Proton Exchange Membrane Fuel Cell System Prognostics and Decision-Making: Current Status and Perspectives

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Abstract

Proton exchange membrane fuel cell (PEMFC), as an attractive alternative power source, has seen its increasing deployment in both automotive and small stationary applications. To improve the durability of the PEMFC system, which is one of the primary challenges standing in the way of its successful market introduction, recent research has engaged in developing prognostics and health management methods. Although the prognostics methods have been extensively studied to improve the prediction accuracy, some critical issues have not been fully addressed. For example, few studies have looked into the prognostics methods by different criteria and under dynamic operation conditions, and none of them have investigated the data availability and quality for PEMFC prognostics. Due to the lack of more comprehensive and general prognostics methods as well as the limitations in data, studies in the post-prognostics decision-making phase have hardly ever been initiated. This paper tends to provide a full review of the existing prognostics research by analysing the prognostics scales, horizon, threshold, and the use of methods. The data used in the previous studies has also been investigated. Moreover, four principal directions of post-prognostics decision-making have been proposed and discussed. This paper reviews the prognostics methods by analysing the prognostics scales, horizon, threshold and the use of methods for different operating conditions and reports the available experimental datasets used for PHM studies and their limitations. Then, we point out that the current research is devoted to investigating the fuel cell prognostics, but the post-prognostics decision-making phase has not been sufficiently studied due to the lack of datasets, inconclusive problematics and incomplete methodology. In this paper, four post-prognostics subjects are analysed and discussed, including

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degradation tolerant control, multi-stack control, energy management, and maintenance scheduling. According to the findings, research challenges and development perspectives in the aspects of data, prognostics and decisionmaking are proposed.

Keywords:

dataset, decision-making, health management, PEMFC, prognostics

Nomenclature

Abbreviations

ANFIS adaptive neuro fuzzy inference system

DBN - ELM deep belief network extreme learning machine

DOE Department of Energy

ECSA electrochemical surface area

EIS electrochemical impedance spectroscopy

 $EKF\,$ extended Kalman filter

EMS energy management strategy

EOL end of life

ESN echo state network

GMDH group method of data handling

GRU gated recurrent unit

 H_2 hydrogen

HITP hardware-in-the-loop

IoT internet of things

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LPV linear parameter varying

LSTM long short term memory

LWPR locally weighted projection regression

MAPE mean absolute percentage error

MEA membrane-electrode assembly

 $MPC \mod predictive \ control$

PEMFC proton exchange membrane fuel cell

PF particle filter

PHM prognostics and health management

 R^2 R squared error

RMSE root mean square error

RUL remaining useful life

SOH state of health

SW - ELM summation wavelet extreme learning machine

 $UKF\,$ unscented Kalman filter

Physics symbols

 D_{fc} fuel cell degradation

 P_{actual} actual power

 P_{rated} rated power

 $P_{required}$ required power

 t_{λ} time to start prognostics

 t_f time of EOL

1 1. Introduction

Proton exchange membrane fuel cell (PEMFC) has seen its increasing 2 deployment in both on-board and stationary applications, which is an at-3 tractive alternative to fossil fuel devices with high energy output and no 4 pollutants. In today's fast energy transition period, minimizing fuel cell sys-5 tem costs is an important task for its successful market introduction. The 6 approach towards this goal is threefold - components design, production, 7 and operations, as shown in Figure 1. In addition to the efforts made in the 8 design and assembly process, enhanced efficiency and durability can be ex-9 pected through appropriate stack operation. The Department of Energy 10 (DOE)'s Fuel Cell Technologies Office has set the 2020 target of 5,000 11 hours' durability for on-road fuel cell electric vehicles, which corresponds 12 to an expected driving distance of 150,000 miles within a particular range 13 of speeds, while the ultimate goal is 8000 hours [1]. According to an evalu-14 ation project launched by the National Renewable Energy Laboratory, the 15 durability of on-board fuel cells has increased 1.5 times since 2006 and the 16 maximum operation time has reached 5,605 hours, however, only 22% of the 17 tested fuel cell stacks have passed 2,000 hours of operation [1]. The Fuel 18 Cells and Hydrogen 2 Joint Undertaking has set the durability targets for 19 the light duty fuel cell vehicles in its Multi-Annual Work Plan 2014-2020 20 (MAWP 2020) that the lifetime of the fuel cell system should be further 21 improved to reach 6000 hours before 2024 and 7000 hours before 2030 [2]. 22



