

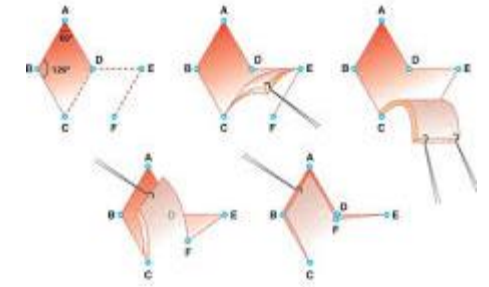
Several devices dedicated to experimental characterization of human skin in vivo/ex vivo (Emmanuelle Jacquet)

Collaborations between : FEMTO-ST (DMA) (Jérôme Chambert, Patrick Sandoz)
INSERM CIC 1431 (Gwenael Rolin, Delphine Binda biologists)
CERT (Thomas Lihoreau, biomedical engineer)
maxillo-faciale surgery (Brice Chatelain)
Plastic and reconstructive surgery (Julien Pauchot)
And PhD students, Fouad Khatyr and D. Remache

OPPORTUNITIES

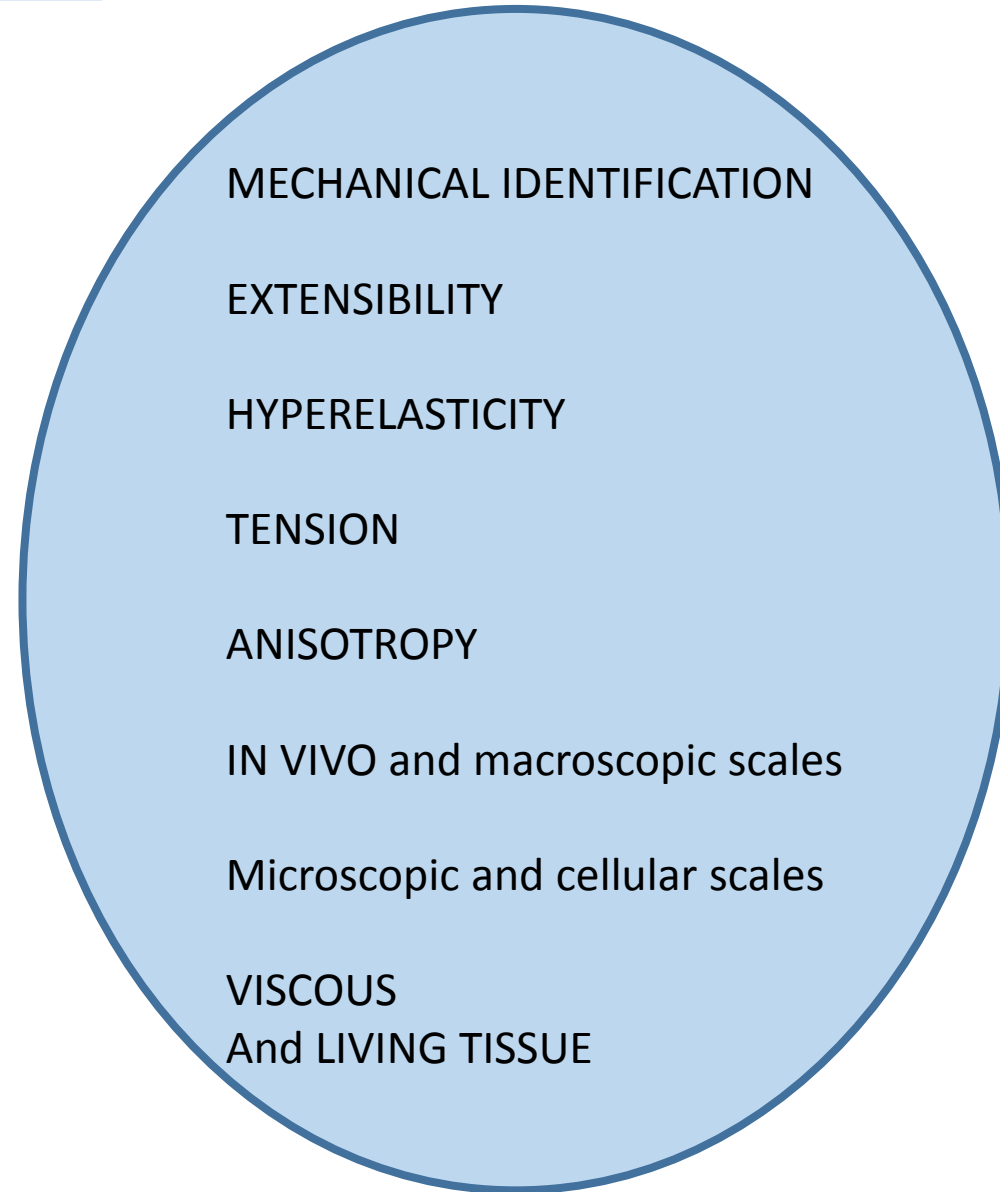
Medical problematics *related to human skin mechanical behaviour*

- Cutis laxa – Aging – diagnosis
- Serious burns
- Flap surgeries
- Keloids or hypertrophic scars
- Virtual reality simulator – Simulator training and learning system
- Haptics
- Sensorial properties



Interest dealing with mechanics of the skin :

- Cutis laxa – Aging – diagnosis
- Serious burns
- Flap surgeries
- Keloids or hypertrophic scars
- Virtual reality simulator – Simulator training and learning system
- Haptics
- Sensorial properties



Thematics

- ❖ Tissue engineering
- ❖ Knowledge of pathology
- ❖ Modelisation
- ❖ Medical devices or Research device
- ❖ ...

