



An Integrated Data-driven Prognostics Approach: from Critical Components Identification to Remaining Useful life Prediction

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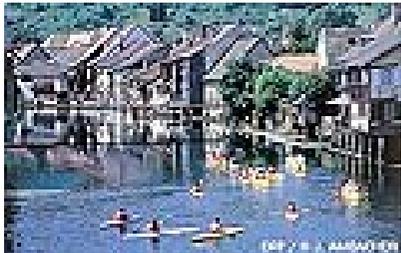
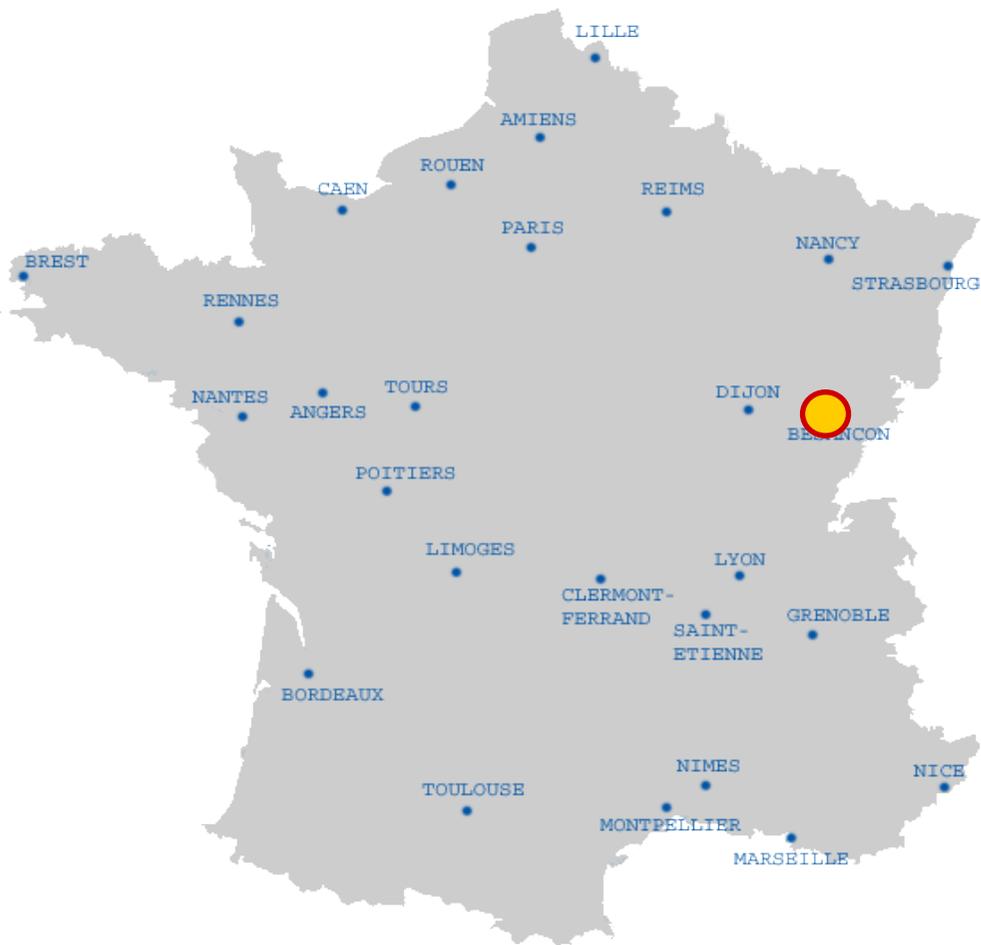
2015 ICRSE & PHM – Beijing

Overview



1. Motivation
2. Prognostics & Health Management
3. Failure prognostics
4. Problematics & main contributions

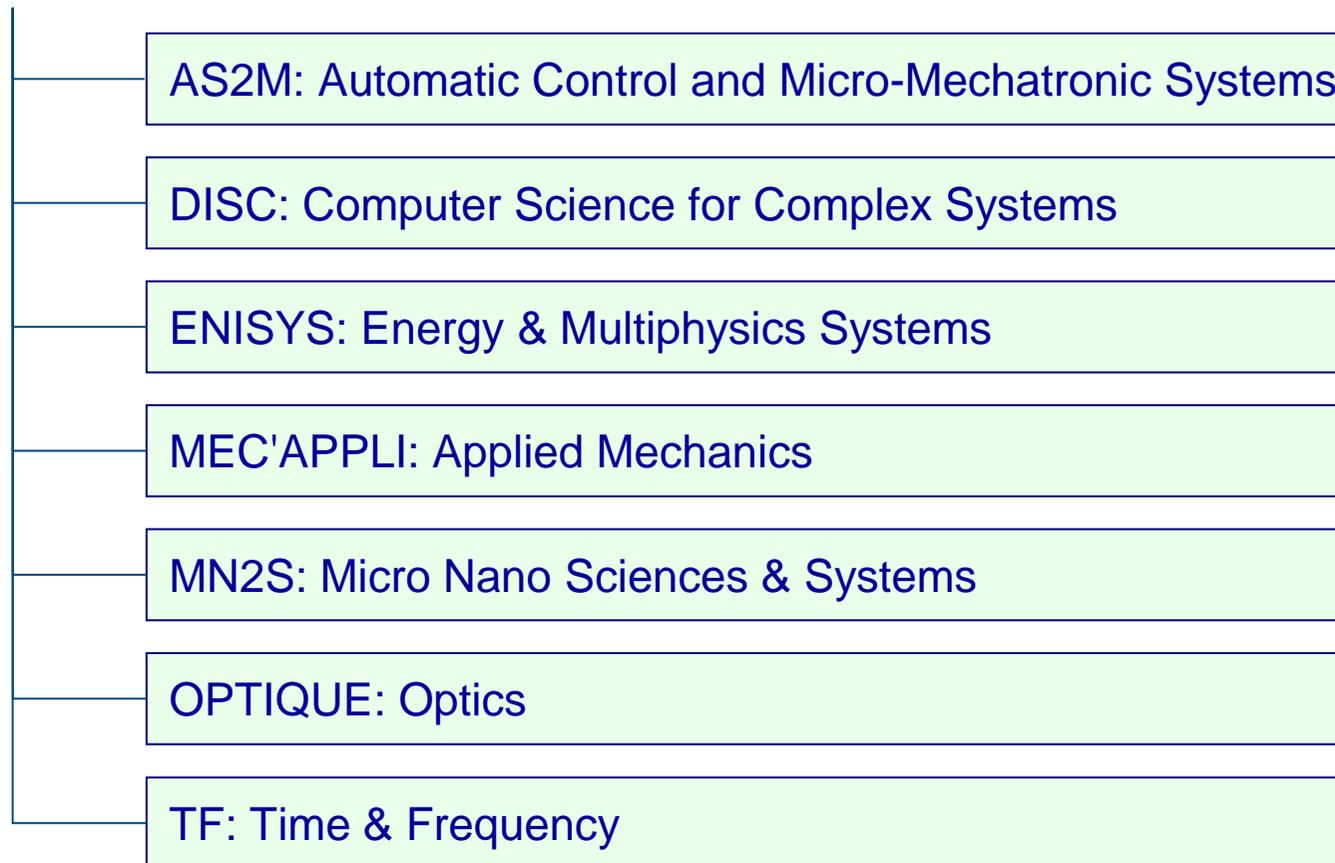
FEMTO-ST Institute



FEMTO-ST Institute



~700 persons (230 Researchers, Professors and Associate Professors, 225 PhDs, 95 Engineers, Technicians and Administratives).



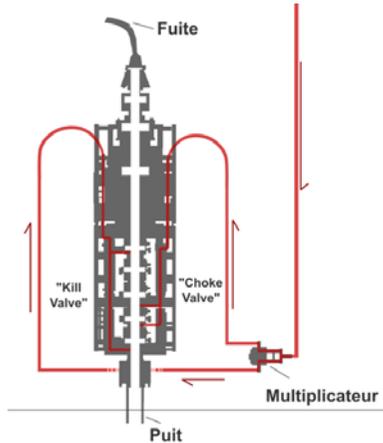
Motivation



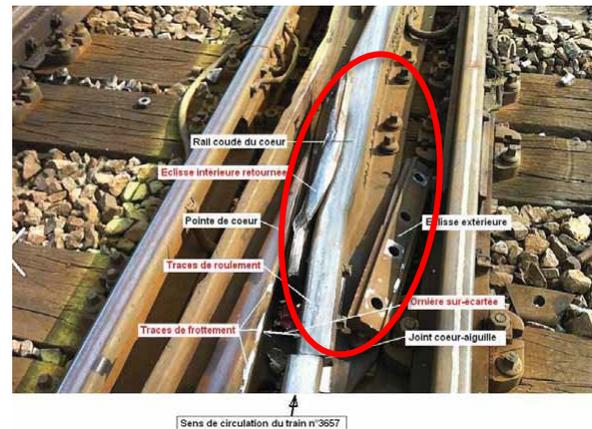
Explosion of the platform Deepwater Horizon in the Gulf of Mexico (USA) in April 2010 (source: sciencesetavenir.fr)



Train derailment in Brétigny-sur-Orge in July 2013



Probable cause: leak in the oil pumping system



Cause: failure of a fishplate (source: Bureau d'enquêtes sur les accidents de transport terrestre)

- According to the « Network Rail » in United Kingdom, faults and failures in railway transports are responsible of about 14 millions of minutes of delay per year
- In civil aviation, delays du to technical problems cost 22 Billions of \$ in 2011
- Losses due to failures in petrochemical industry were estimated to 2 millions of \$ per day
- In automobile domain, failures cost around 288 millions of \$ per day

Sources: Keynote de Pierre Dersin at PHM Europe 2014, Muller et al. 1996, Sovacool 2008, Tzanakakis 2013

Motivation



Need to monitor – assess – anticipate – act

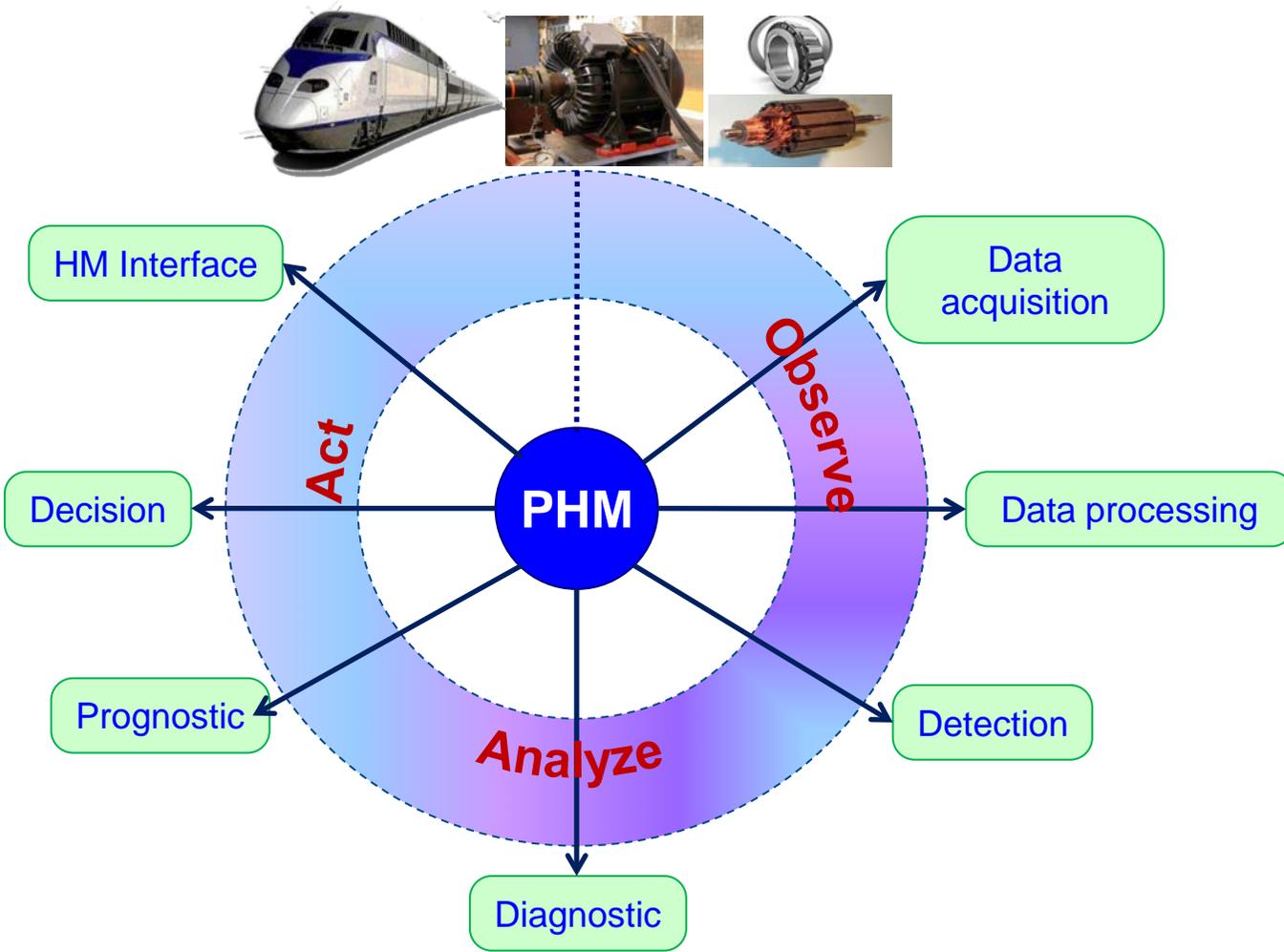
↗ Reliability ↗ Availability ↗ Security ↘ Costs