Figure 1: Techno-economic challenges of PEMFC commercialization

The durability issue of PEMFC systems has attracted increasing attention in recent years. Concerning the hydrogen-fuelled PEMFC itself, by its very nature, is prone to irreversible degradation phenomena during its 1 storage and operation mode, leading to accelerated performance loss and 2 shortened lifetime [3]. Neglecting the degradation could result in the misun-3 derstanding of the components' available lifetime and the overconfidence of 4 the system's health condition, which will cause serious consequences. The 5 degradation modes and experimental techniques dedicated to studying the 6 PEMFC stack durability in vehicular applications are reviewed in [4], which 7 helps to understand the root causes of the fuel cell and conduct degradation 8 mitigation control. Degradation-related parameters have been investigated 9 in [5] on various fuel cell components and the reactant starvation, known 10 as an important source of the stack degradation, has been analysed in [6] 11 including its causes, consequences and mitigation measures. As the degra-12 dation remains as one of the weak points of PEMFC technology, efforts 13 have been made to provide guidance to optimize the system control and 14 management strategy and to prolong the stack lifetime. To meet this goal, 15 monitoring the online health state for the fuel cell itself is of significant im-16 portance in assessing its health state and provide useful information. The 17 necessity of developing internal state observers for fuel cell state estimation 18 has been revealed in [7], in which the authors have argued that the ob-19 servation of the internal state is important to the management of the gas, 20 water and heat systems in fuel cell applications. Recently, prognostics and 21 health management (PHM) exists and positions itself as an innovative dis-22 cipline allowing to protect the integrity of the system, predict the downtime 23 and avoid unanticipated operational failure. Jouin et al. [8] have reviewed 24 the PHM activities in PEMFC applications. The PHM procedure contains 25 a set of activities: data acquisition and processing, condition assessment, 26 diagnostic, prognostics, decision support and human-machine interface. It 27 allows us to evaluate the system's reliability in real operating conditions and 28 improve the system's durability by predicting its approaching failures and 29 making corresponding operations. They have also pointed out that prog-30 nostics, as an important process in PHM, has been actively investigated for 31 PEMFC applications, while post-prognostics phases, i.e. decision-making, 32 need more investigation efforts. Moreover, Lin et al. [9] have reviewed fuel 33 cell prognostics methods from different scenarios such as health monitoring, 34 fault diagnosis, prolonging life span, etc. and separates the applied methods 35 into data-driven, model-based and filter-based methods. In order to select 36 different prognostics methods, Sutharssan et al. [10] have reviewed different 37 applications in fuel cell prognostics, e.g. degradation mechanisms, failure 38 models, accelerated tests, etc. Moreover, Liu et al. [11] have reviewed the 30 degradation indexes for PEMFCs that have been applied in different prog-40

nostics methods, in which the authors have pointed out that for the PEMFCs operating under dynamic conditions, traditional indexes can hardly be
applied to predict degradation performance.

However, the existing review papers focus majorly on prognostics meth-4 ods, which are investigated based on finished experimental degradation data, 5 i.e. they use the historical data from the system to perform prognostics and 6 validate the performance with these offline data. Although these methods 7 contribute to predicting the remaining useful life (RUL), post-prognostics 8 decisions are lacking. Developing an integrated PHM cycle to benefit not g only from the results of the prognostics but also health management path-10 ways is demanding [12]. A general framework of PHM has been proposed in 11 [13], in which the health state of the stack corresponds to the modifications 12 of the stack quality, maintenance schedules, operating conditions, as well as 13 the monitoring phase. In this paper, both prognostics and decision-making 14 phases are reviewed and analysed. The question on how to make use of the 15 RUL information to prolong the fuel cell lifetime has been proposed towards 16 the real objective of PHM. This paper reviews the existing fuel cell prog-17 nostics methods from the perspective of PHM by analysing the prognostics 18 scales, horizon, threshold and the use of methods and their performance. 19 It also reports the available PEMFC experimental datasets used for prog-20 nostics studies and their limitations, which are never been investigated in 21 other relevant papers. We also point out that the post-prognostics decision-22 making phase has not been sufficiently studied due to the lack of datasets, 23 24 inconclusive problematics and incomplete methodology. To this regard, four post-prognostics subjects have been analysed and discussed in this paper, 25 including degradation tolerant control, multi-stack control, energy manage-26 ment and maintenance scheduling. Prognostics-enabled decision-making 27 methodologies of these matters are described. According to the findings, 28 remaining challenges and perspectives regarding data, prognostics methods 29 and prospective post-prognostics decision-making actuations are proposed. 30 The paper is organized as follows: Section 2 introduces the problematics 31 of prognostics, in which a rich study on prognostics scales, horizon, threshold 32 and methods are reviewed, and the effects of datasets are analysed. Section 33 3 outlines the potential study areas of post-prognostics decision-making. 34 Finally, Section 4 summarizes the challenges and perspectives before con-35