Standalone uniaxial extensometer in vivo

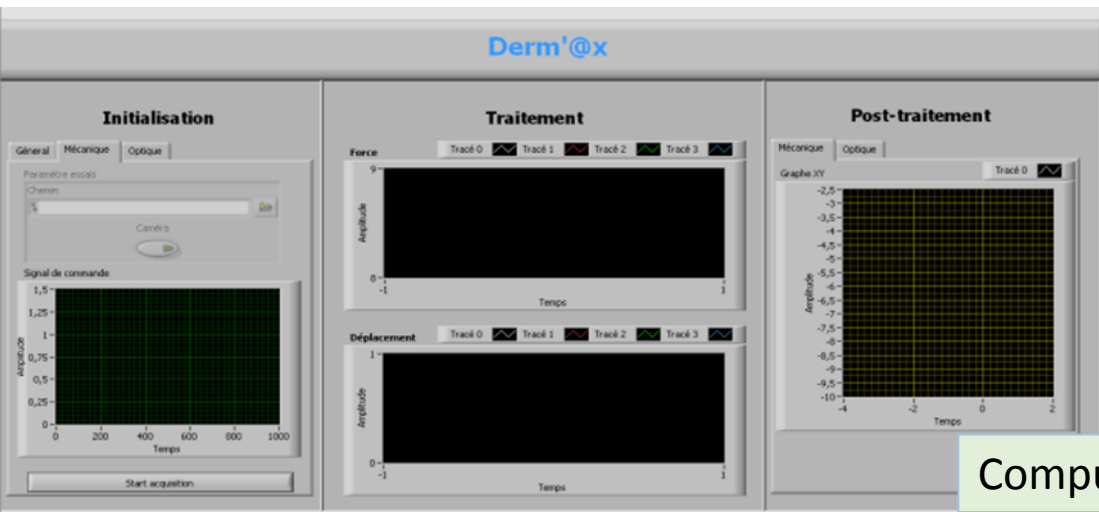
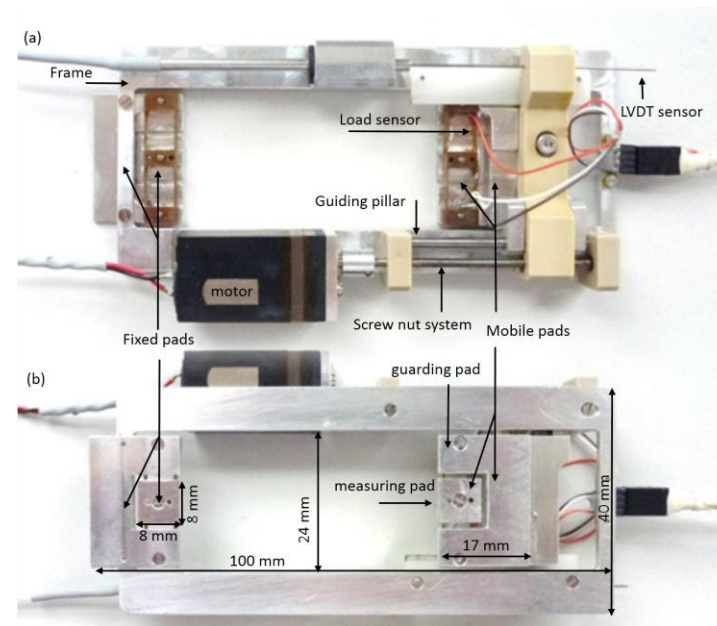
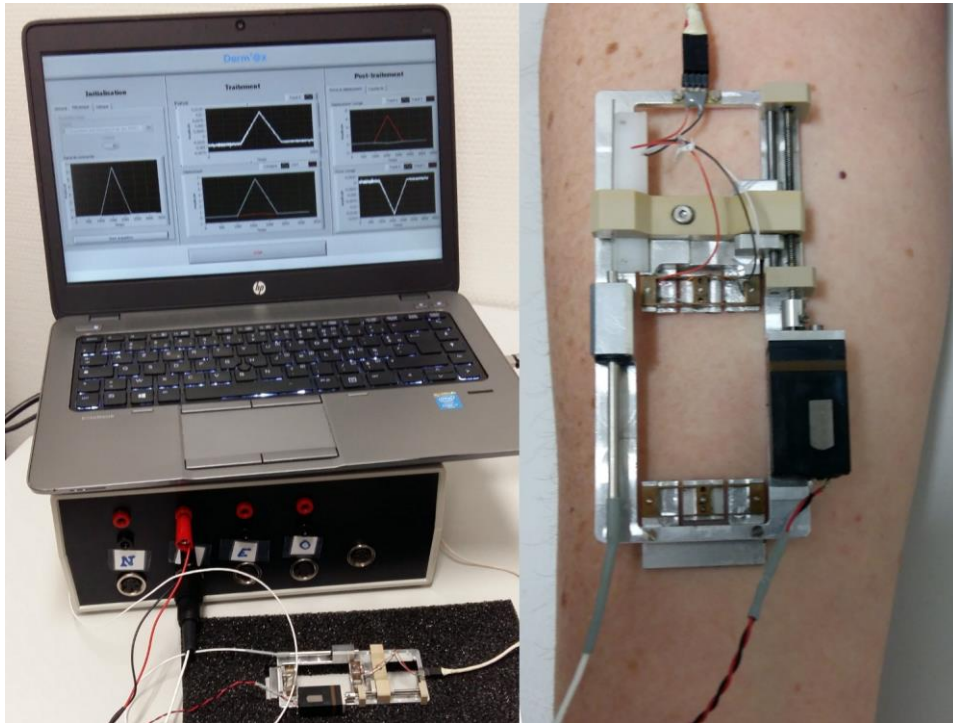
ULTRA-LIGHT

NUMEROUS

ANATOMIC SITES

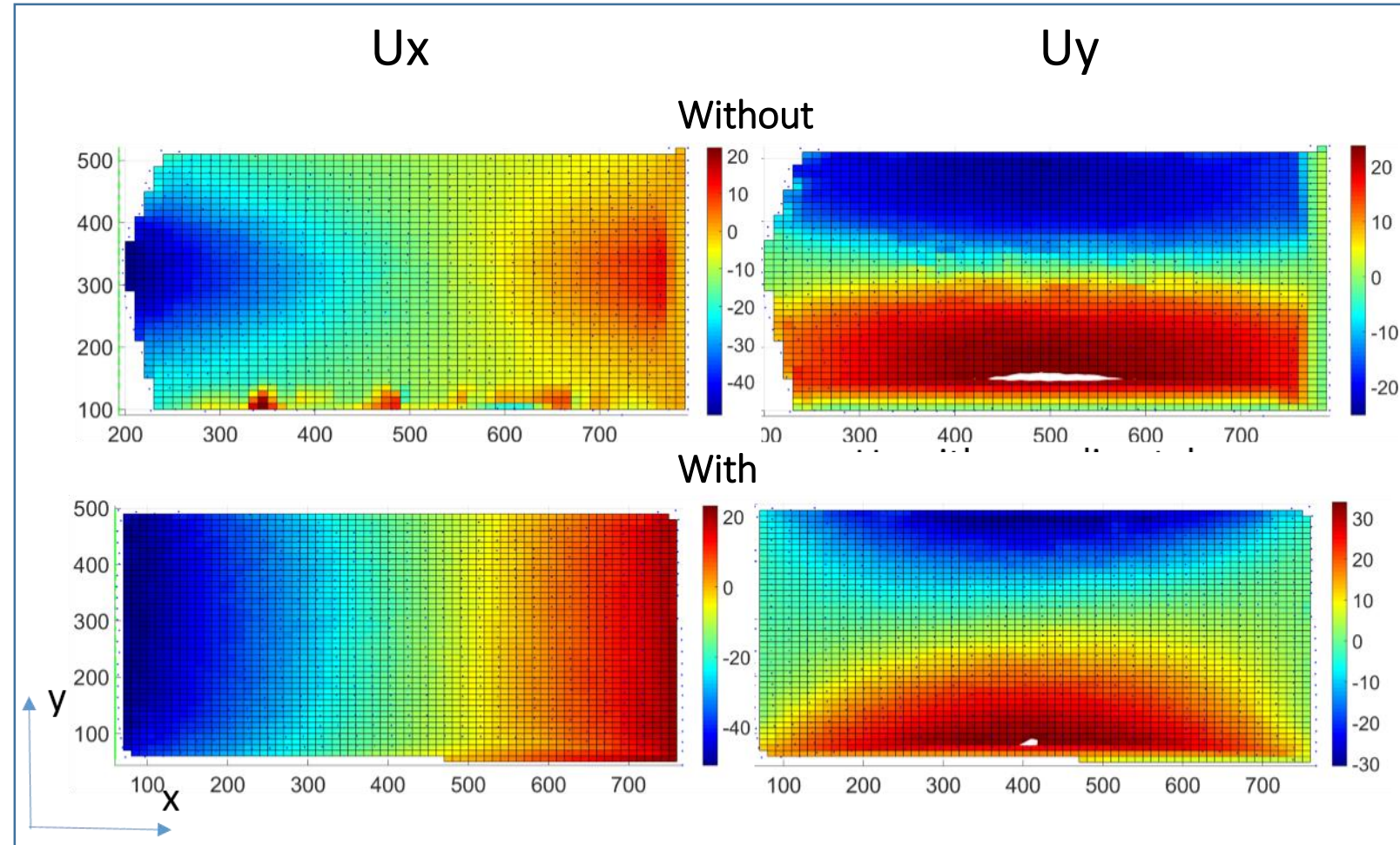
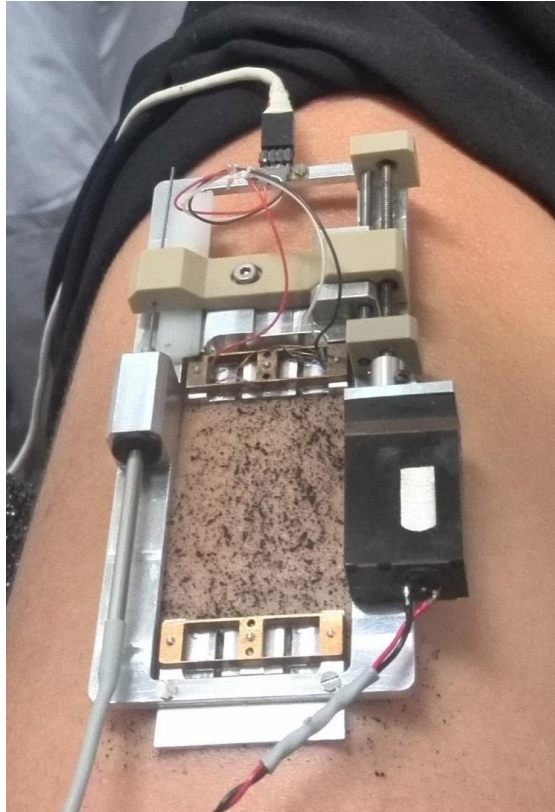
Technical specifications Values