Overview

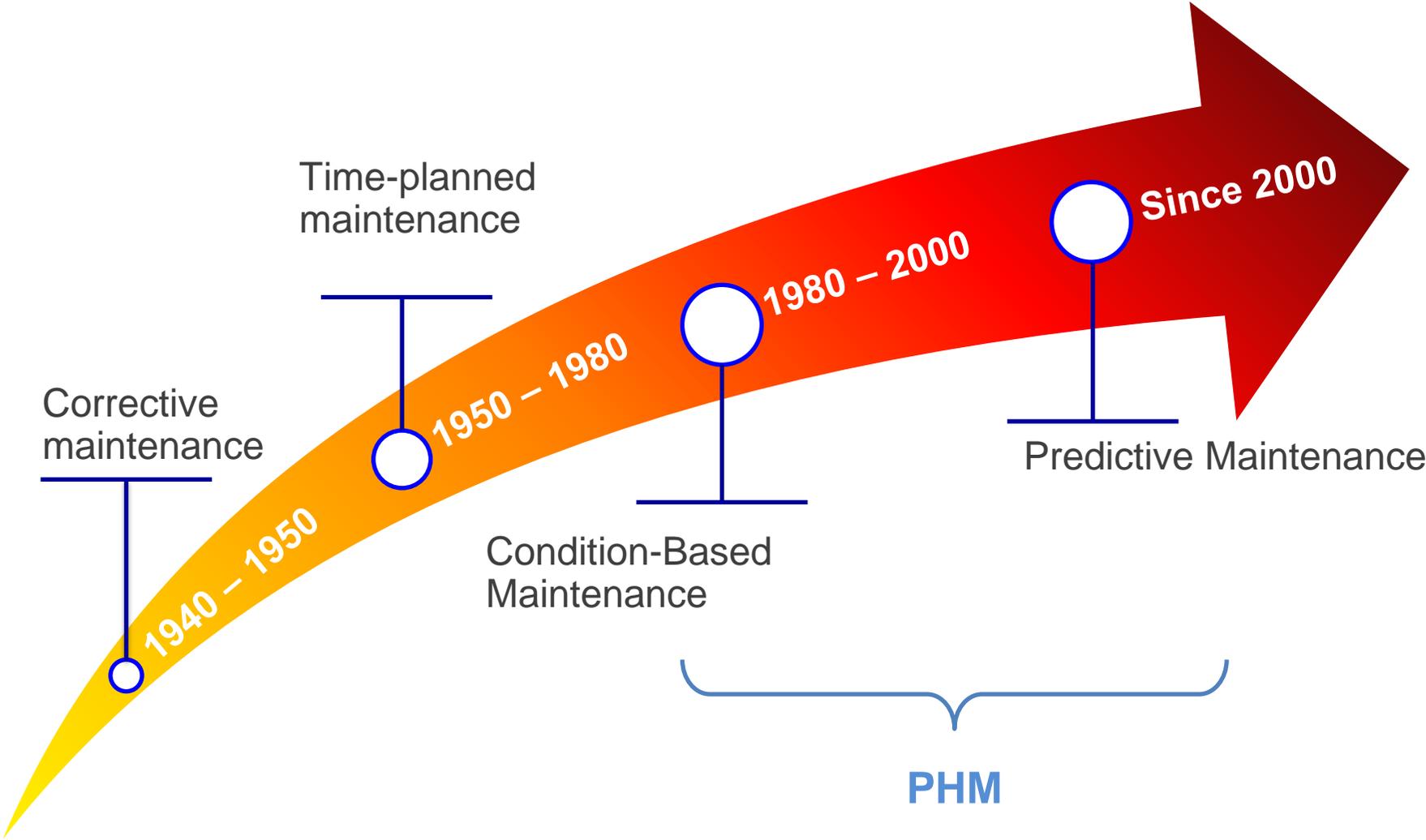


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Prognostics & Health Management



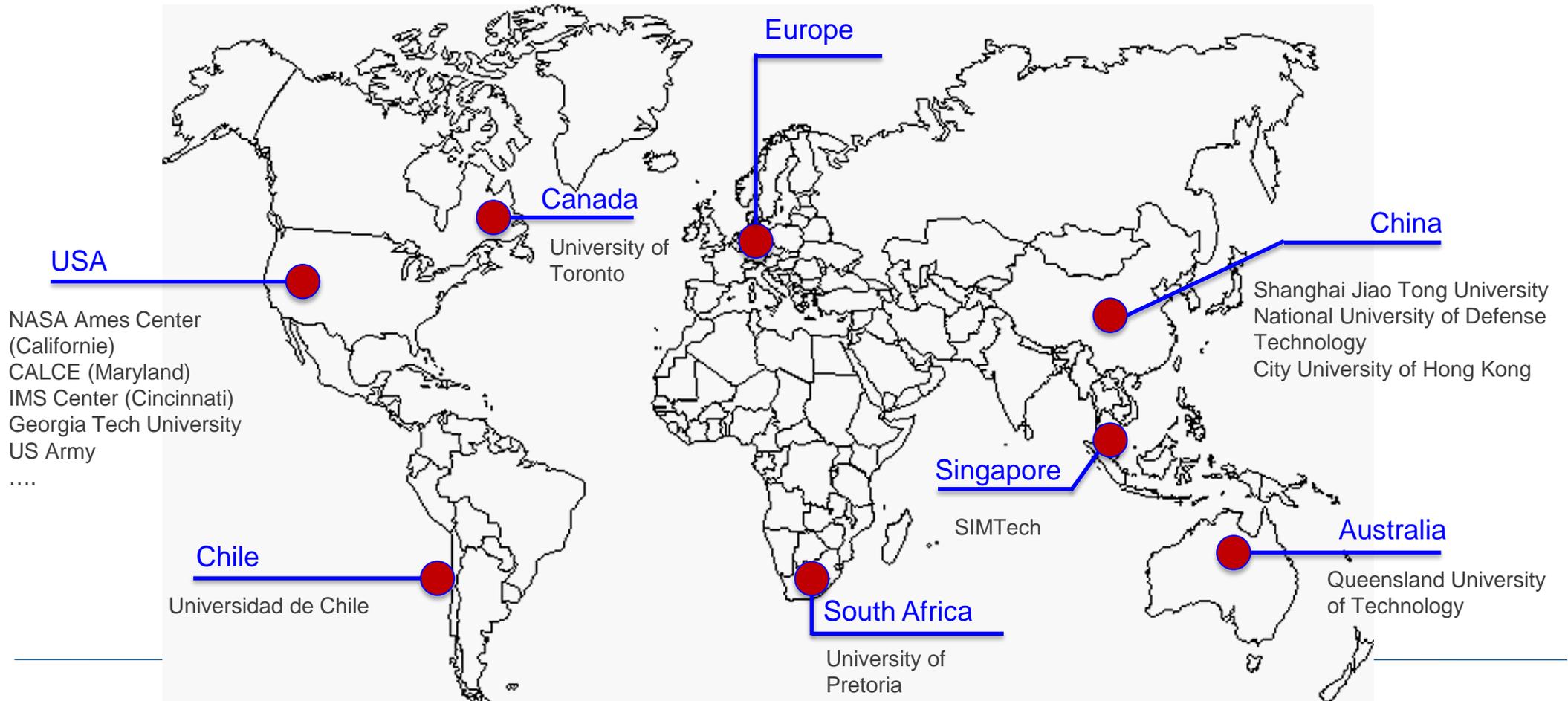
PHM vs Maintenance



PHM in the world



Femto-ST, CRAN, Centrale-Supélec, LSIS, Gipsa Lab...(France)
IVHM (Cranfield, UK)
Politecnico di Milano (Italy)
Fraunhofer-Chalmers Centre (Sweden)
Antalya International University (Turkey)
Tekniker (Spain)



PHM in industry



Aerospace



Energy



Railway transport



Automobile

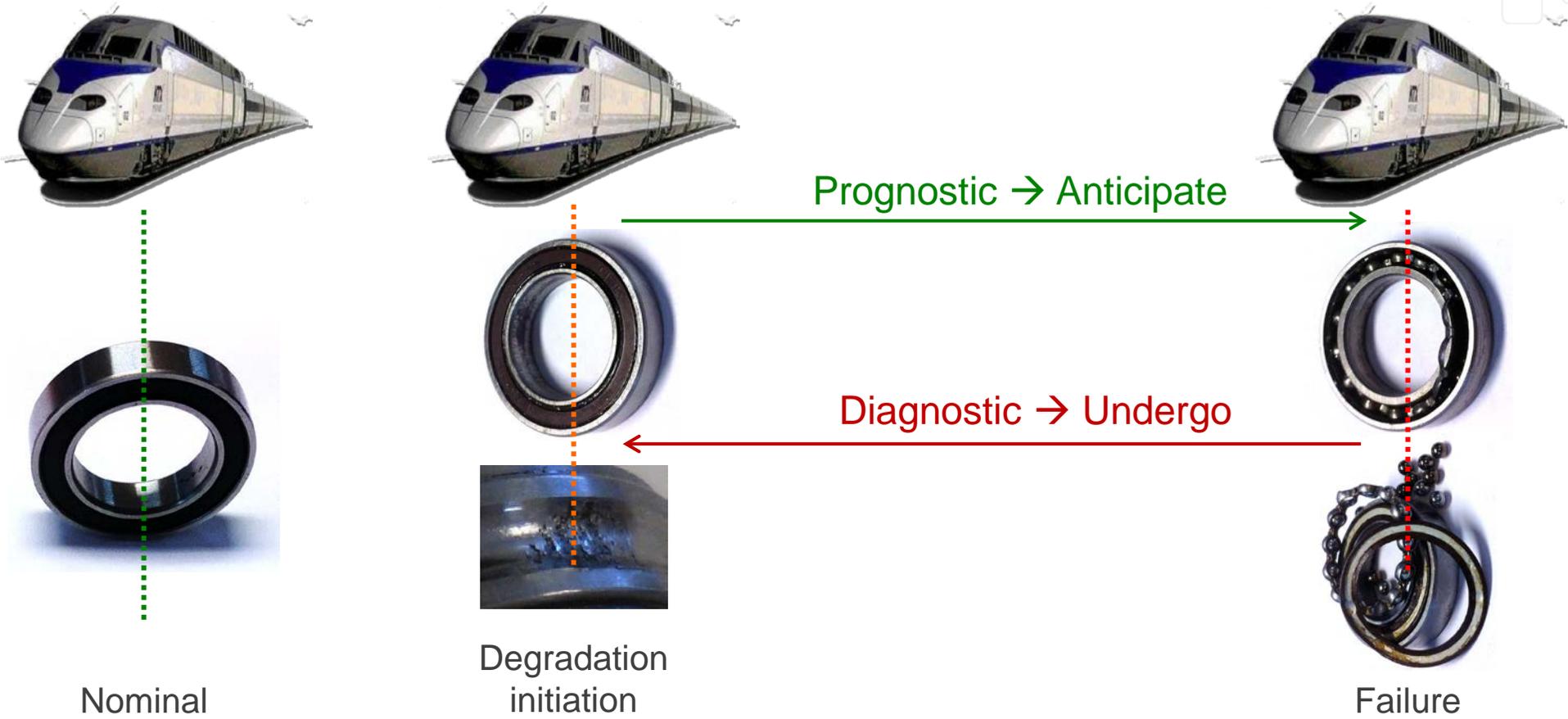


Overview



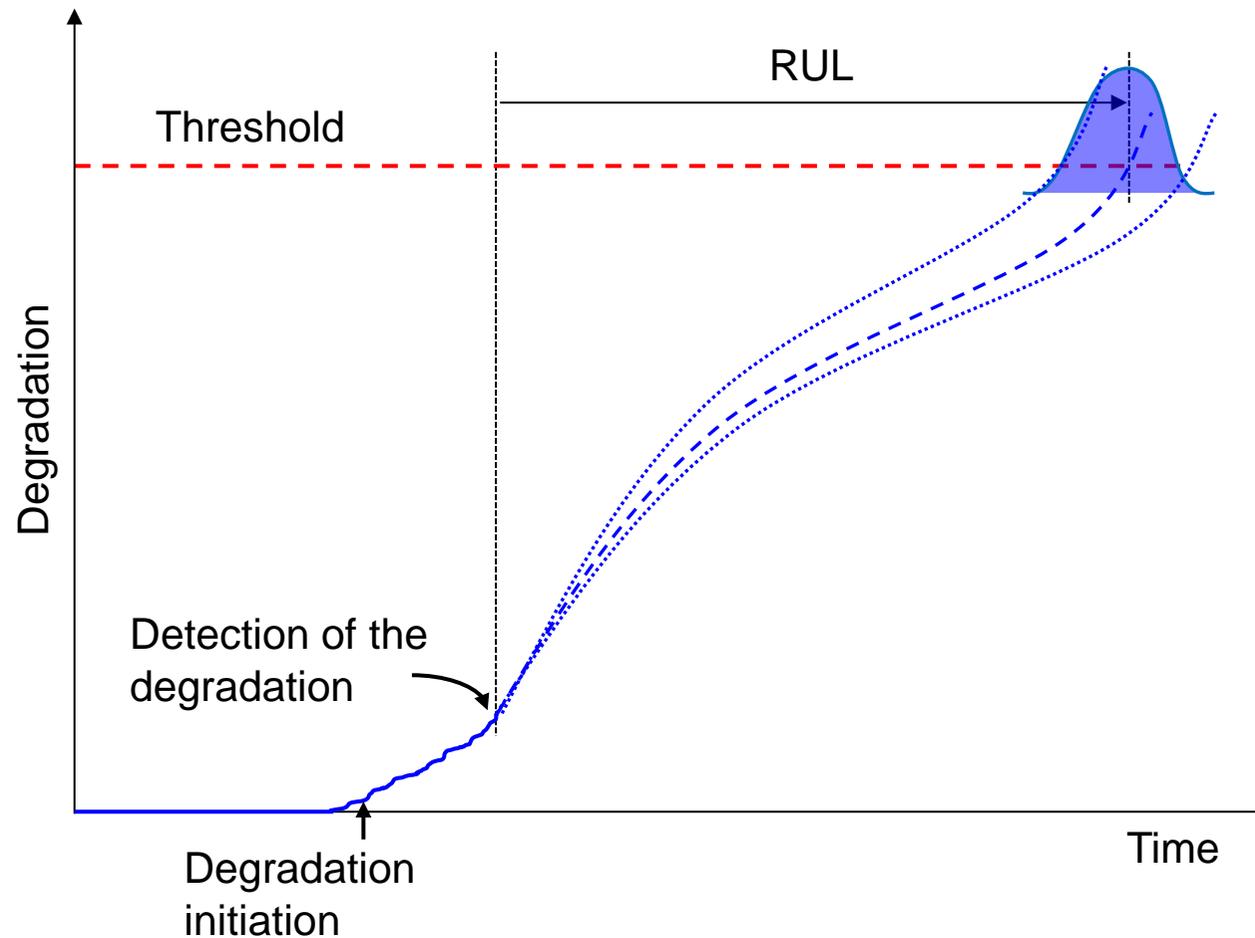
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Failure prognostics

