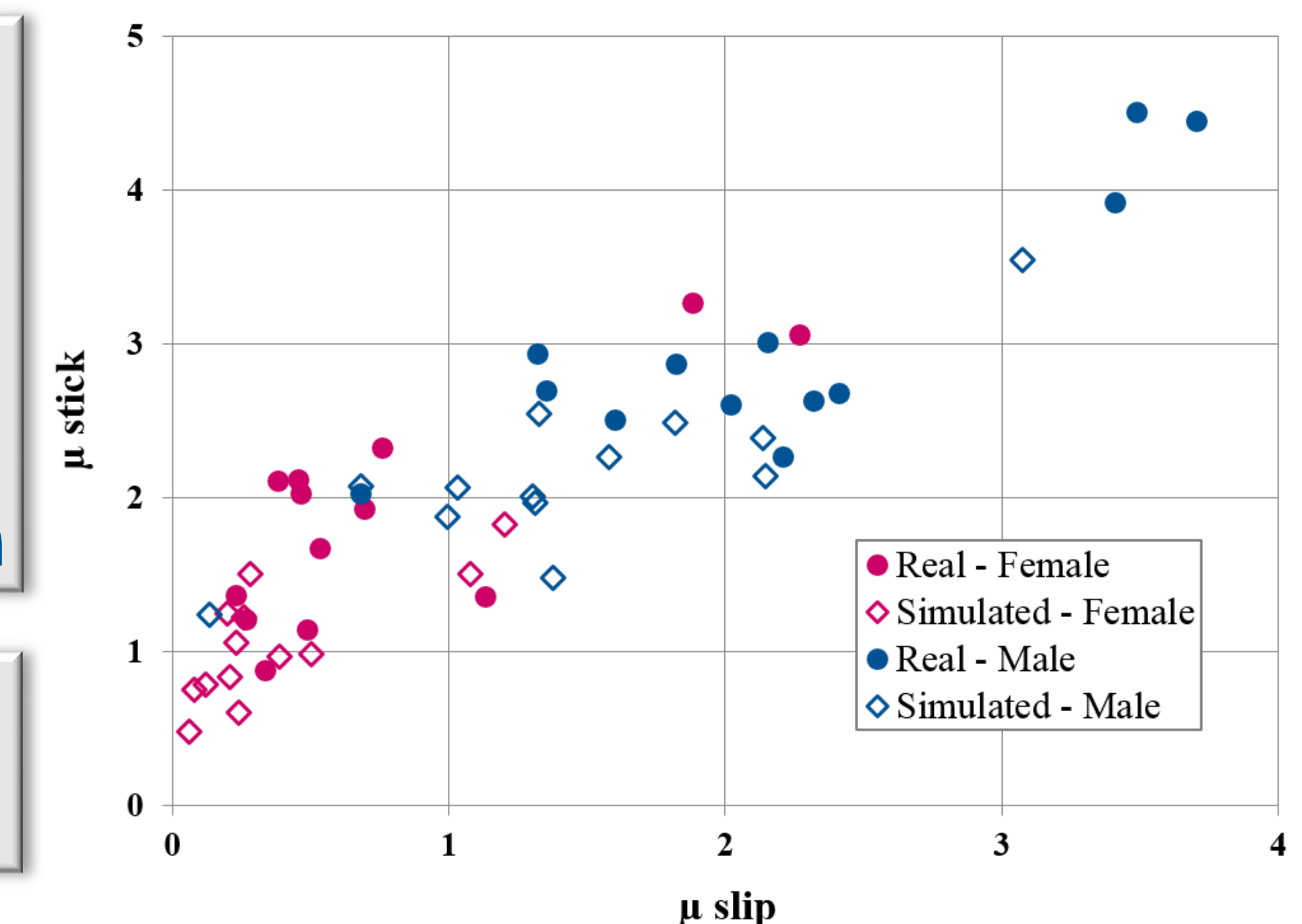
Frictional distinction of sticky/slippery surfaces