Size	100 x 40 x 6 mm ³
Mass	35g
Observable area	40 x 24 mm ²
Maximal strain	150%
Maximal load	10N
Effort sensor	5mN
Displacement sensor	38µm
Maximal displacement	17mm
Maximal speed	1,5mm/s



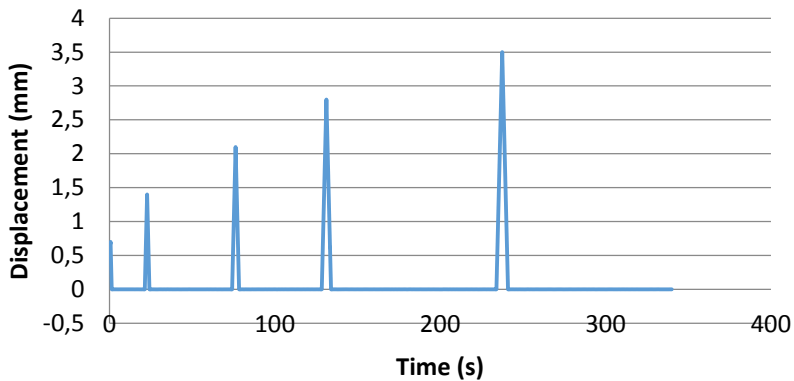
Standalone uniaxial extensometer in vivo

IMAGING DEVICE : ADDITIONNAL U-PADS
DIGITAL IMAGE CORRELATION (DIC)

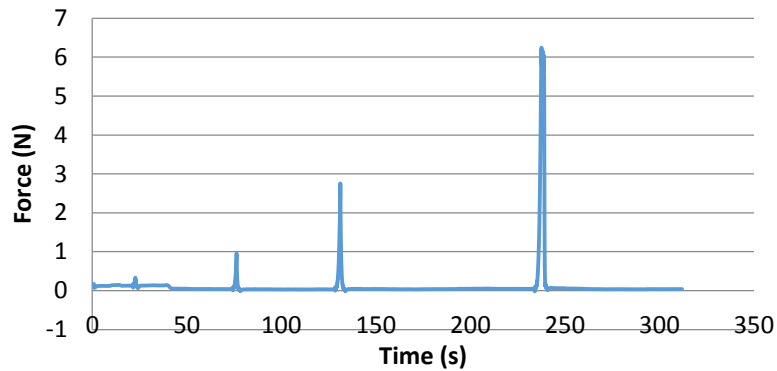


*SLIGHT DISTURBANCE ACCORDING LOW
GESTURES*

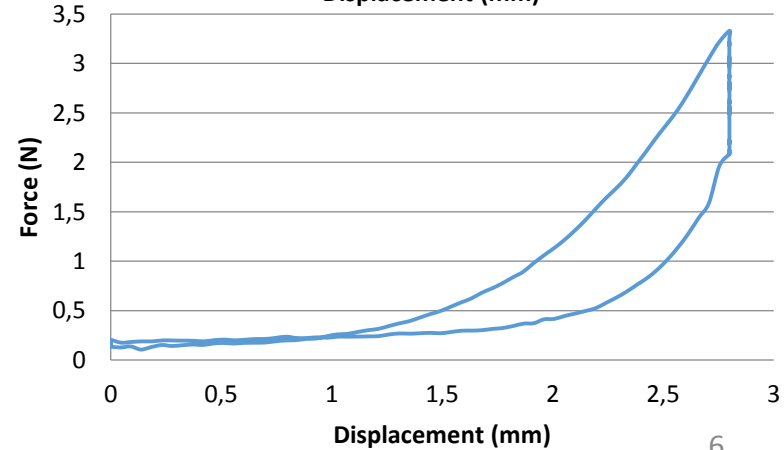
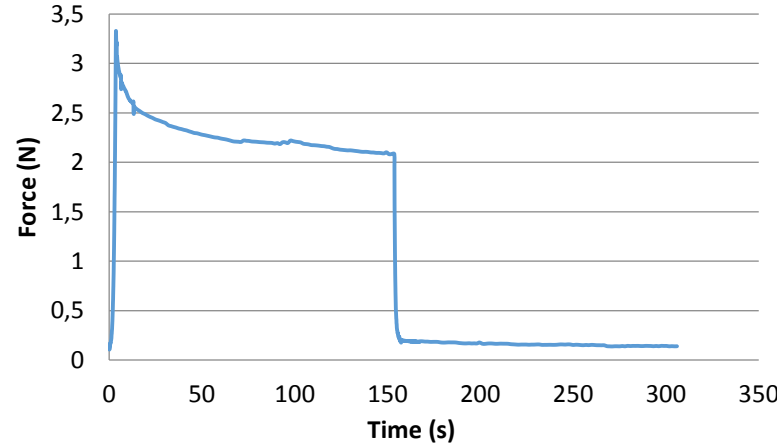
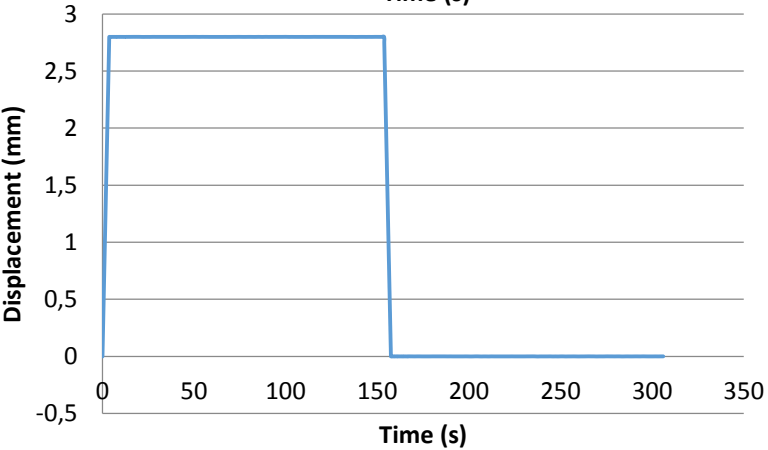
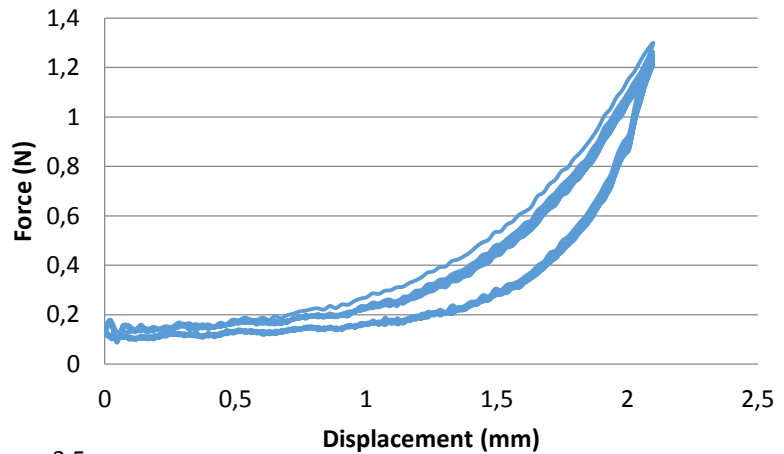
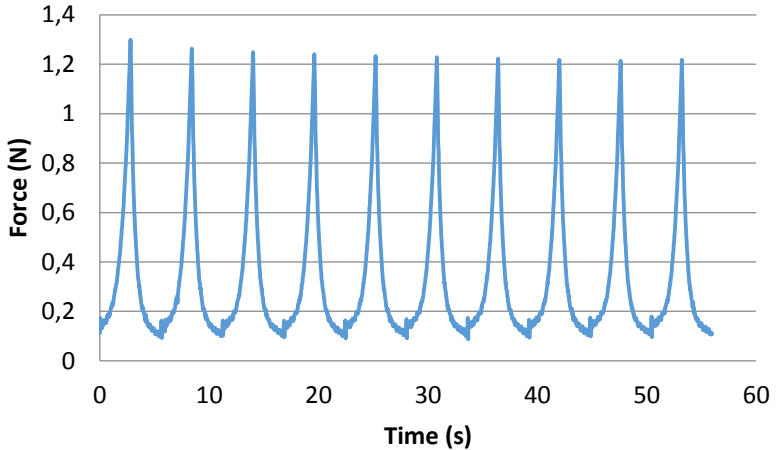
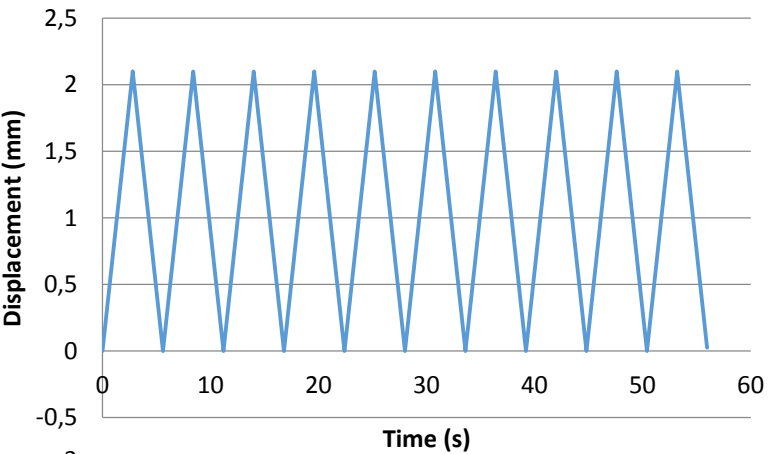
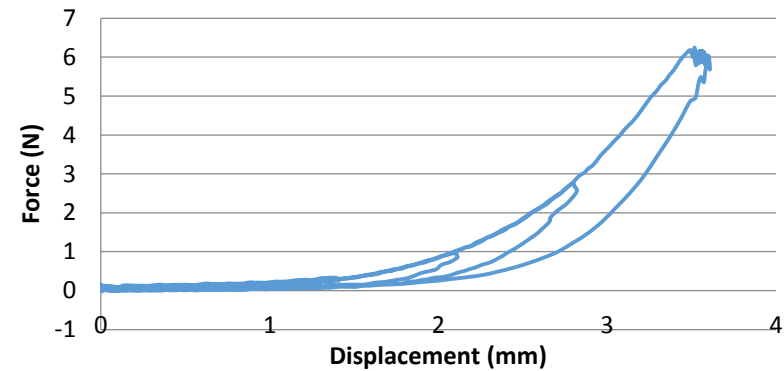
Command