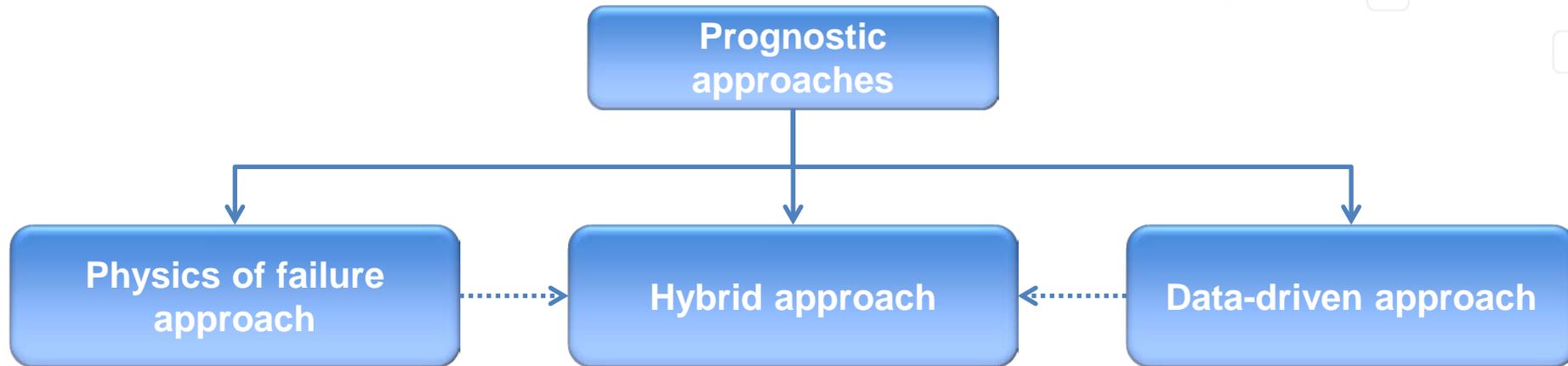


Definition of failure prognostic

Prognostic : prediction of the remaining useful life (RUL) of a system based on its current health state and its future operating conditions



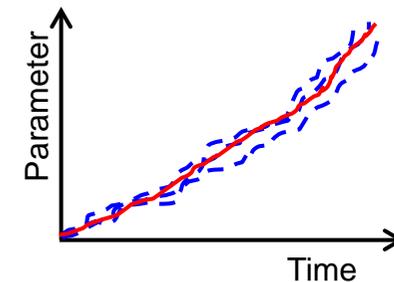
Prognostic approaches



$$\begin{cases} \dot{x} = \phi(x, \theta, u) \\ \dot{\theta} = g(\theta, x) \\ y = h(x, u) \end{cases}$$

Physical modeling

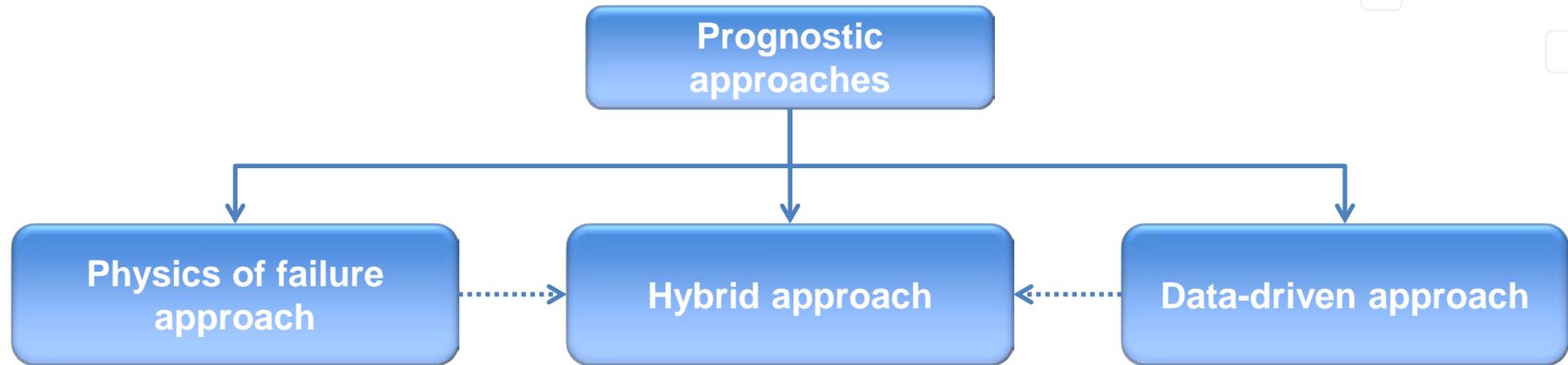
- Algebrao-differential equations
- Fatigue, corrosion, wear... models
- Paris-Erdogan laws



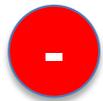
Data oriented modeling

- Trend analysis and regressions
- Artificial Neural Networks
- Probabilistic/stochastic (DBN, HMM)

Prognostic approaches



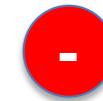
- Physical approach: quantification of the degradation
- Reuse of models



- Simplifying assumptions \Rightarrow reduced applicability
- High implementation cost

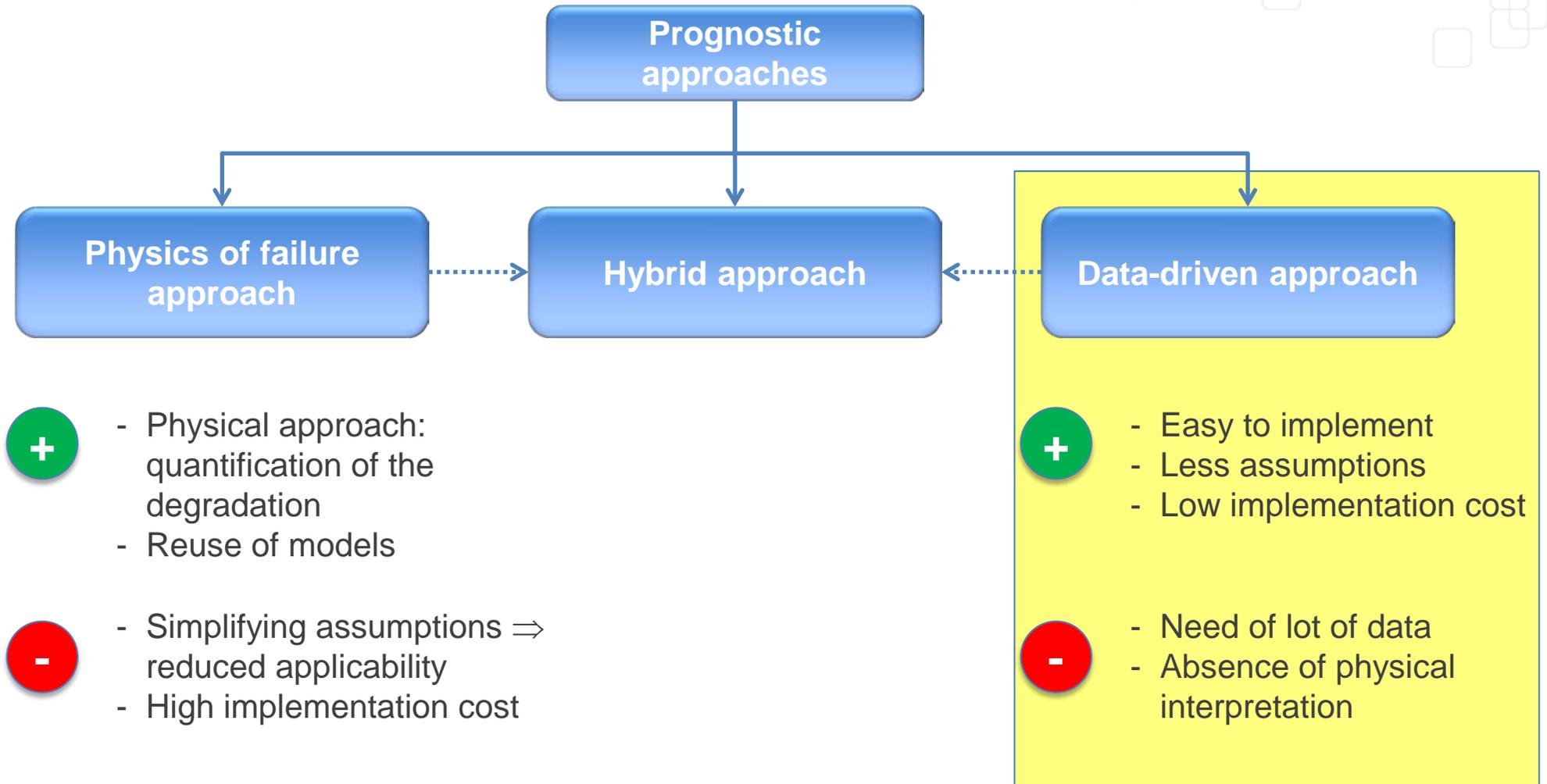


- Easy to implement
- Less assumptions
- Low implementation cost



- Need of lot of data
- Absence of physical interpretation

Prognostic approaches

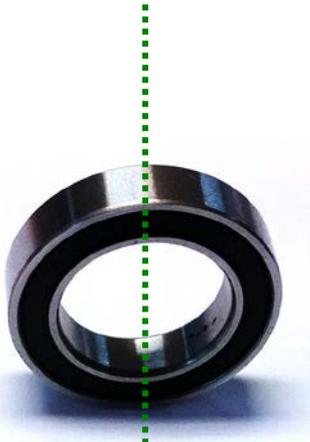


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Scientific issues

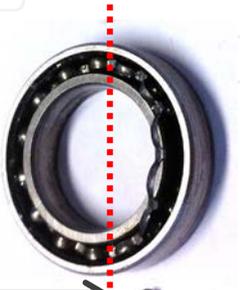


Nominal

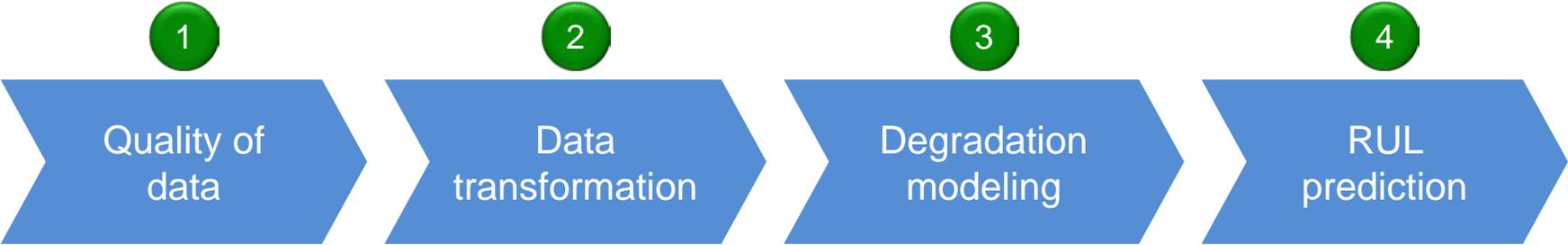


Degradation initiation

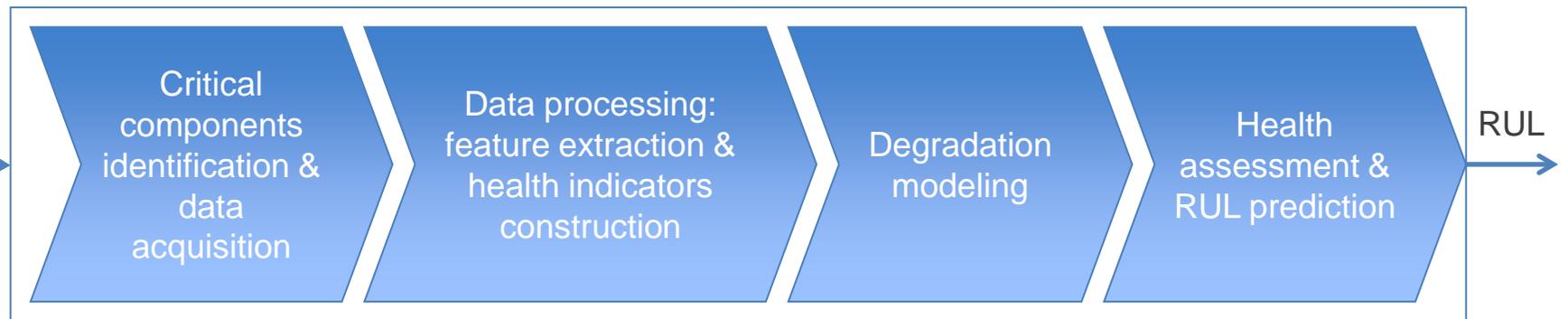
Remaining Useful Life (RUL)



