## femto-st SCIENCES & **TECHNOLOGIES Robotic nano-manipulation of MWCNTs on optical fibers for** flexoelectric measurements.

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We report on a new generation nanofactory able to produce 3D nano-structures under vacuum by functionalizing and/or patterning and/or assembling materials on top of optical fibers, with very high accuracy. This nano-factory, called µRobotex, consists in a Zeiss Auriga 60 dual beams SEM/FIB, a GIS (Gas Injection System) and two microrobotic arms (from Kleindick and SmarAct). It allowed us to manipulate Multi-wall Carbon Nanotubes (MWCNTs) one by one in order to measure flexoelectric properties.

- I The platform
- Auriga 60 from Zeiss with dual
- Gas Injection System with: XeF<sub>2</sub> for

## MEB/FIB beams.

- Sample holder stage 5 DoF: X, Y, Z, Z' for eucentric point, and  $\Theta$  and smarAct Θ'.
- SmarAct micro robot with 6 DoF : X\*Y\*Z: 150\*70\*70 mm±10 nm, Θx (tools)  $360^{\circ}\pm0,001^{\circ}, \Theta y, \Theta z$ : 7°±0,001°.

etching and patterning materials,  $W(CO)_6$ , Cyclopentadienyl Pt, and naphtalen gas for CVD thin layer.

- Kleindick tip with 3 DoF,
- Working space of  $(0,5 \text{ mm})^3$  for assembly of the MWCNTs.



## **II** – **The robotic system**

- the eucentric point (SEM/=/FIB).





• Different movements were applied on the optical fiber or on the silicon cantilever. • These movements bend the MWCNT welded between a tip and a silicon cantilever. Difficulties to bend the NTC always in the observation plane for measurements.



Important projects in the field of nano-manipulation and assembly are on the way in µRoboteX station, in order to build 3D nano- or microstructures on top of optical fibers or tips. Using this facility, we can bend individual MWCNTs welded between two tips or between a tip and a silicon cantilever, in order to study flexoelectricity effects in a single MWCNT by measuring the variation of brightness.

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