Force vs. Times

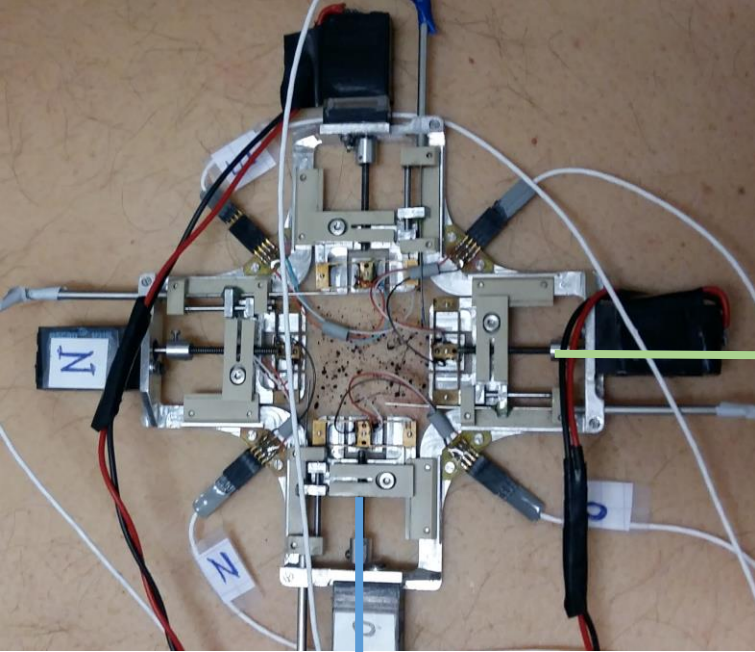


Force vs. Displacement



Standalone biaxial extensometer 3 in vivo

S. Joly, K. Rekik, J. Chambert, P. Sandoz 2016



COMMAND SOFTWARE
4 MOTORS
4 LVDT
4 FORCE SENSORS
UNUSABLE (MANY WIRES)