Failure



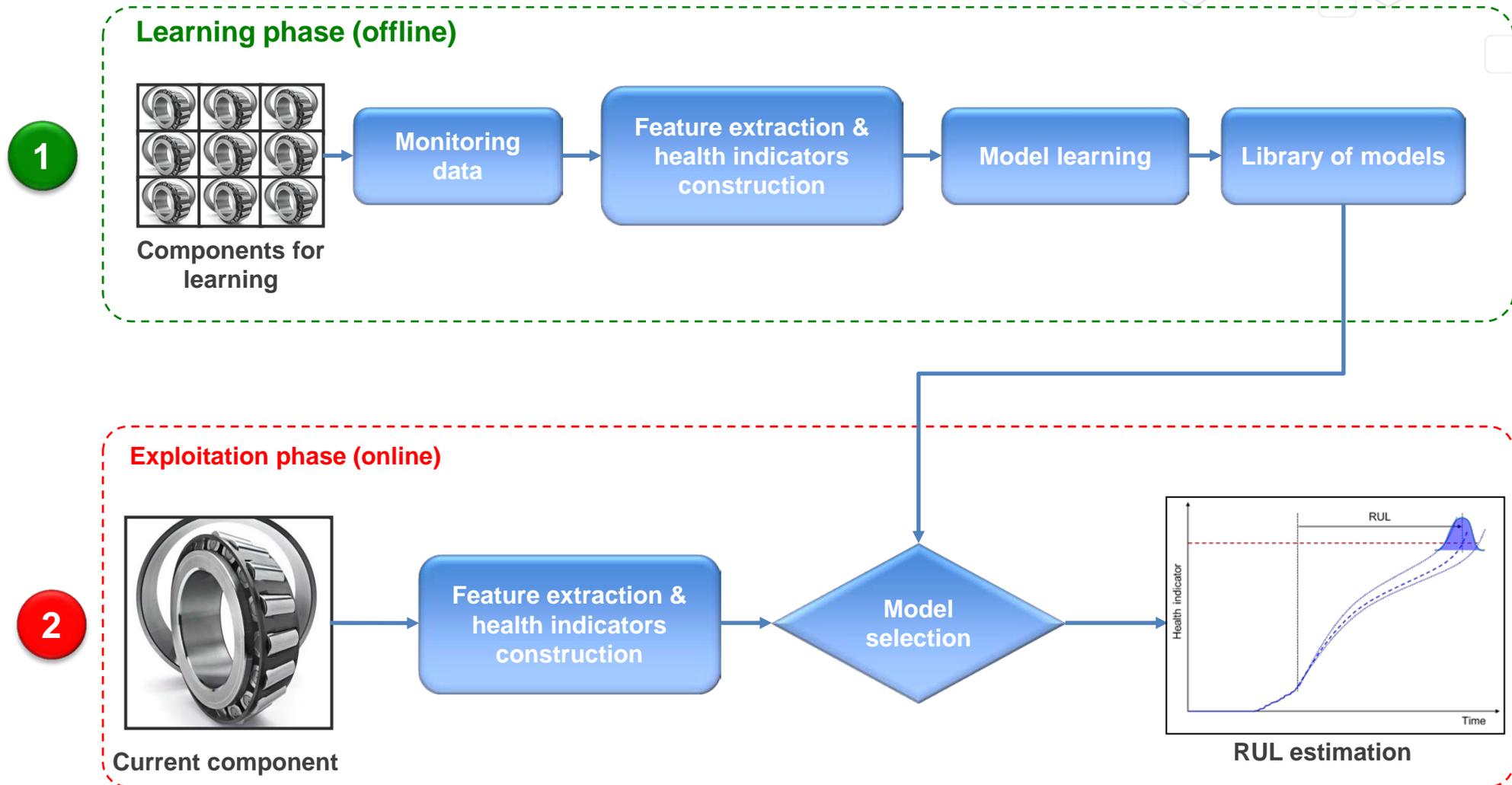
Main contributions



- Expertise manufacturer / operator
- Exploitation of experience feedback
- Dependability tools (FMECA, fault tree...)
- Signal processing (statistical parameters, temporal analysis, time-frequency analysis...)
- Data reduction (PCA, ISOMAP)
- Dynamic Bayesian Networks
- Support Vector regression
- Gaussian Process Regression
- Exploitation of models
- Definition of fault thresholds
- Prognostic metrics

Transform the data to models to estimate the RUL

Integrated data-driven prognostic approach



Critical components & data for PHM

Quality of data

Data transformation

Degradation modeling

RUL prediction

1

Learning phase (offline)



Components for learning

Monitoring data

Feature extraction & health indicators construction

Model learning

Library of models

2

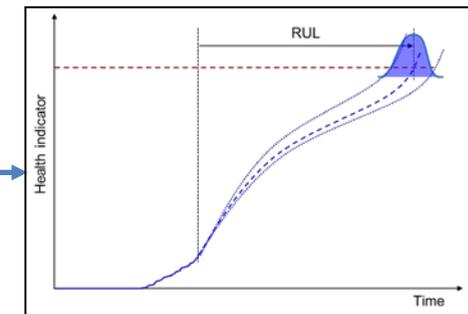
Exploitation phase (online)



Current component

Feature extraction & health indicators construction

Model selection



RUL estimation

Critical components & data for PHM



- Is it necessary to monitor all system components?
- The degradations are they observables?
- What are the implementation constraints?

1

Choice of critical components

2

Representative data
→ « observability » of the degradations



- **Engineering steps (important & indispensables)**
- **Close collaboration with industrials**

Critical components & data for PHM



- Industrial projects

ALSTOM

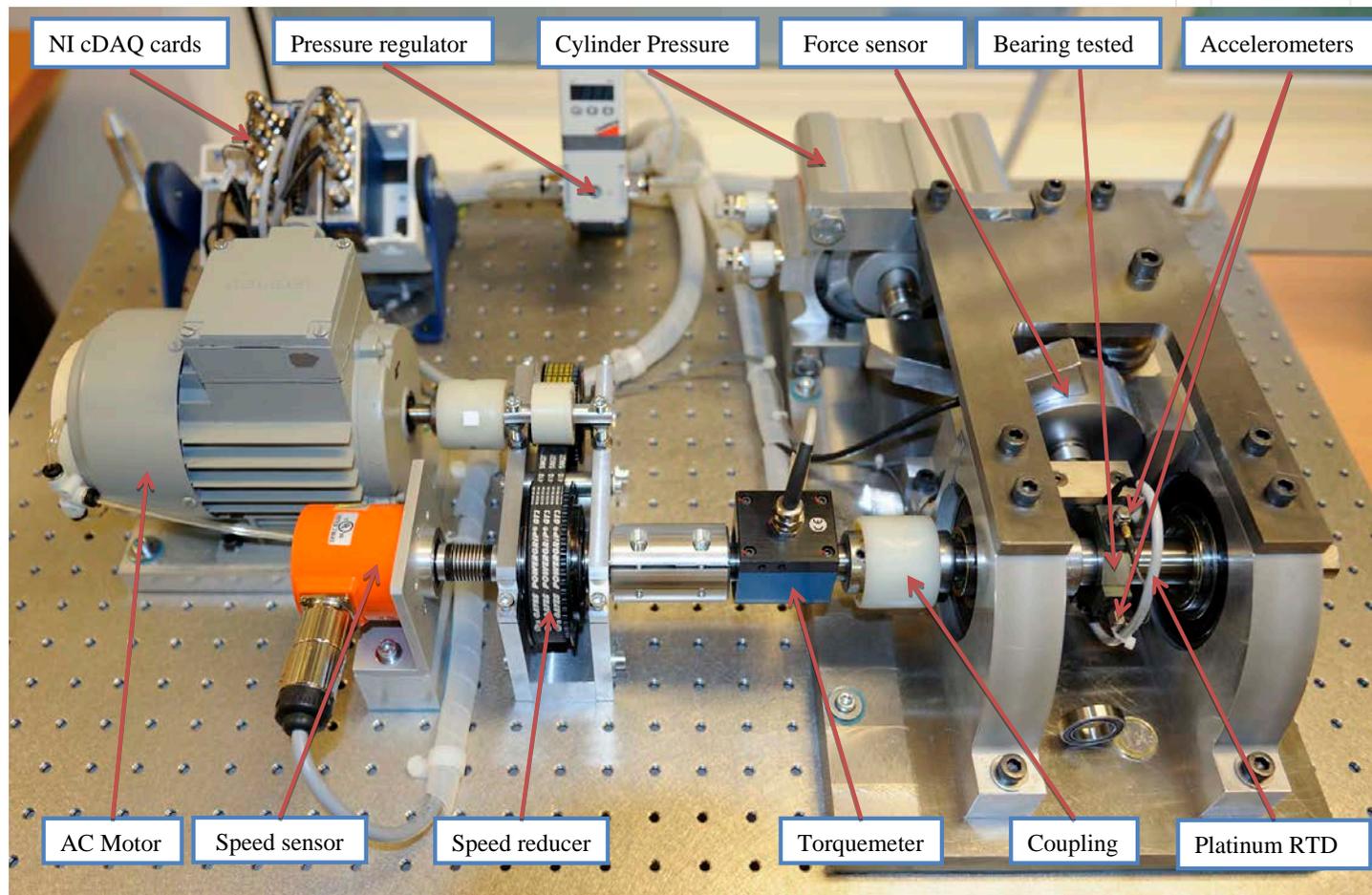


TORNOS



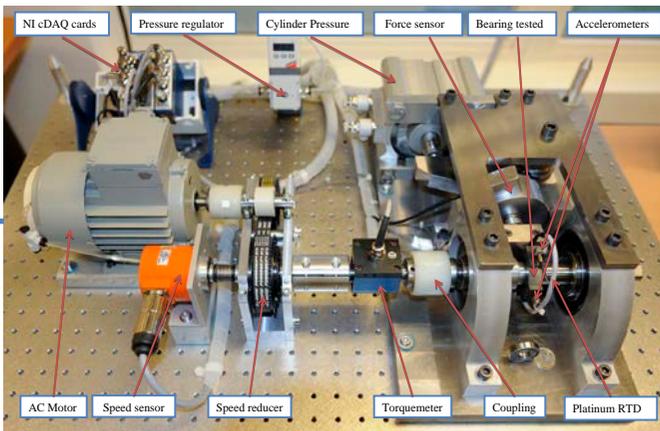
- INTERREG project (with EPFL)

Experimental platform: PRONOSTIA



- Test & validation of PHM algorithms
- Organization of PHM Data Challenge 2012 <http://www.femto-st.fr/ieee-PHM2012-data-challenge>
- Data available at <http://ti.arc.nasa.gov/tech/dash/pcoe/prognostic-data-repository/>

Experimental platform: PRONOSTIA

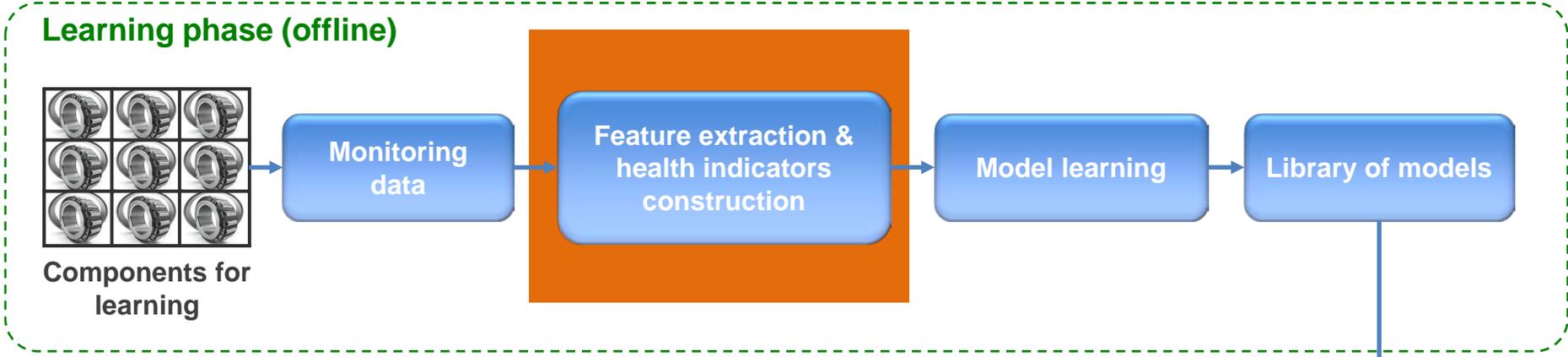


PRONOSTIA

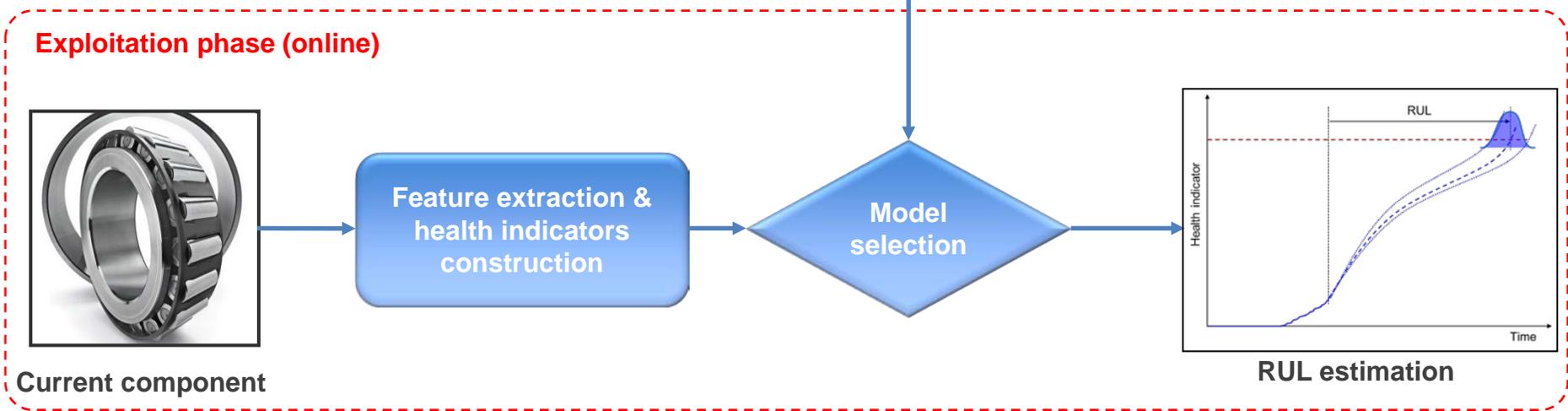
Data processing



1



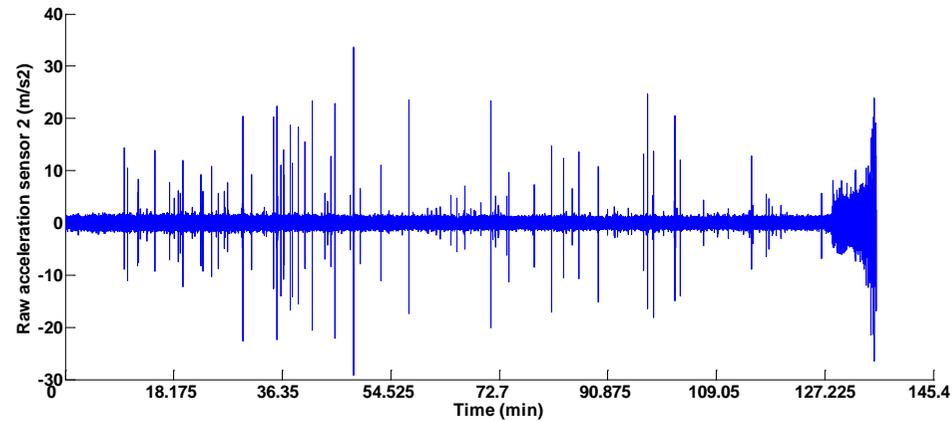
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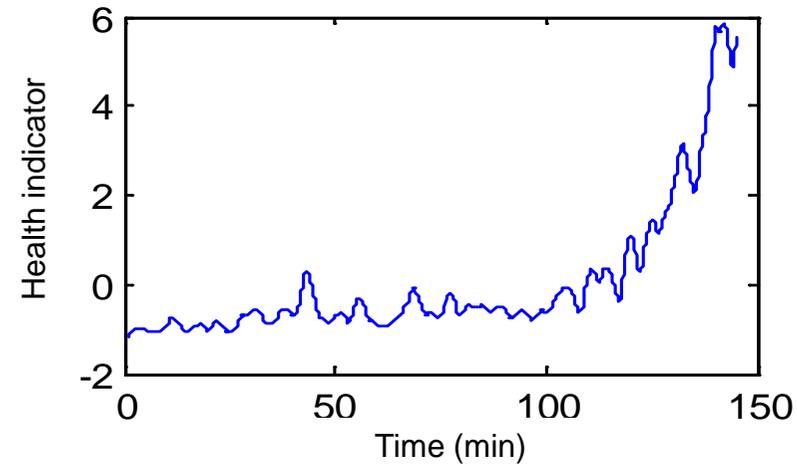
Data processing