$$FC = 1 - \frac{\mu_{slip}}{\mu_{stick}}$$

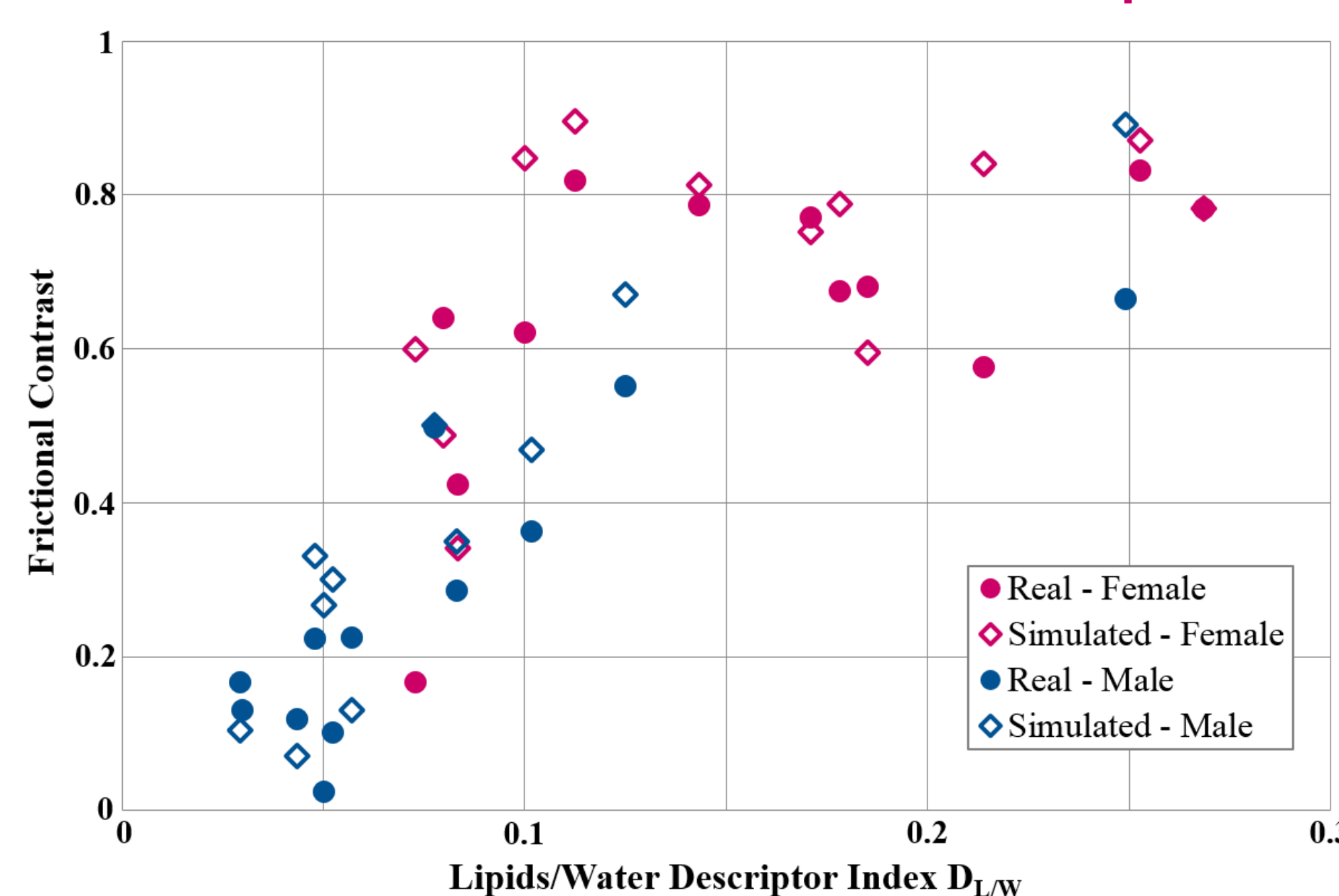
Results

Validation of Stimtac as a good tactile friction forces modifier for sticky/slippery surfaces simulation

Gender influence on μ_{stick}, μ_{slip} & FC



Bad correlation of R_t, S_p or E* with both Frictional Contrast & COFs (μ_{stick} or μ_{slip})... But...



Hydrolipidic film composition is highly responsible of Frictional Contrast values for sticky/slippery flat surfaces