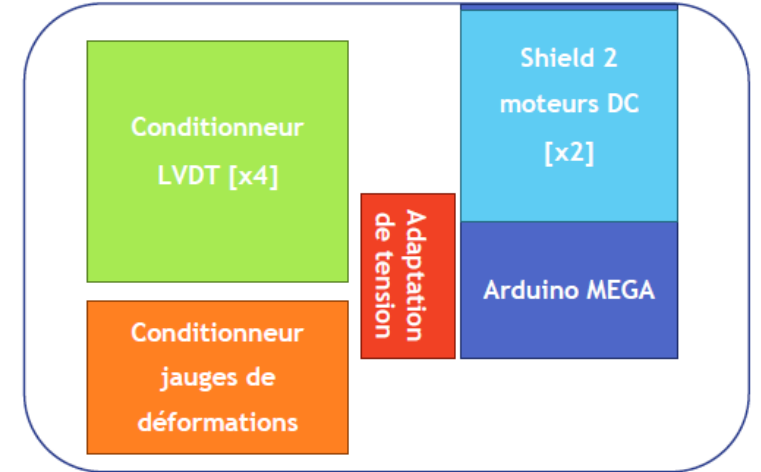
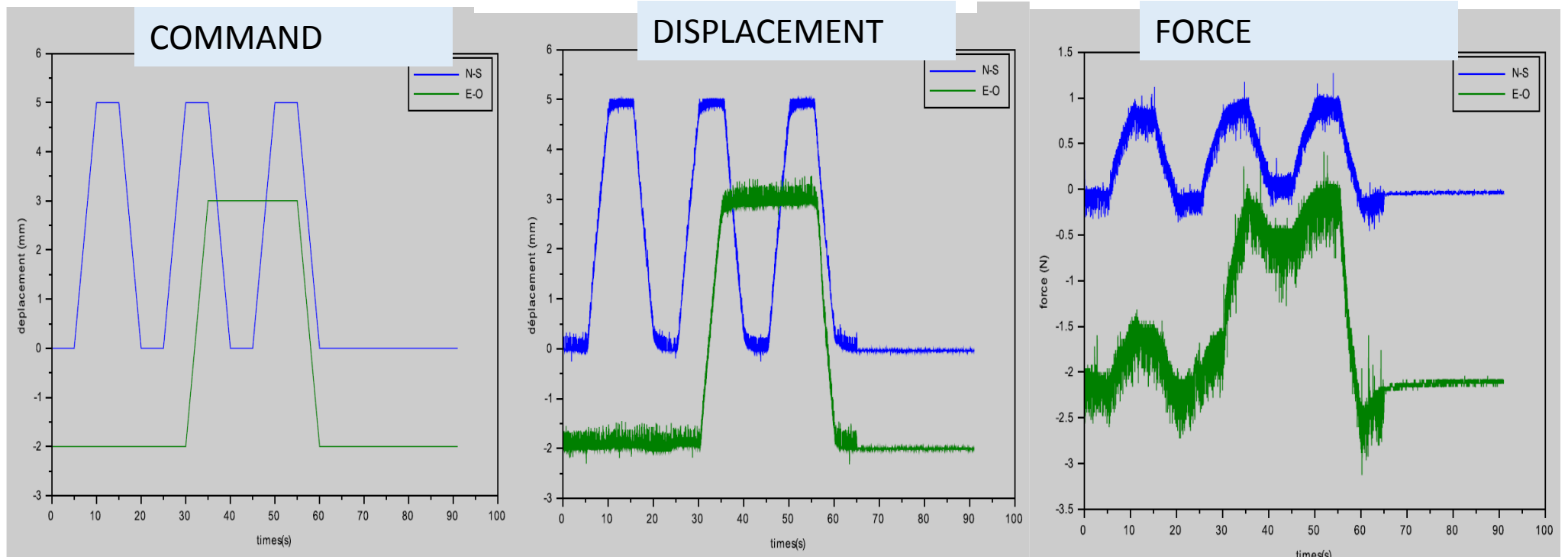
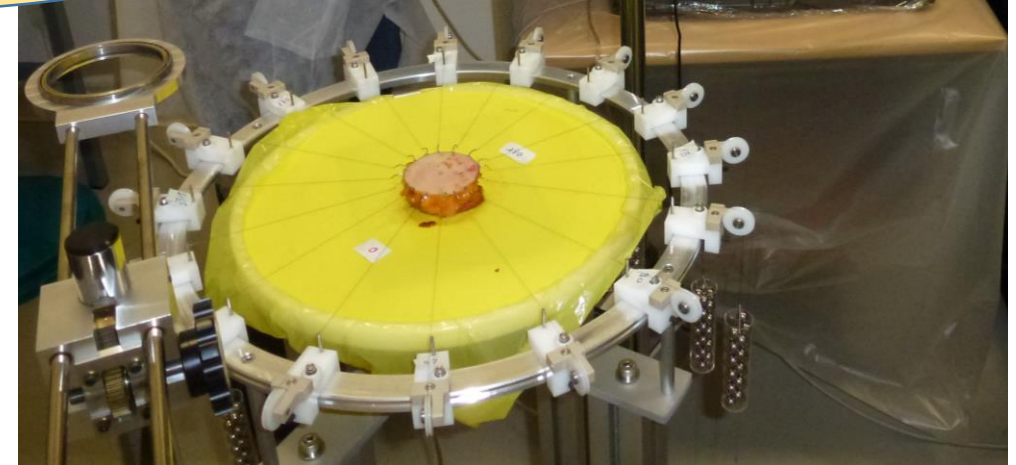
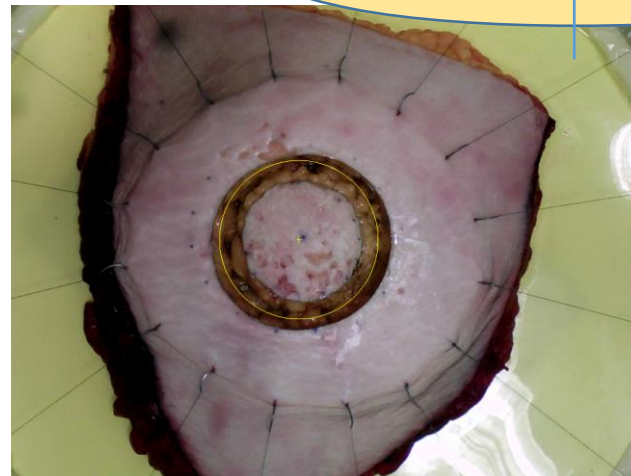
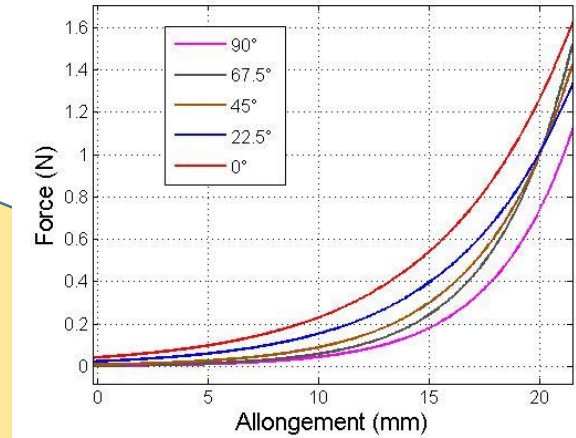
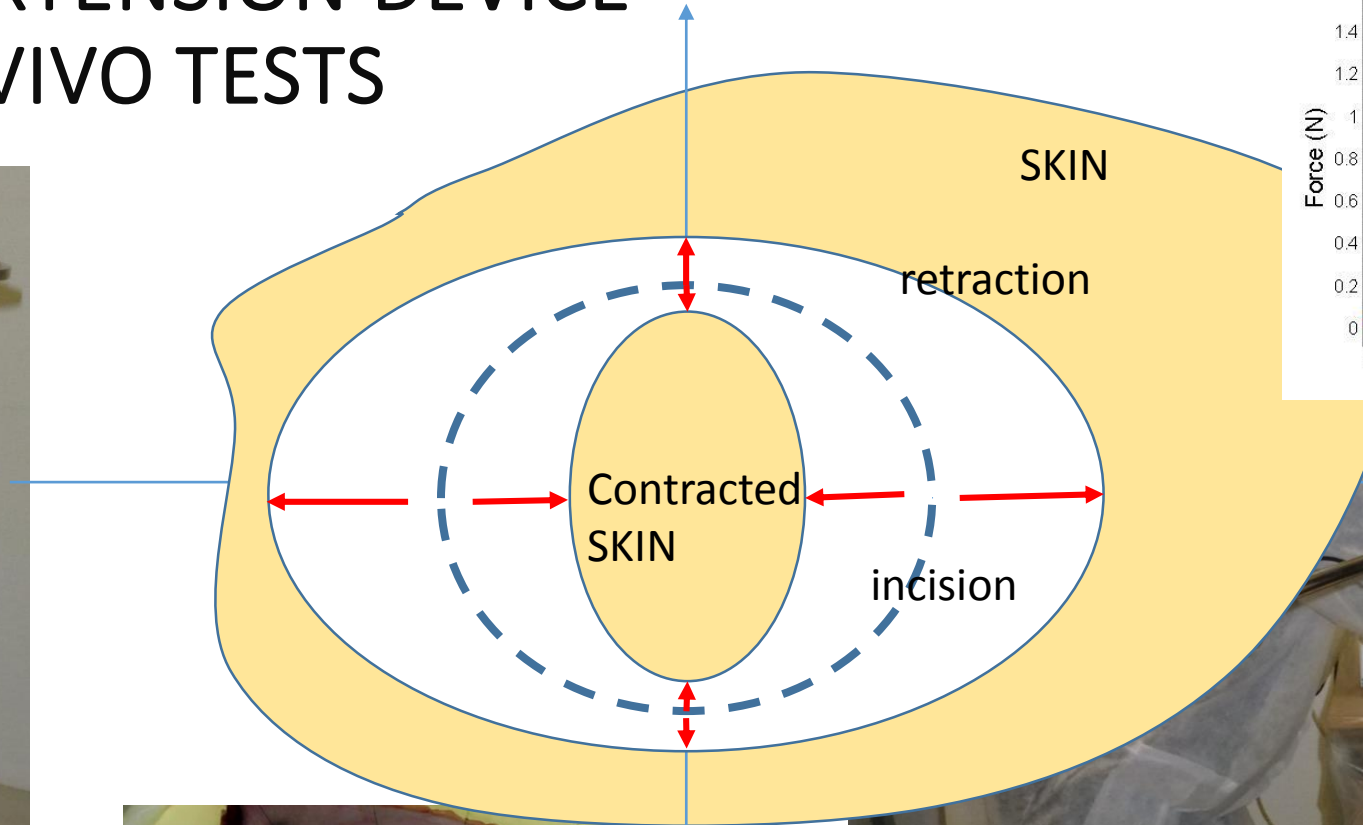


Figure 1 : Implantation cartes électroniques dans le boîtier



MULTIAXIAL EXTENSION DEVICE FOR EX VIVO TESTS



Remaining problems :

- High variability
- Unknown initial stress state

But also

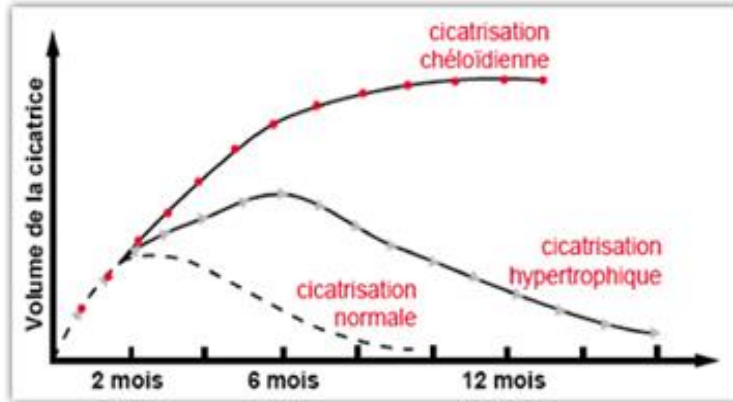
- Initial and induced anisotropy
- viscoelasticity

Project and priority:

Develop an useful tool for surgeon to characterize the tissue directly with intrinsic mechanical parameters