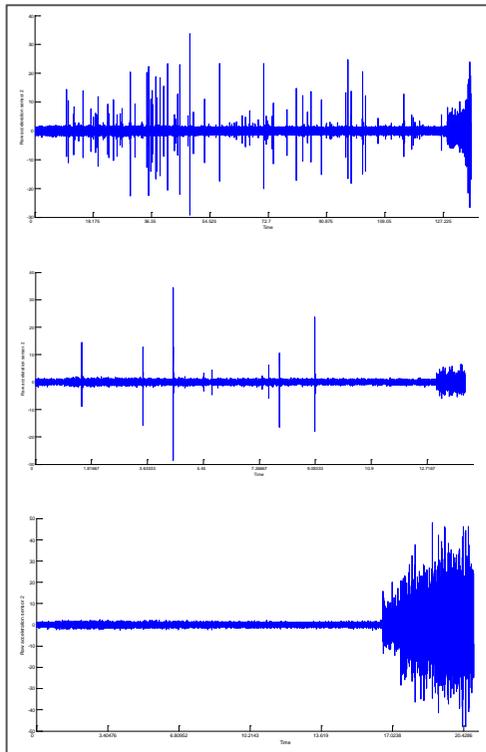
➔ Feature extraction and health indicators construction to track the component degradation



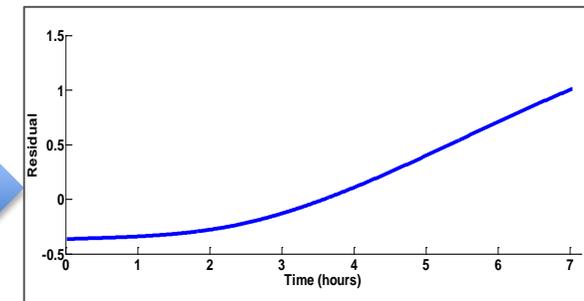
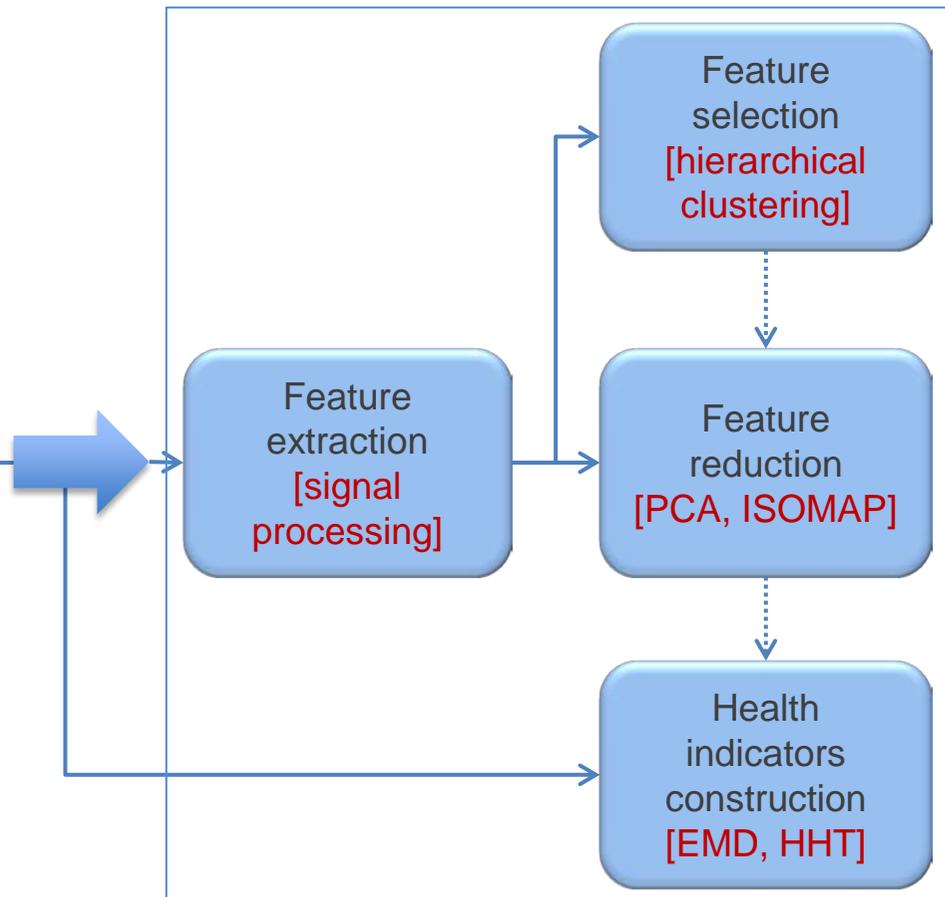
- Which feature to extract?
- Which health indicator to build?



Data processing

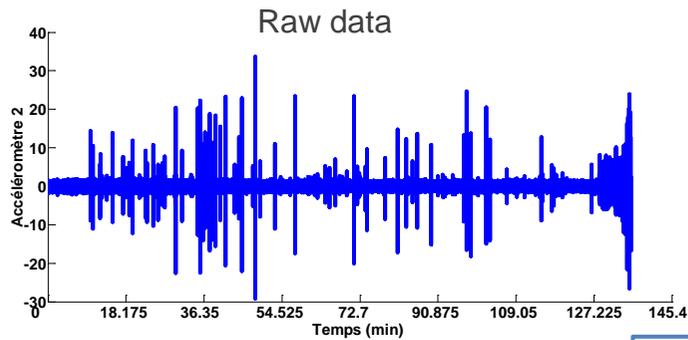


Raw signals

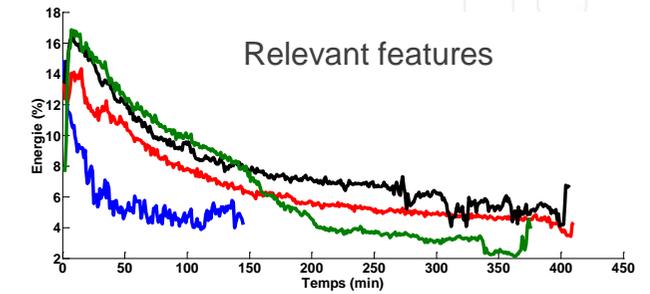


- Relevant features
- Health indicators

Feature extraction



Feature extraction



Stationary signals

Non stationary signals

Temporal domain

- RMS
- Mean
- Crest
- Skewness
- Kurtosis
- Defect factor
- Correlation
- Convolution

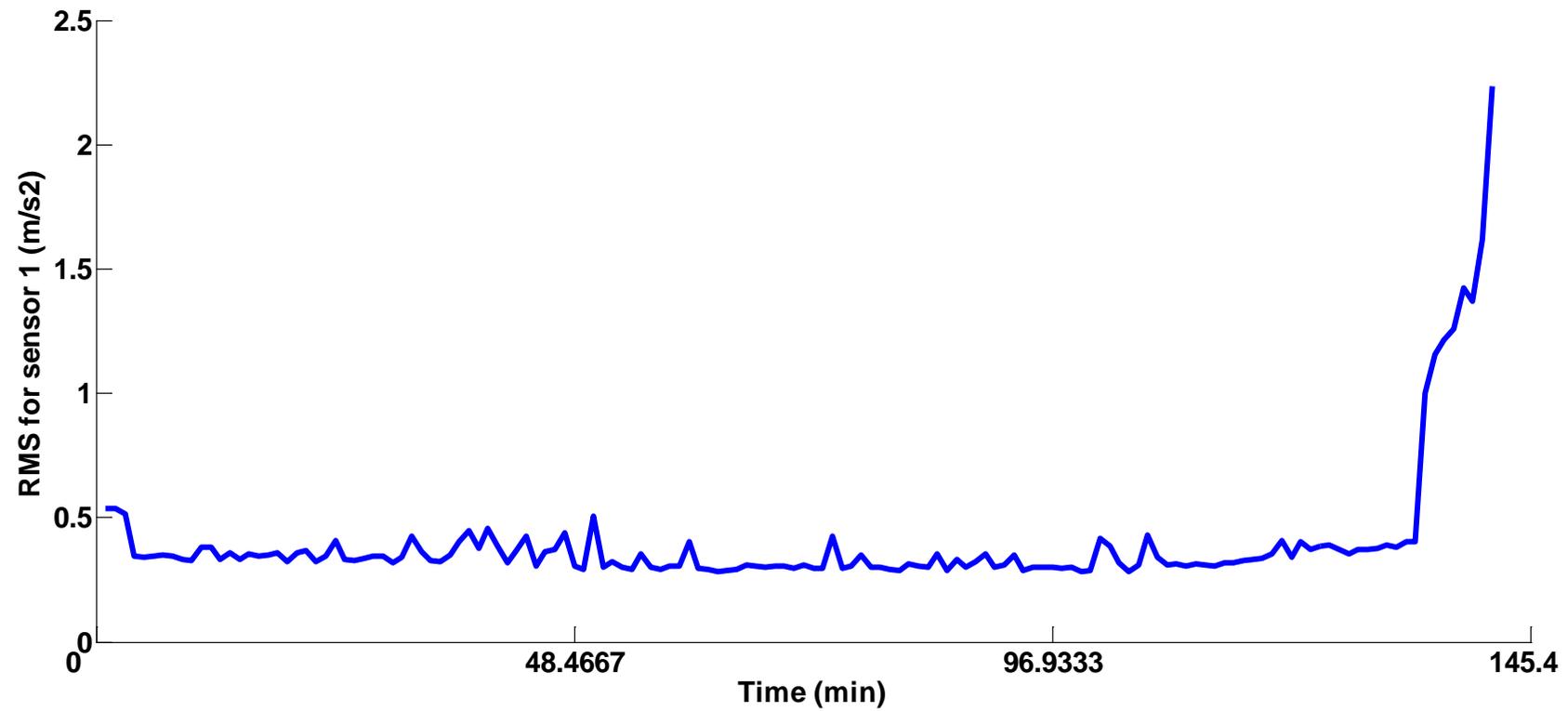
Frequency domain

- Spectral analysis
- Envelop analysis
- Cepstrum

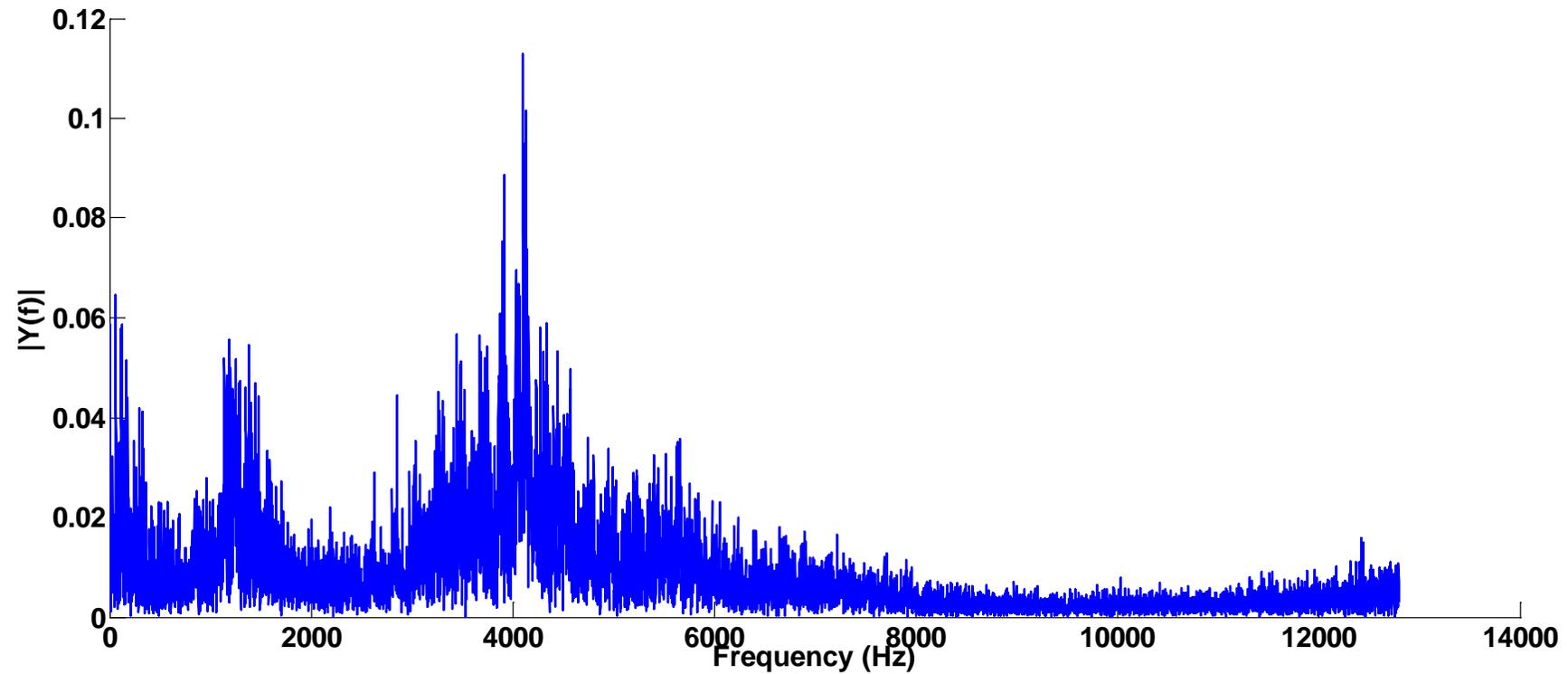
Time-frequency

- Short Time Fourier Transform
- Cyclostationary analysis
- Wigner-Ville distribution
- Empirical Mode Decomposition (EMD)
- Wavelets
- Wavelet Packet Decomposition (WPD)
- Hilbert-Huang transform