36 cluding.



Figure 2: Prognostics in a closed loop

2. Problematics of PEMFC prognostics

The prognostics process can be summarized as a process of estimat-2 ing a system's RUL and its uncertainties. The definition of RUL refers to 3 the period between the current instant t_c and the instant where the failure threshold at t_f - end of life (EOL) is reached. The international organization 5 for standardization (ISO) committee has defined prognostics as [14]: 6

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Standard ISO 13381 (2004). The aim of prognostics is the "estimation of time to failure and risk for one or more existing and future failure modes".

Prognostics appears to be a key process which makes the current in-10 dustries think more about "predict to prevent" rather than "fail to fix". 11 The principle of implementing prognostics is shown in Figure 3. The first 12 part of prognostics process is to learn from the operating system and to 13 extract the degradation feature from the available measurements. When 14 the measurement is no longer available, the second part is to forecast the 15 future information without available measurements. The prediction is made 16 based on the training process and the expected result is the RUL and its 17 uncertainty based on the definition of the EOL threshold. 18

This section reviews the existing PEMFC prognostics studies from dif-19 ferent aspects: prognostics scales, prognostics horizon, design of the EOL 20 threshold and prognostics methods. Moreover, the current situation and 21 quality of the available datasets used for fuel cell prognostics purpose are 22 analysed. 23



Figure 3: General principle of prognostics

¹ 2.1. Prognostics scales

2 2.1.1. Component level

A PEMFC stack is an assembly of several cells in series, while a single cell is composed of several components: electrodes, membrane, bipolar plates, gas diffusion layers and sealing gaskets, as shown in Figure 4. The performance degradation of the stack is due to the different level of degradation on these components [13]. Jahnke et al. [15] have reviewed the performance and degradation models on the component scale, while only the ones applied to prognostics studies are considered in this paper.

According to Jouin et al. [13], electrodes and membrane are identified 10 as the most significant degrading components in the cell. The electrodes 11 consist of the catalyst and the carbon supports, while the catalyst usually 12 suffers from Pt dissolution, coarsening and coalescence process. Efforts have 13 been conducted to model the internal degradation mechanisms regarding the 14 electrodes. For example, Zhang et al. [16] have proposed an ageing mod-15 elling method for fuel cell catalyst, which is used for the health monitoring 16 and prognostics of PEMFCs. In this work, the degradation rate of the elec-17 trochemical surface area (ECSA) has been estimated based on the operating 18 conditions. Similarly, a mathematical model has been proposed in [17] to 19 represent the ECSA reduction rate as well as the stack voltage decay, which 20 allows proper estimation of RUL under different operating conditions. Other 21 works have proposed to identify the evolution of the PEMFC degradation 22 by monitoring the membrane thickness [18, 19]. A fused model has been 23



Figure 4: Structure of a single cell in a PEMFC stack

proposed in [20] to predict the degradation of the electrode and membrane 1 based on a series of degradation indexes, i.e. the average radius of Pt particles, ECSA and membrane thickness. 3

The hydrophobicity loss of the gas diffusion layer has also been iden-4 tified as a degradation index of the PEMFC in [21] through hydrophilic 5 pore network modelling. However, it was based on rough approximations 6 and the method has not been verified. Besides, the degradation of bipolar 7 plates and sealing gaskets mainly leads to the increase of the contact resis-8 tance. Although one can estimate the change of the impedance of a PEMFC 9 using electrochemical impedance spectroscopy (EIS), it is difficult to sepa-10 rate the contributors: the change of the impedance could result from inter-11 facial charge-transfer resistance, membrane resistance, contact resistance, 12 mass transport resistant, double-layer capacitance, and Faradaic pseudo-13 capacitance, etc. Therefore, few studies have used the performance loss of 14 them individually as degradation indexes due to the difficulties in capturing 15 their changes [13]. 16