One model problem

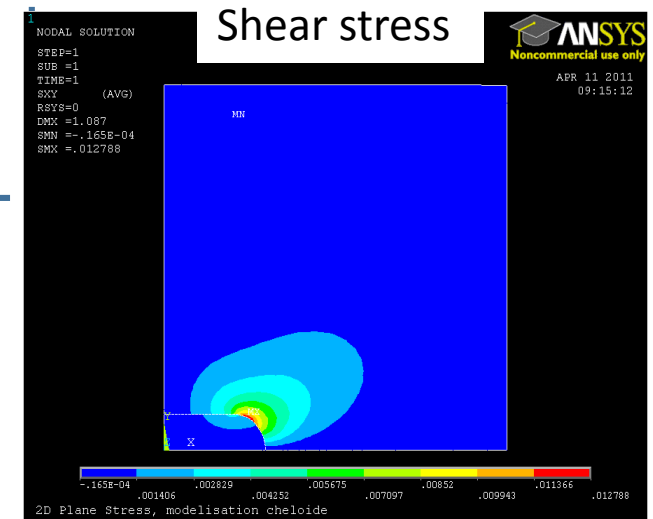
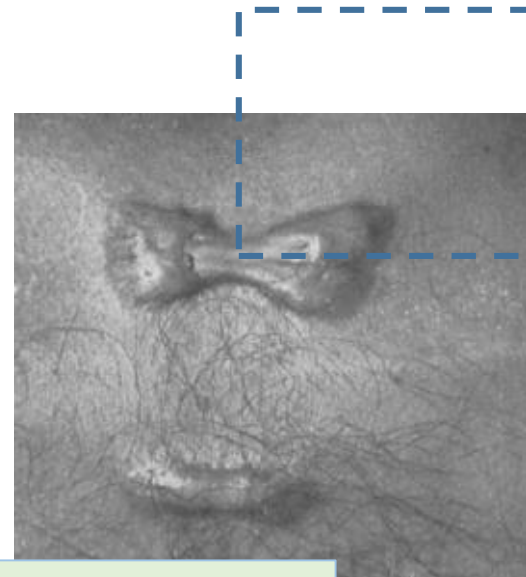
TRY to UNDERSTAND What HAPPENS mechanically in keloid scars



Medical aim : develop a strategy to mechanically prevent keloid growth

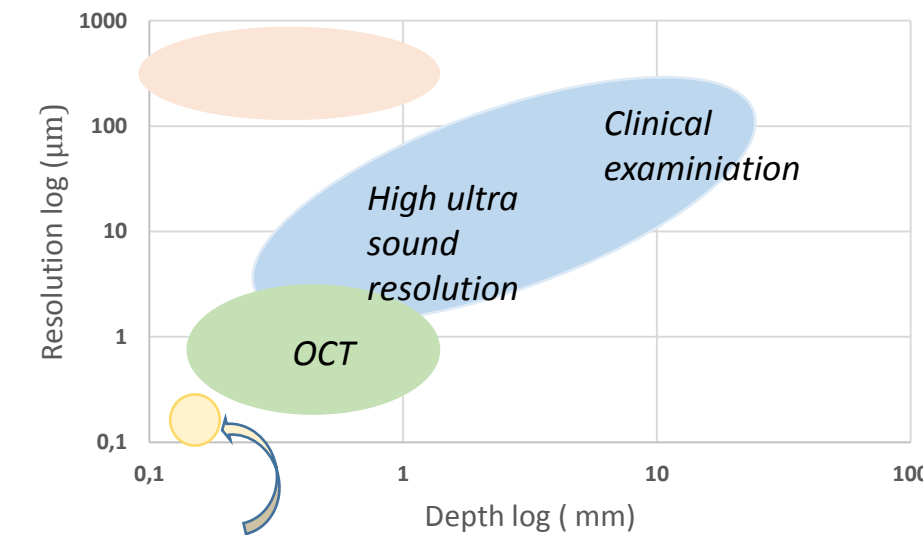
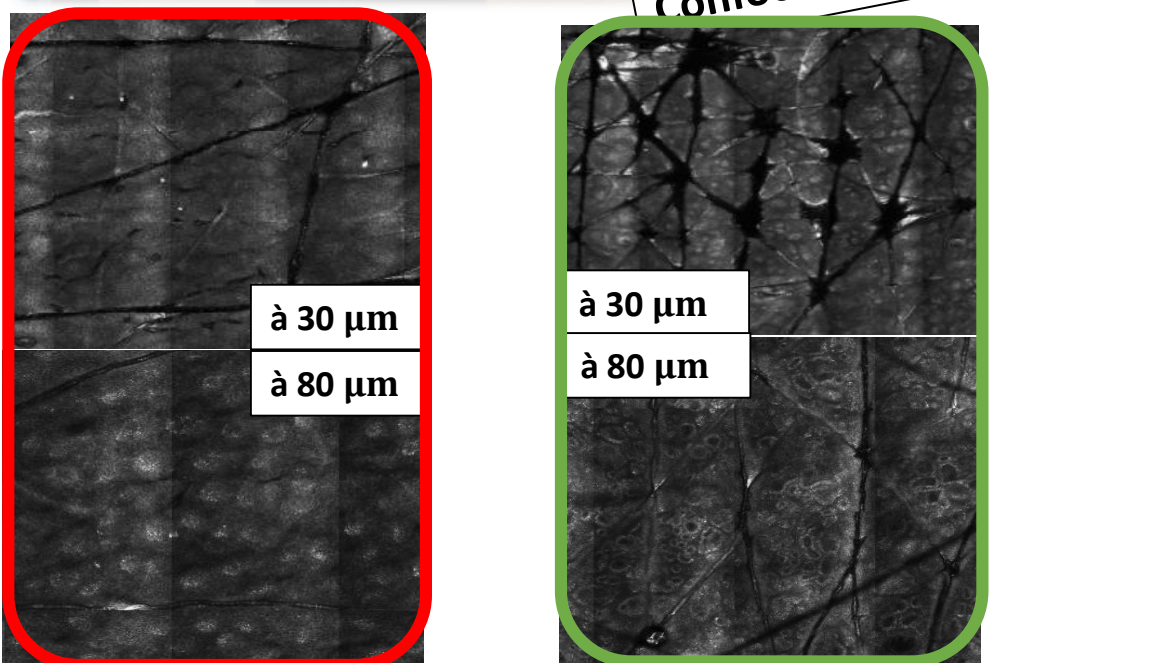
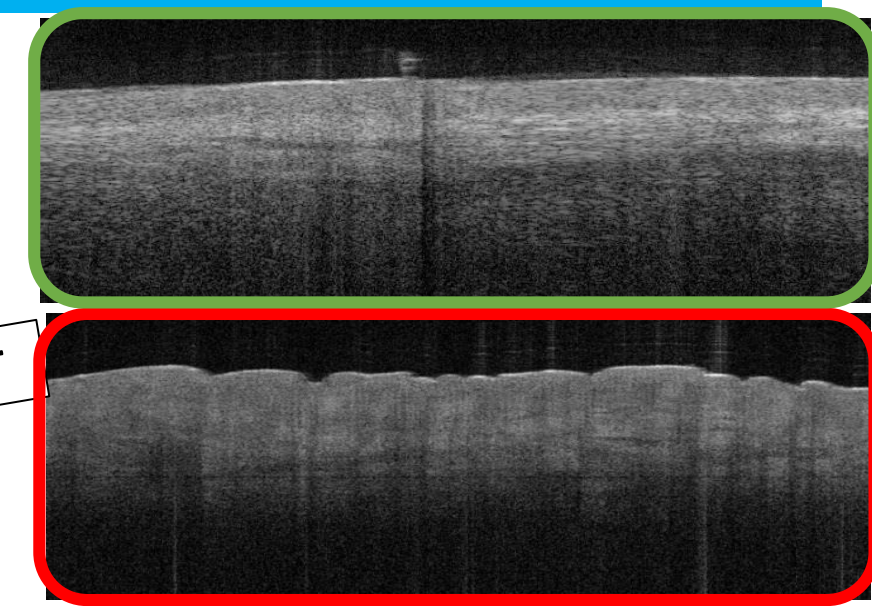
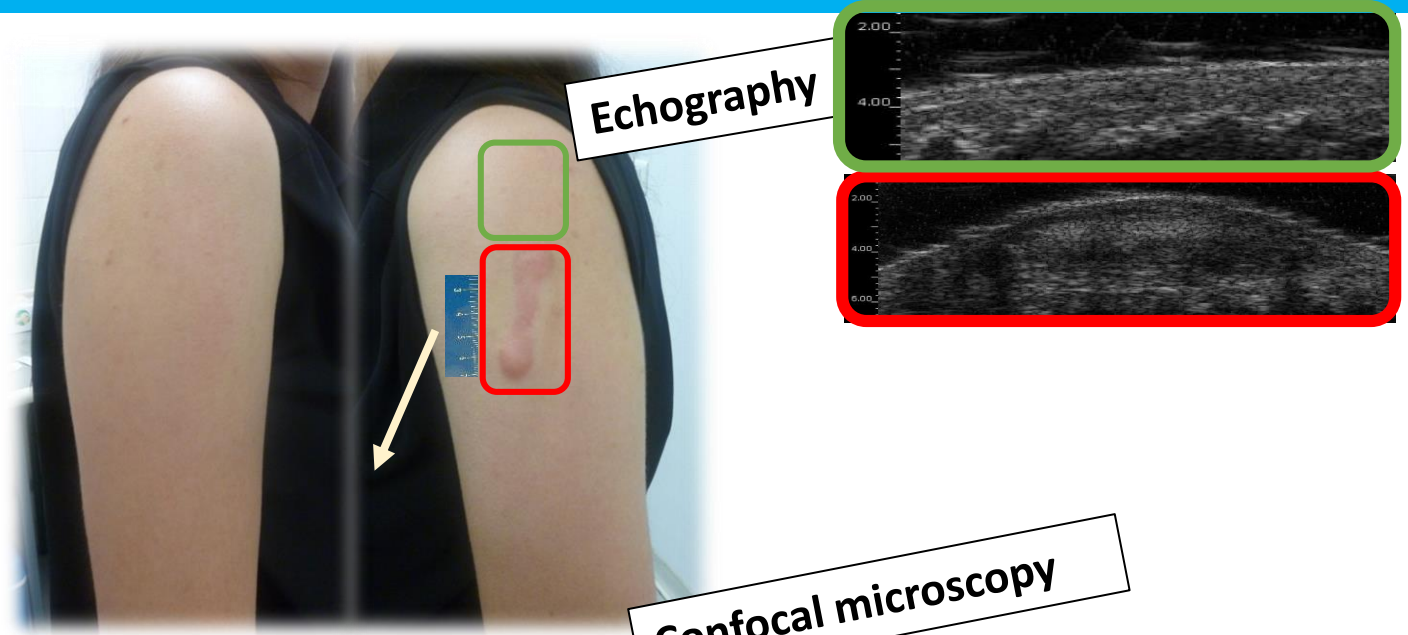