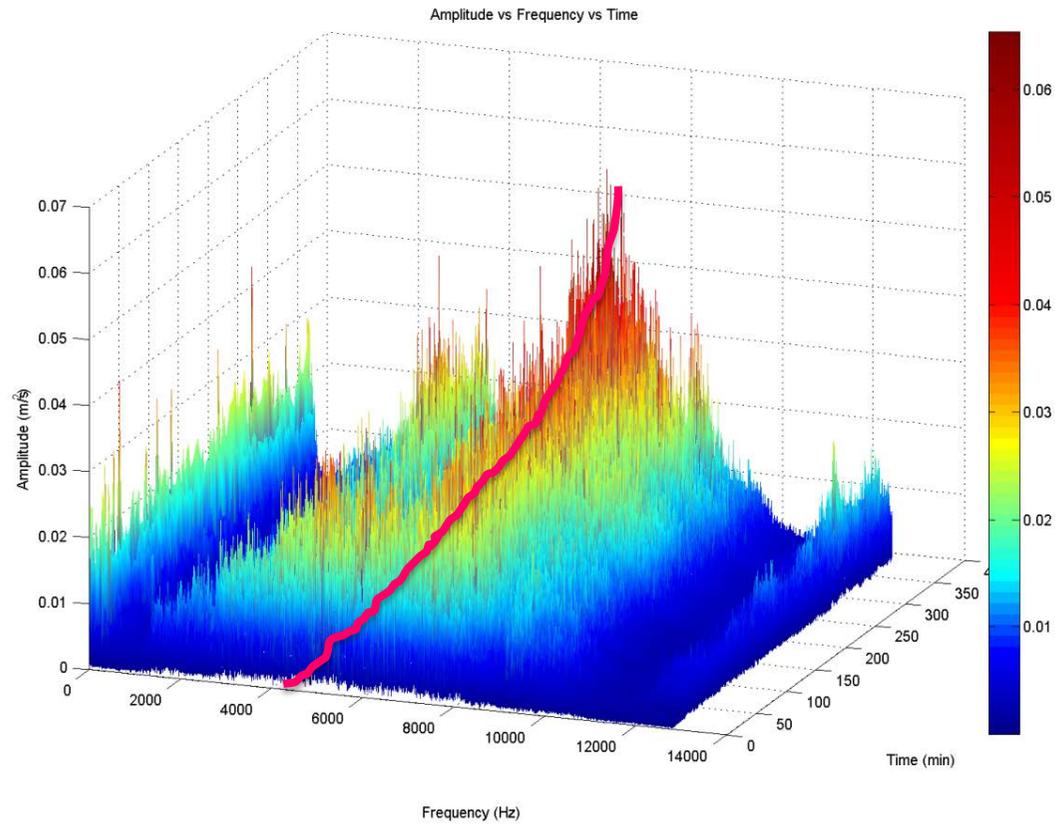
Temporal feature



Frequency feature

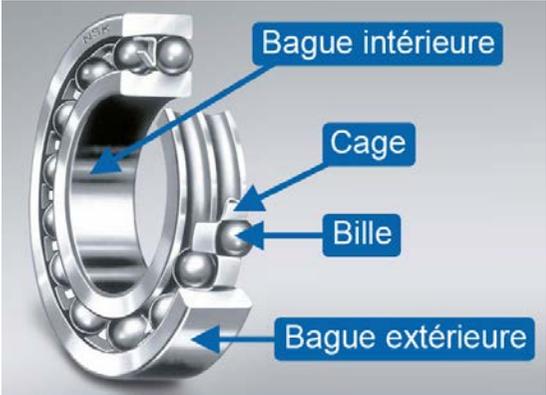


Time-Frequency feature



Health indicator

Health indicator



Inner race frequency

$$f_{ir} = \frac{n_b}{2} \cdot f_r \cdot \left[1 + \frac{DB}{DP} \cdot \cos \psi \right]$$

Outer race frequency

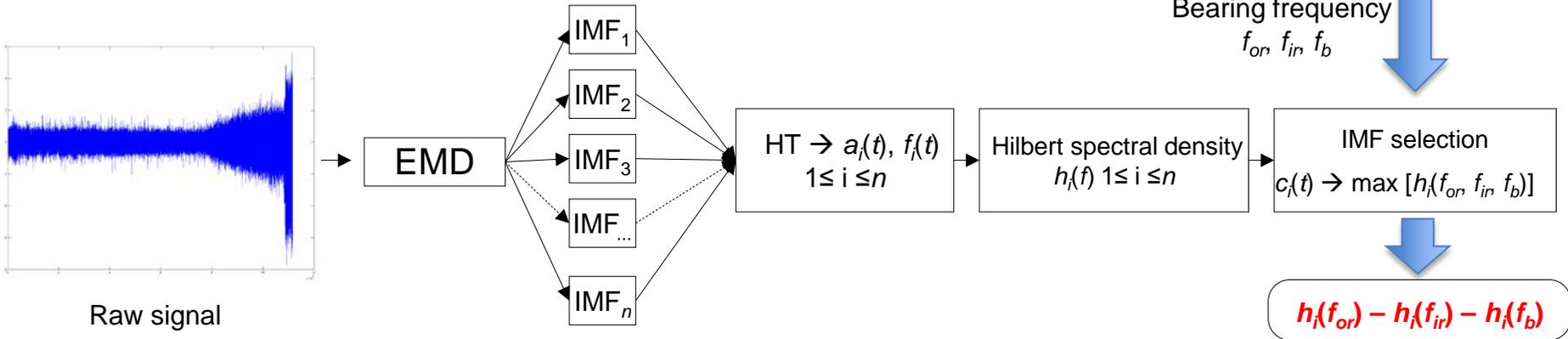
$$f_{or} = \frac{n_b}{2} \cdot f_r \cdot \left[1 - \frac{DB}{DP} \cdot \cos \psi \right]$$

Ball frequency

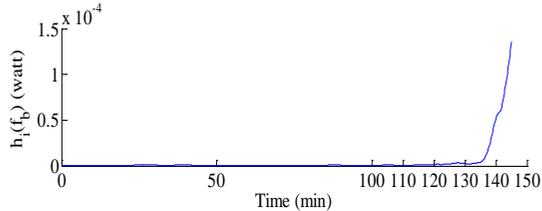
$$f_b = \frac{DP}{DB} \cdot f_r \cdot \left[1 - \frac{DB^2}{DP^2} \cdot \cos^2 \psi \right]$$

Bearing frequency

$f_{or} f_{ir} f_b$



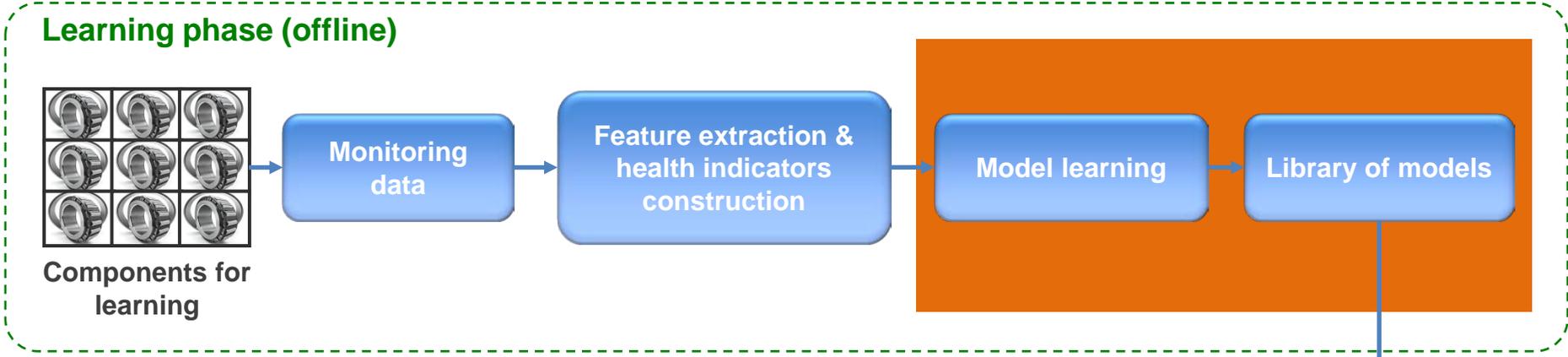
$$h_i(f_{or}) - h_i(f_{ir}) - h_i(f_b)$$



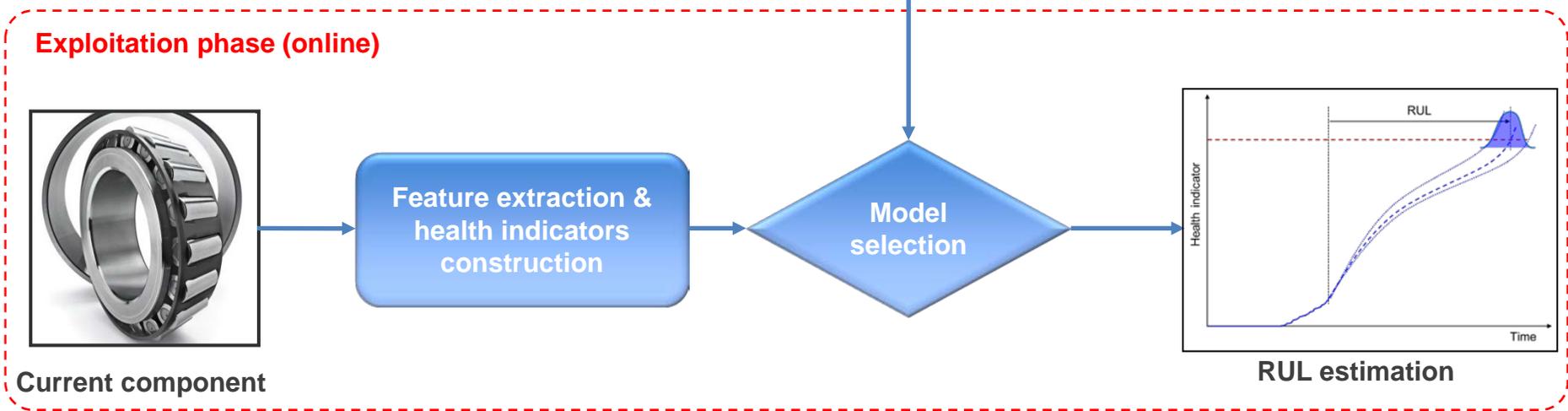
Degradation modeling



1



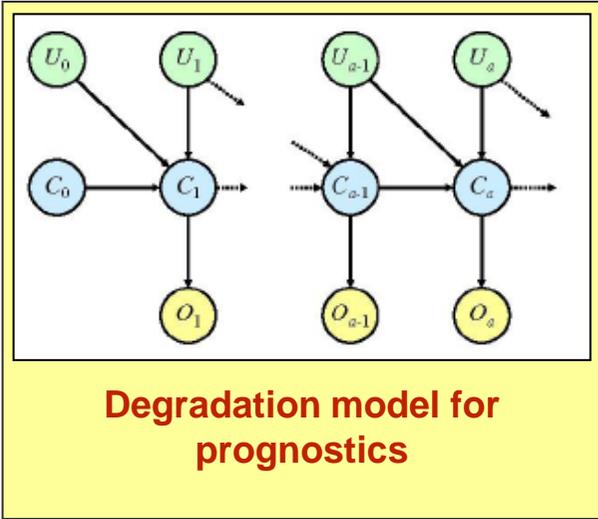
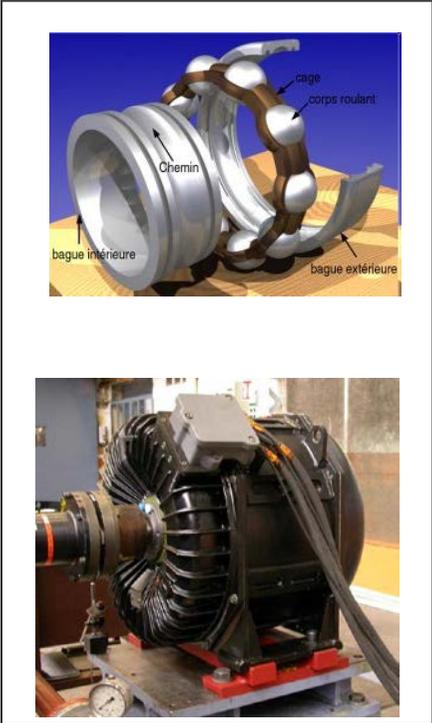
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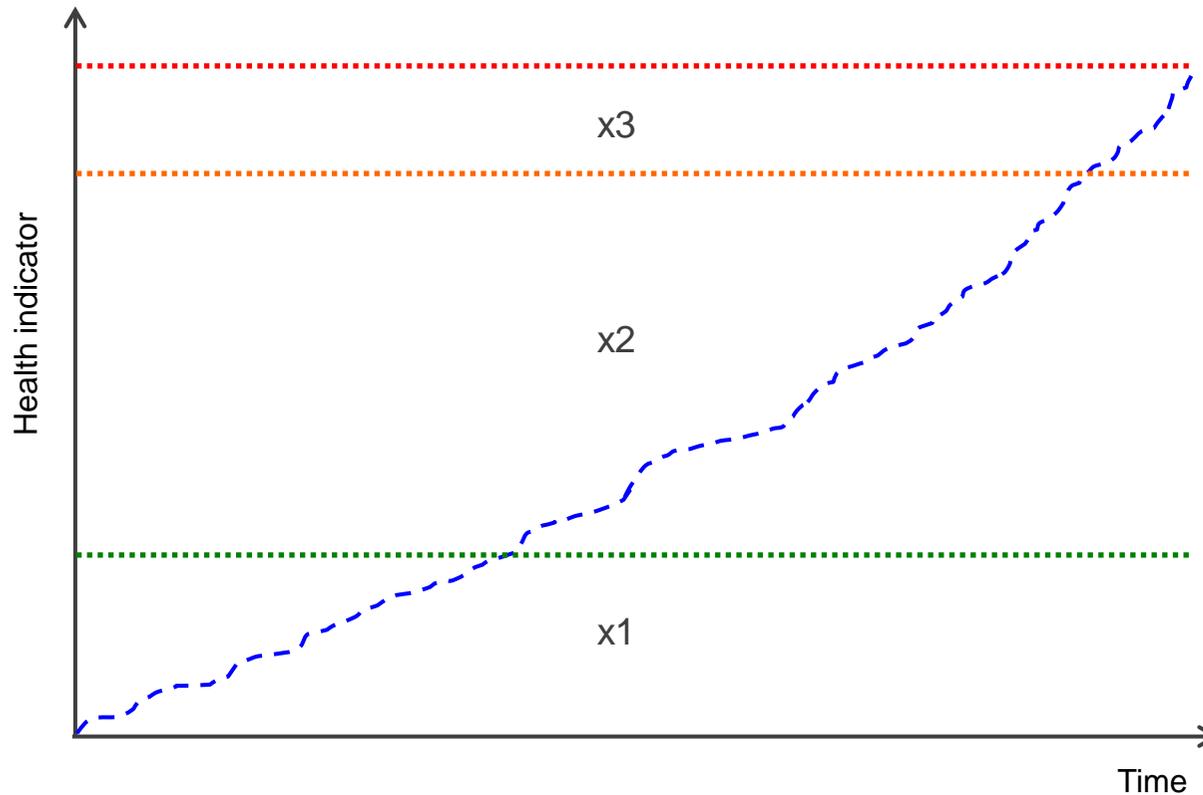
Degradation modeling