Nevertheless, the current prognostics works on the component level con-17 sider the ageing mechanisms of the PEMFC in a separated way, in which the 18 coupled phenomena is not taken into account. Moreover, Jahnke et al. [15] 19 have pointed out that the use of Butler-Volmer theory cannot be justified 20 to describe the electron transfer reactions in nanomaterials with an evolving 21 structure. Robin et al. have presented an indirect coupling approach in 22 [22], in which the degradation rate is given by a look-up table. It helps to 23 determine the degrading state of the fuel cell, however, when it comes to 24

¹ prognostics, predictions are hard to be made.

² 2.1.2. Stack level

Most prognostics works nowadays are conducted on the stack level [23]. This is due to the fact that no matter what is the cause of the fuel cell performance loss, it can be observed from its stack voltage decay, however, the voltage decay of each cell might not be the same, e.g., the edge cells degrade faster. Besides, as the purpose of prognostics is to predict the RUL, analysing the stack voltage degradation is sufficient to do so unless the specific measurement is required.

To date, most prognostics works on the stack level are developed for the 10 PEMFCs operating under constant load. For example, Jouin et al. [24] 11 have proposed a prognostics method by adapting the particle filtering pro-12 cess and the algorithm is validated by a long-term experimental dataset with 13 constant load. A considerable number of works have been conducted using 14 this dataset by developing different prognostics strategies [25, 26, 27]. Be-15 sides, Morando et al. have used a recurrent neural network to estimate the 16 RULs by separating the voltage degradation signal into the approximation 17 part and the detail part. The tested PEMFC stack is operated under a con-18 stant current profile of 0.6 A/cm^2 [28]. The development of the prognostics 19 strategies applied to constant loads have enriched the choices of fuel cell 20 prognostics methods, however, most of them are not applicable to the fuel 21 cells operated dynamically, especially for those in automotive applications. 22

Prognostics strategies for the PEMFCs operating under dynamic loads 23 have not been fully developed. This is due to the difficulties in catching 24 the varying parameters in dynamic operating conditions and also due to 25 the scarcity of the open-source datasets [29]. Under dynamic loads, the 26 stack voltage is varying according to the load changing so that the challenge 27 should be extracting its degradation trend. Li et al. [30] have developed 28 a prognostics strategy for an ageing PEMFC stack operating in a hybrid 29 system, in which a linear parameter varying model is deployed to reformu-30 late the fuel cell voltage degradation. Using the same dataset, Yue et al. 31 [31] have proposed to decompose the voltage signal through multiplicative 32 decomposition. However, it requires the fuel cell to operate under a cyclic 33 load profile. It is hard to apply these methods for on-board vehicle appli-34 cations if the driving conditions remain unpredictable. Zhang et al. have 35 proposed an empirical PEMFC life prediction model in [32] based on driving 36 conditions. Zuo et al. [33] have proposed to predict the dynamic voltage by 37 defining certain current levels, i.e. extract the voltage values under the same 38 current and then perform prognostics. Moreover, Bressel et al. [34] have 39

introduced a degradation coefficient to the state estimation model. This method supposes that the degradation can be tracked through a single linear state variable. The prognostics strategy is applied to a PEMFC system operated under a μ -CHP profile.

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The current prognostics methods on the PEMFC stack level mostly evaluate the overall performance loss, while lacking the insights of the intrinsic degradation analysis. As the time-varying online operating conditions can deviate the fuel cell degradation phenomena, developing degradation identification and prognostics strategies that can be adapted to random external conditions is required.