- COMMON SITES OF KELOIDS
 - ANTERIOR CHEST
 - SHOULDER
 - SCAPULAR REGION
 - SUPRAPUBIC REGION
- RARE SITES OF HEAVY SCARS
 - PARIETAL REGION
 - ANTERIOR LOWER LEG

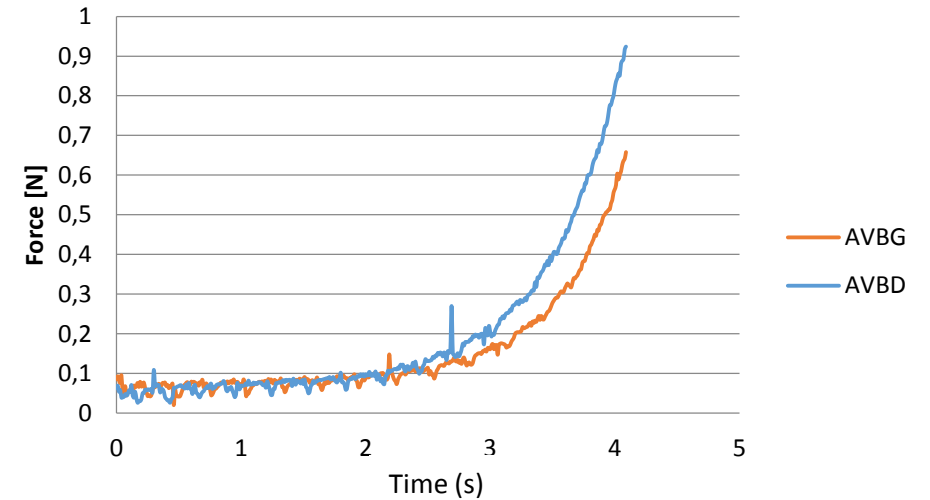
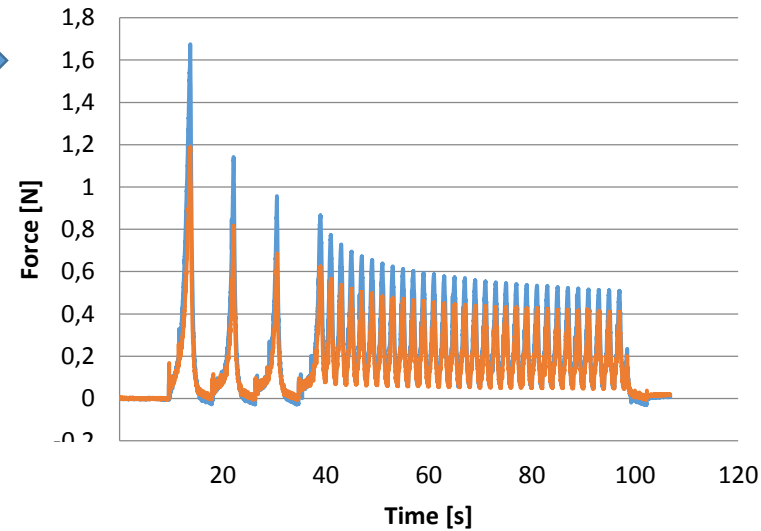
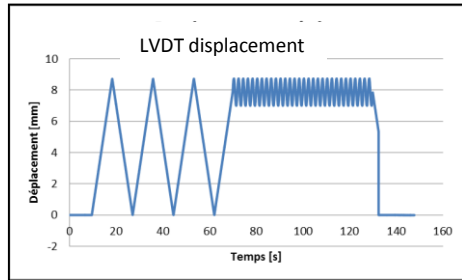


Various physical and biological observations, keloid versus healthy skin in vivo

Collaboration LIBC (Gwenael Rolin), CERT (Thomas Lihoreau), CHRU service de chirurgie maxillo-faciale (Brice Chatelain)