Transform the monitoring data into degradation models

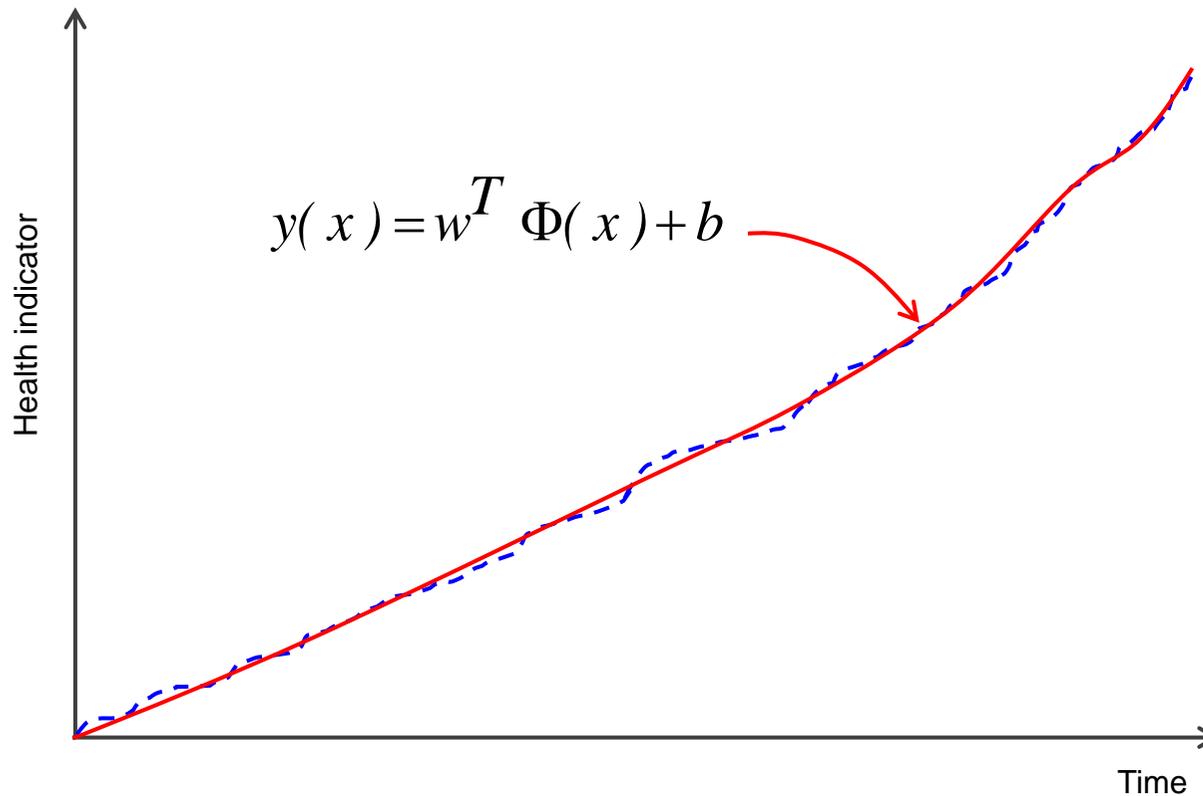


Degradation modeling



- Probabilistic/stochastic representation
- Taking into account variability of data
- Learning and inference time
- Simplicity of representation
- Generalization of HMM and Kalman filters

Degradation modeling



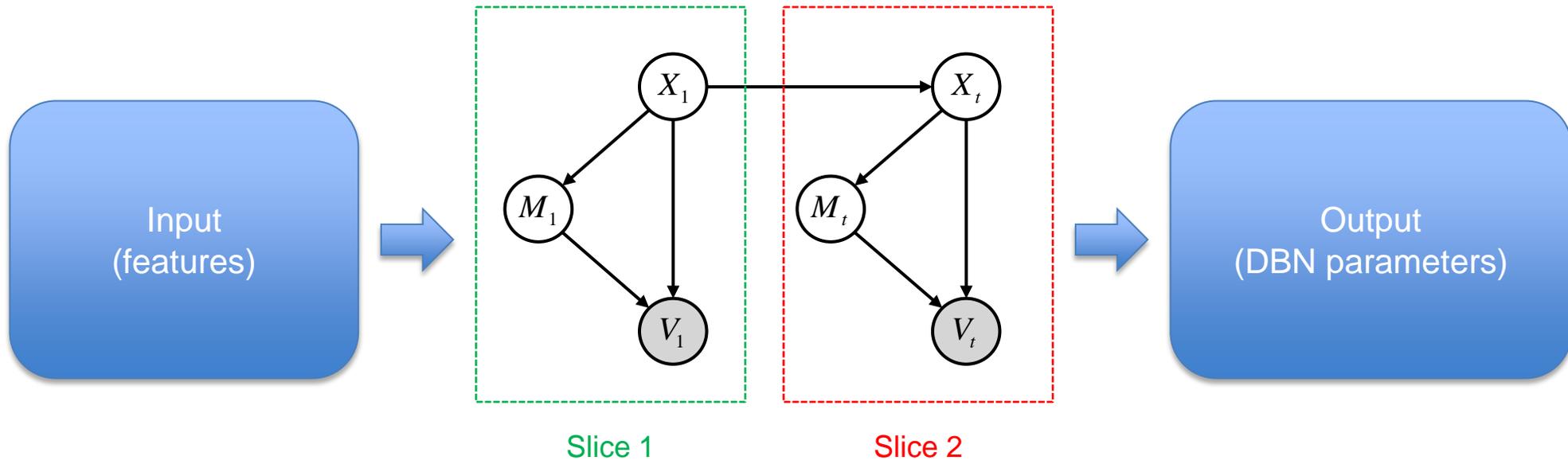
Regression models
(GPR, SVR)

- Modeling of uncertainty
- Taking into account of nonlinearities and nonstationarities
- Sparse regression
- Simplicity of implementation

Dynamic Bayesian Networks



$$\lambda_{RBD} = \{\pi, A, B, M\}$$



Learning: Baum – Welch algorithm

$$\{\pi, A, B, M\} | O$$

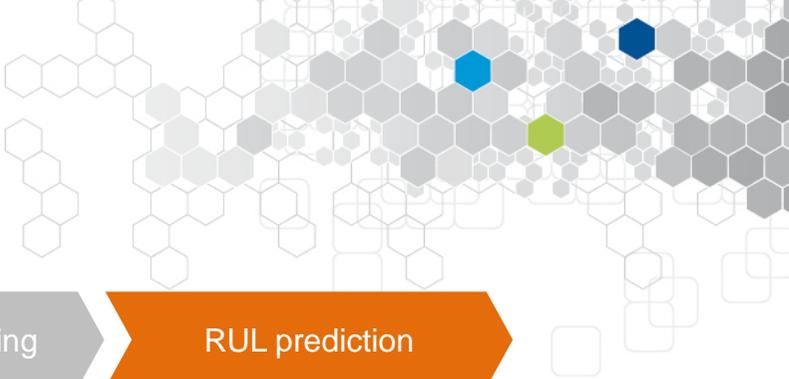
recognition: Forward – Backward algorithm

$$P[O | \lambda]$$

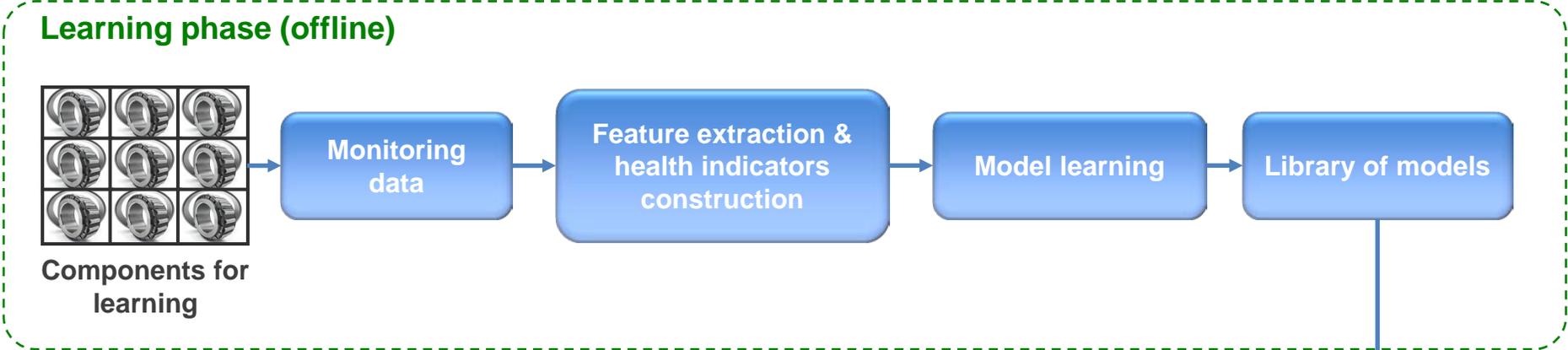
Identification of hidden states: Viterbi algorithm