2.2. Prognostics horizon

The prognostics horizon is used to evaluate whether a prognostics algo-12 rithm is good to leave enough duration for the future corresponding opera-13 tion based on the prognostics results. As shown in Figure 5, the prognostics 14 performed at time instant t_{λ} is said to well represent the current health state 15 only if the RUL estimation is in the acceptable error zone. As the shortening 16 of the prognostics horizon, the acceptable error zone is shrinking and the 17 acceptable error margin differs according to applications. Moreover, it has 18 been defined as 16% of the original value for early prediction and 8% for 19 late prediction for a horizon of 300 hours [35]. It is important to ensure the 20 accuracy of the RUL prediction in the case of a greater prognostics horizon 21 in order to schedule the maintenance and the corrective actions to an earlier 22 extend and to achieve more effective cost minimization and risk mitigation. 23



Figure 5: Demonstration of prognostics horizon

Zhou et al. [36] have proposed an improved grey prediction model by ²⁴ adding a Fourier function to the error correction term of the grey model to ²⁵

consider the varying prognostics horizon, therefore, to improve the predic-1 tion accuracy even if only limited measurements are available. Xie et al. [37] 2 have found that recurrent neural networks are efficient tools when conduct-3 ing short-term fuel cell degradation prediction and have used a fused method 4 to improve the short-term prediction accuracy. Long short-term memory 5 framework can benefit from the short memory of the prediction steps to 6 update the network so that to make reliable long-term predictions. Several 7 PEMFC prognostics works are conducted based on this method [38, 39, 40]. 8 In the framework of PHM, making decisions and performing maintenance 9 activities strongly depends on the prognostics horizon because different ac-10 tions regarding control and management should be deployed for the system 11 failing in different time horizons [41]. Few studies have investigated the 12 relationship between the fuel cell prognostics performance and the prognos-13 tics horizon, which have put backwards the development of decision-making 14 methods in PEMFC systems. 15

16 2.3. EOL threshold

One of the metrics to quantify the prognostics results is the RUL, while 17 the RUL is calculated according to the definition of EOL threshold [35]. The 18 EOL threshold is usually set as a certain percentage of the original value 19 from the fuel cell's health state. The commonly used EOL threshold of 20 the PEMFC system is defined by the United States Department of Energy, 21 which is losing a percentage of 10% of its nominal power. This criterion 22 23 is given only considering the power loss but not the operational utility of the system. It is used to calculate the RUL of the stack in many research 24 works [42, 43]. For the dataset described in [24], 96% of the initial stack 25 voltage is selected as the EOL considering the length of the dataset in many 26 works [44, 45]. A state-of-health (SOH) estimation method proposed in [46] 27 has used a degradation path γ to indicate SOH, in which a value of 0.15 28 is deduced from the EIS measurements. The prognostics method proposed 29 in [47] have used 34% of the degrading state variable as the EOL thresh-30 old. Using a different dataset, the state estimation method proposed in [48] 31 have used 50% degradation of the state variable as the EOL threshold for 32 the RUL calculation to have a life of about 1550 hours. The uncertainty 33 of EOL threshold can impact the prognostics performance. Studies in [26] 34 have set the EOL thresholds at 10% and 15% of the initial stack voltage, 35 respectively and the prognostics strategies showed different performance on 36 the two different EOL thresholds, while the quantity of the learning data 37 affects the prediction accuracy. In [49], the authors have proposed to cal-38 culate the RUL of the stack based on the reference value of the requested 39

power and keep tracking the maximum available power of the fuel cell to perform degradation tolerant control.

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The definition of EOL threshold affects directly the prognostics results, however, it is difficult to determine as it is an unknown value with prospective nature, and it may change due to the variation of operating conditions. If the power profile is known, e.g., implementing a specific mission, the EOL threshold can be easily determined.

2.4. Prognostics methods

Prognostics methods are categorized into three types: 1) data-driven 9 methods; 2) model-based methods; and 3) hybrid methods [10]. It is also 10 true with respect to the RUL prediction. Previous research has reviewed 11 numerous degradation identification and estimation methods but not all of 12 them can be applied to predict the RUL due to the parameter complexity 13 and measurability [11]. This section does not aim to execute an exhaus-14 tive survey for all the methods but focus on those dedicated to performing 15 prognostics and predicting the RUL. 16

2.4.1. Data-driven method

Data-driven methods are applied to perform prognostics when sufficient 18 data is available to learn the system behaviour using a "black-box" model. 19 Using data-driven methods, the black-box models are created directly from 20 the data, and they are able to project the future states or match similar 21 patterns in the historical datasets. No precise physical model is required. 22 Different from model-based methods, data-driven methods can reflect the 23 inherent relationships by learning the historical and monitoring data and 24 then predict the future trend. Thus, this approach gradually becomes the 25 main methodology for fuel cell prognostics due to the easy-to-use and flexible 26 modelling properties [50]. 27