Mechanical uniaxial behaviour Right versus left forearm



- Forearm
- Right and left
- Along Langer's lines

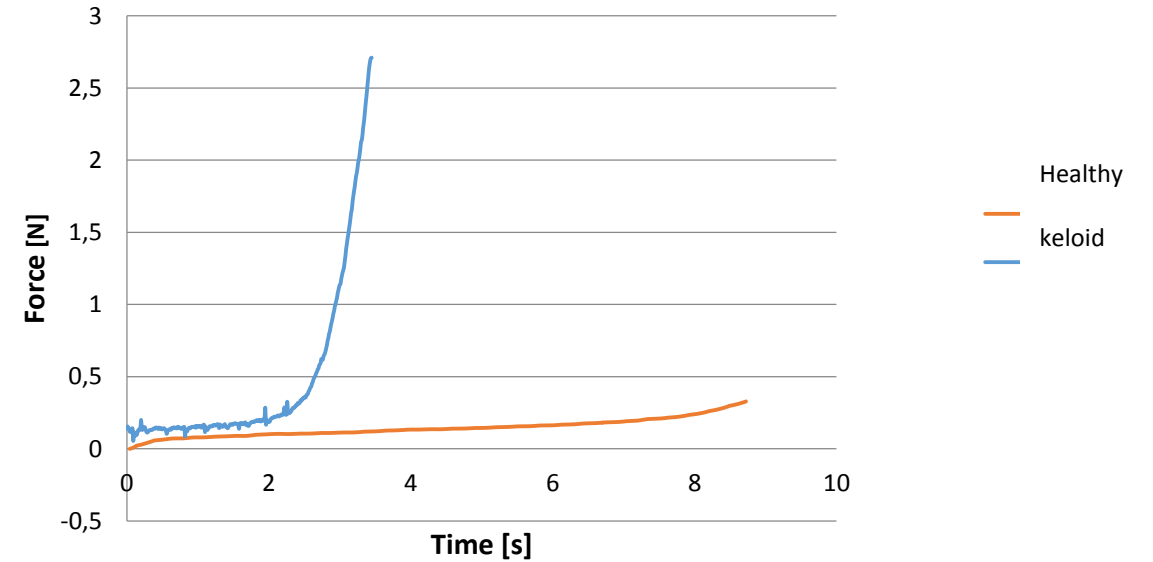
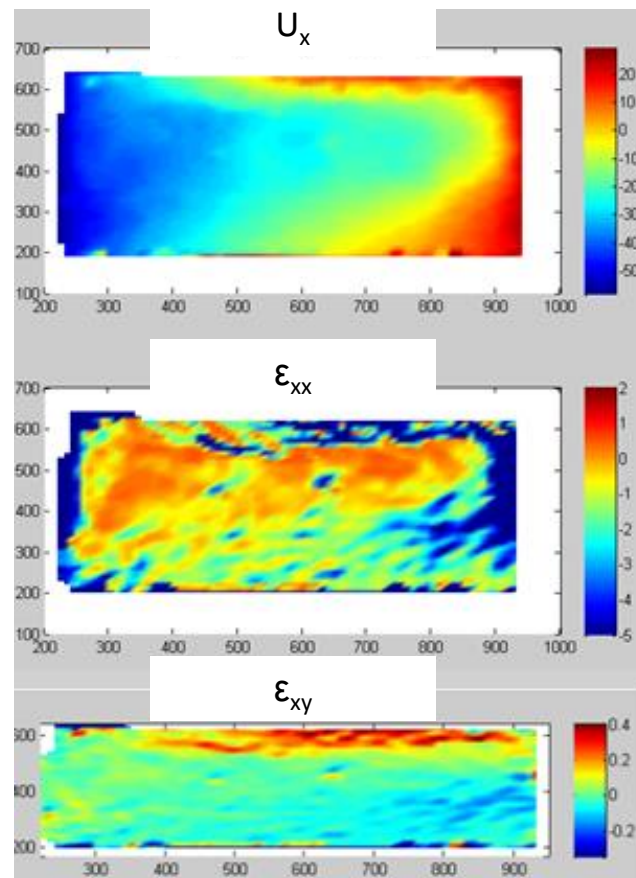
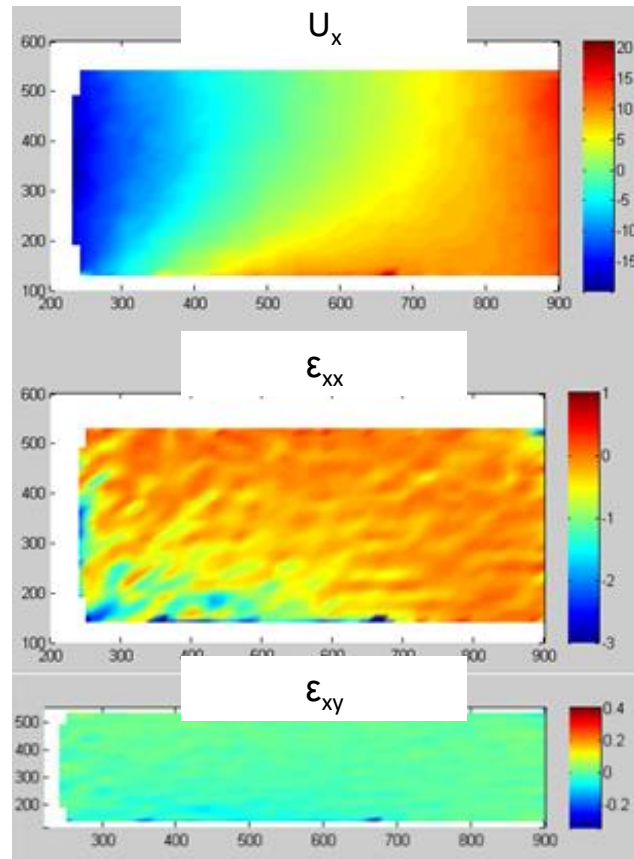
Healthy skin

and

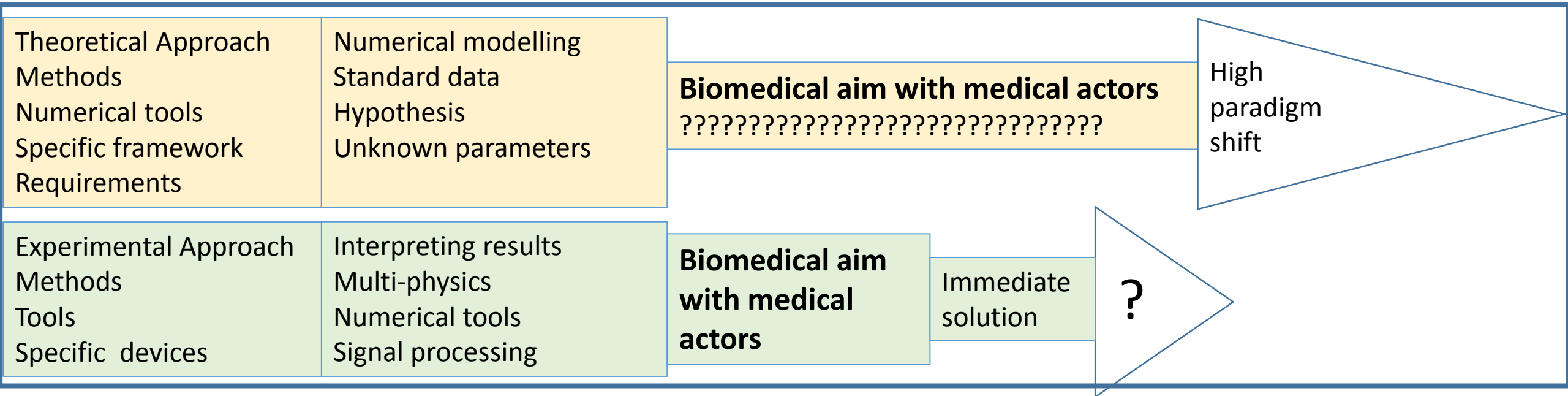
Keloid



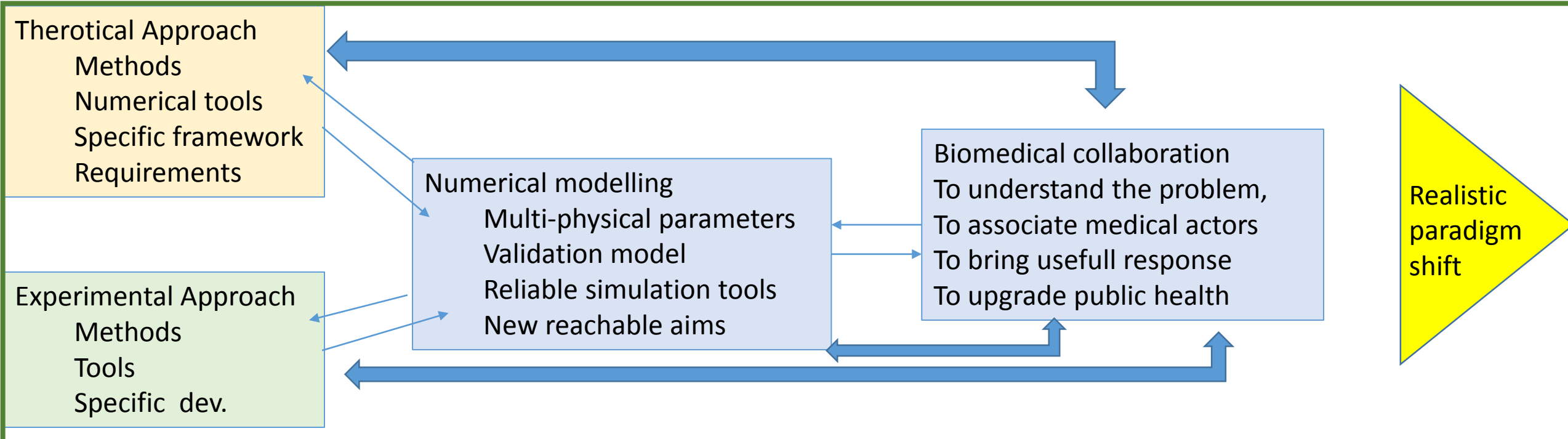
Comparison Keloid/Healthy skin



USUALLY now :



OUR CHALLENGE is like for now :



THANK YOU FOR YOUR ATTENTION