$$\{X = x_1, x_2, x_t, \dots, x_T\} | O, \lambda$$

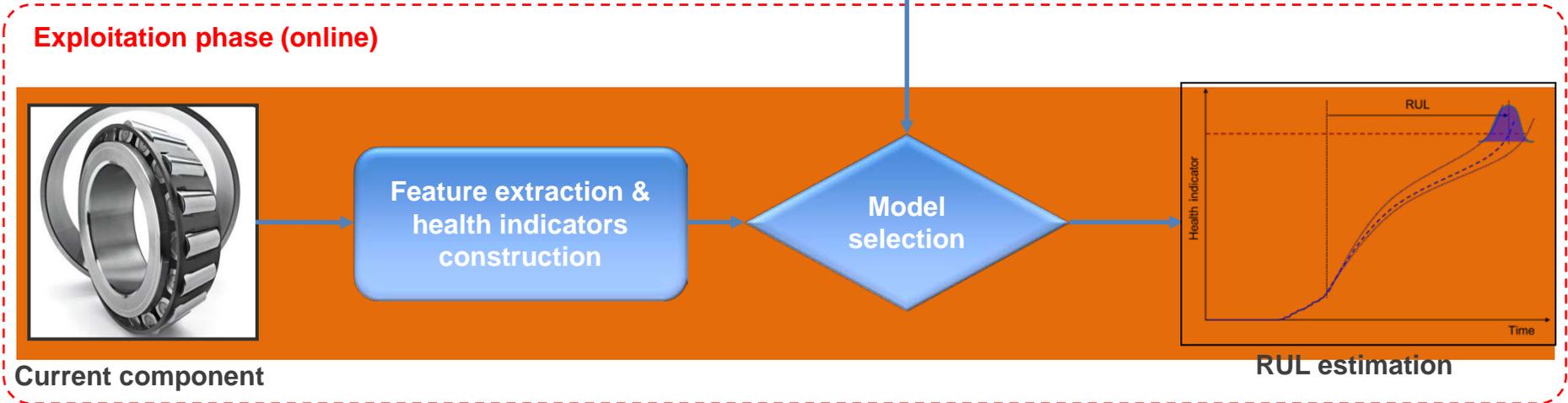
Health assessment & RUL



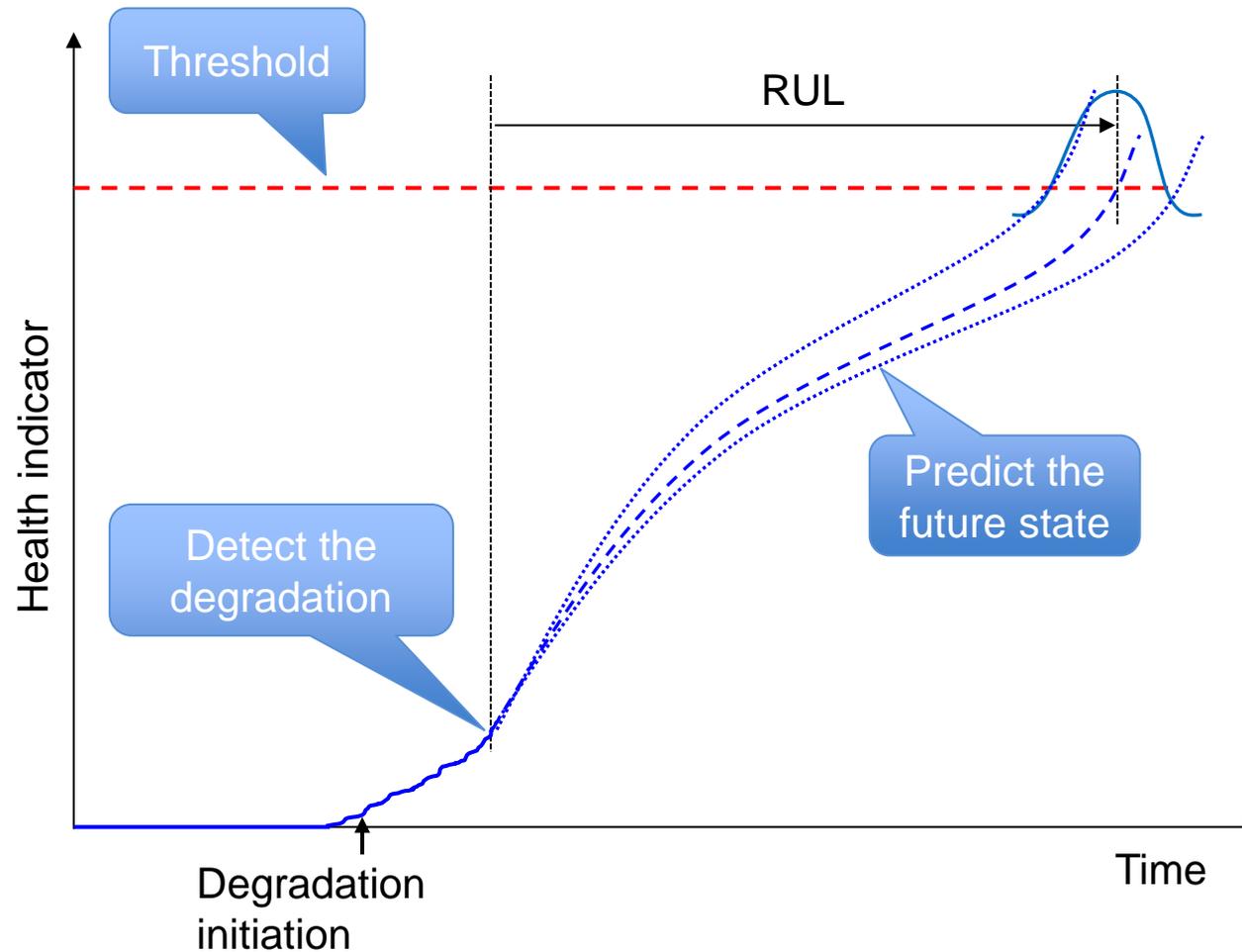
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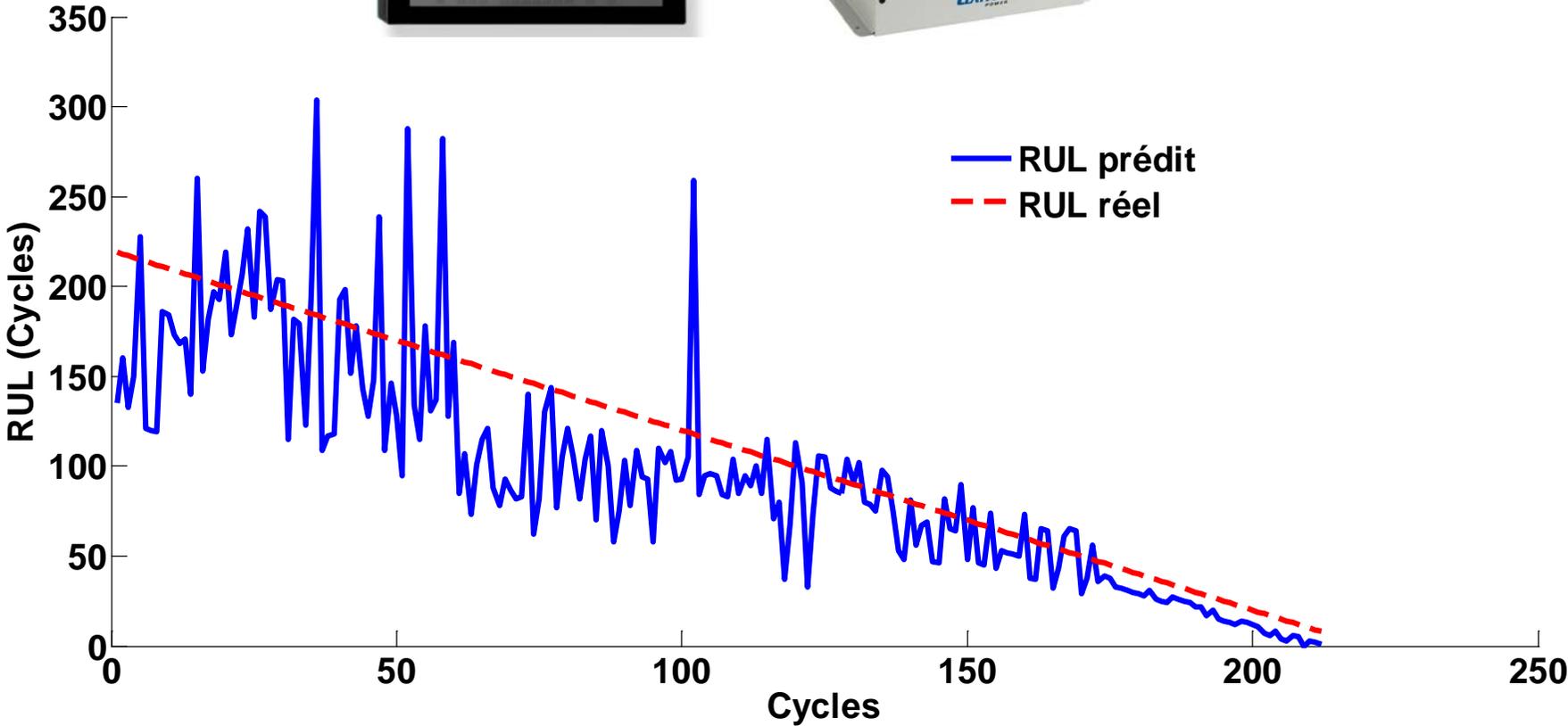
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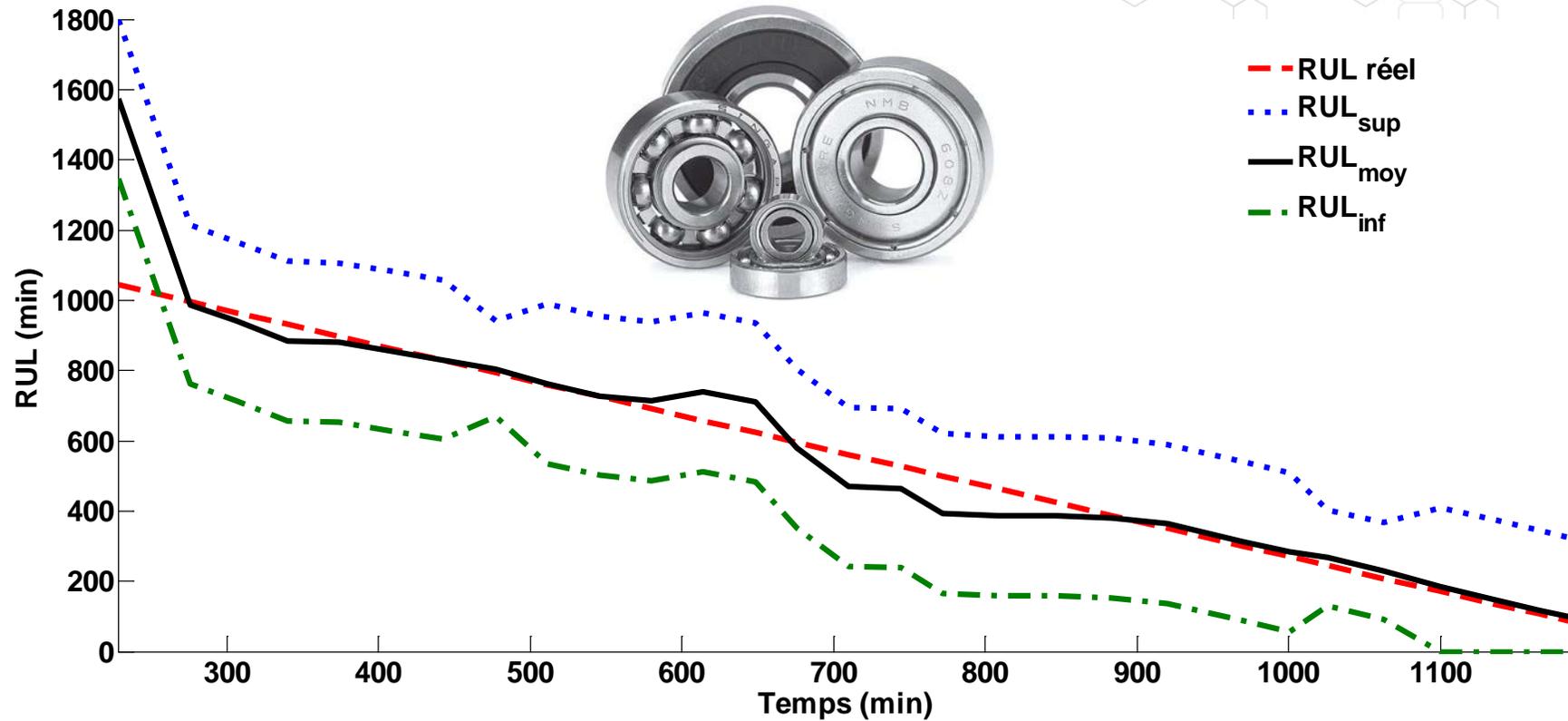
Health assessment & RUL



RUL results

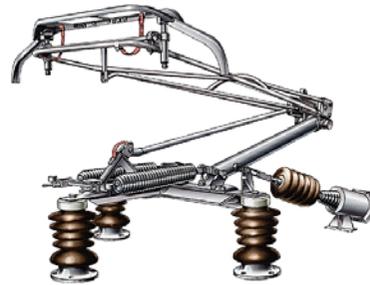


Résultats de RUL



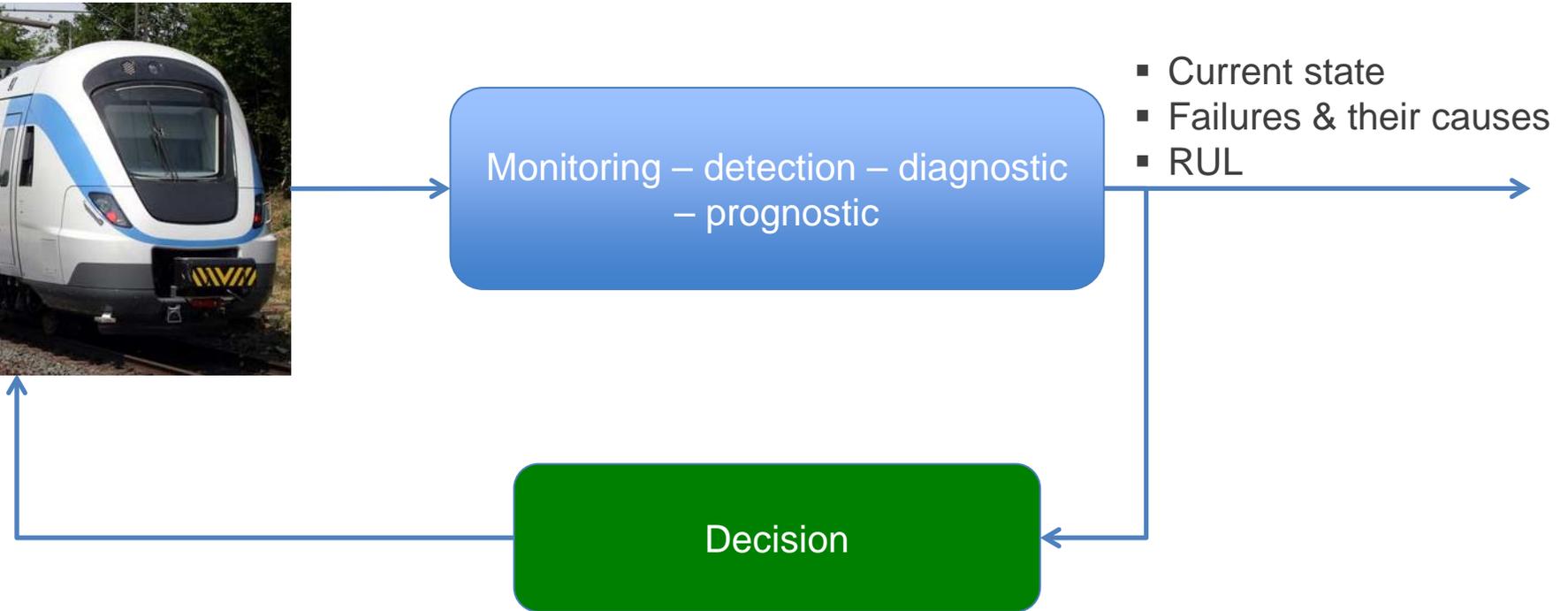
	Accuracy	Precision	MAPER	HP	$P_{\alpha_c - \lambda_c} (0.2-0.5)$	ER [0.25 0.5 0.75]
RUL _{sup}	0.5987	111.1	64.89	913	Yes	[0.81 0.75 0.20]
RUL _{moy}	0.9224	108.1	8.52	913.6	Yes	[0.98 0.83 0.95]
RUL _{inf}	0.6238	116.1	50.44	961.1	No	[0.84 0.43 0.28]

PHM of complex systems



- Model the interactions between components
- Assess the global health state of the system
- Predict the global RUL of the system

Decision



Conclusion & Perspectives



- **Dependency between components**
- Observability of the degradations

- Universal features/indicators
- **Physical health indicators**

- **Physical models**
- Validation of the models

- Uncertainty associated to predictions and to RUL
- **Adaptive thresholds**



What about decision?

« Automation » – Implementation – validation on real systems

Conclusion & Perspectives



PHM designed systems



Self-reconfiguration, fault tolerant...

Self-monitoring, self-detection, self-diagnostic,
self-prognostic



Towards smart monitoring for more availability & safety...

Questions?



Thank you for your attention!



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