In the state-of-the-art, traditional neural networks [45, 51], echo-state 28 networks (ESNs) [28, 30, 31], long short term memory networks (LSTMs) 29 [38, 40] and adaptive neuro fuzzy inference system (ANFIS) [25] and other 30 methods have been adapted to predict fuel cell's RULs. Efforts have been 31 made to improve the prediction performance of data-driven prognostics 32 methods and reduce the requirements of the degradation data. For example, 33 two recurrent neural networks have been developed in [33] including LSTM 34 and the one with the gated recurrent unit, which show good prognostics 35 performance with root-mean-square-error (RMSE) values under 0.02 for the 36 PEMFC stack operating under dynamic profile. A constraint-based summa-37 tion wavelet-extreme learning machine has been proposed in [26], in which 38

the authors point out that constraints are necessary for any connectionist
methods to in case of limited measurements.

The accuracy of the data-driven prognostics methods depends on the 3 confidence level of the training data as the behaviour models (black-box models) are established only based on historical measurements [10, 52]. The 5 future states are propagated only due to the models and the measurements 6 since there is no physical meaning. The predicted results of data-driven 7 methods are usually deterministic values so that the confidence level cannot 8 be examined in most cases. Therefore, in prognostics applications, chalg lenges are confronted in obtaining enough data to ensure the prediction ac-10 curacy. Besides, over-fitting issues of the algorithm, as well as the adaptabil-11 ity of changing operating conditions should be addressed. Another challenge 12 is to configure the connectionist network, such as the number of connect-13 ing points and layers, dropout rate and other model parameters. Most of 14 the research has defined the configuration according to the human exper-15 tise and engineering experience [37]. Some researchers have used searching 16 algorithms to select good parameters for the data-driven models, however, 17 it is time-consumption and requires huge computation [39]. Remarkable 18 research works using data-driven prognostics methods are summarized in 19 Table 1, which concludes the method, the load profile, the prognostics scale, 20 the achieved prediction accuracy and the pros and cons. 21

22 2.4.2. Model-based method

Model-based prognostics method is to develop mathematical equations 23 that include many physical parameters to predict the physics governing fail-24 ures. Many researchers have used precise electrochemical models to predict 25 the power sources' health states [61]. An accurate physical model can fa-26 cilitate the RUL prediction because it can reproduce the behaviour of the 27 system and therefore, to calculate the estimated output without any calcula-28 tion burden [62]. Once an appropriate model is found for certain conditions, 29 the prediction results are reliable to the users. 30

A physical model that used for the prognostics purpose must contain 31 time-dependent parameters. For example, a PEMFC model has been pro-32 posed in [62] that can be inserted in the prognostics process. It consists of 33 a static part and a dynamic part. The static part models the activation loss 34 at the electrodes, which can be identified by fitting the polarization curves. 35 The dynamic model is developed according to the changing impedance of an 36 equivalent circuit model, in which the parameters are tuned by fitting the 37 EIS spectrum. Similarly, Pan et al. [44] have used an analytical equivalent 38 circuit model to assess the fuel cell health, in which the parameters are tuned 39

	Publication	Year	Method	Load profile	Prognostics	Prediction accuracy	Pros and Cons
					scale		
	Silva et al. [25]	2014	ANFIS	Constant load	Stack level	$R^{2} > 0.95$	Pros: model-free
	Javed et al. $[26]$	2015	SW-ELM	Constant load	Stack level	$R^2 = 0.91$ for one stack	without complex
						and $R^2 = 0.91$ for the	physical
						other stack	parameters; easy to
	Yin et al. $[53]$	2016	LWPR	Constant load	Stack level	Not applied	implement; high
	Morando et al. [28]	2017	ESN	Constant load	Stack level	MAPE=0.97%	generality.
	Liu et al. $[47]$	2017	GMDH network	Constant load	Stack level	RMSE = 0.09 for one	Cons: need a
						stack and $RMSE = 0.06$	great amount of
						for the other stack	data to ensure the
	Zhu et al. $[54]$	2018	Gaussian pro-	Constant load	Stack level	Within $\pm 10\%$ error zone	accuracy; need
			Cess			of the actual RUL	human expertise to
Data-driven	Zhou et al. [45]	2018	Neural network	Constant load	Stack level	RUL estimation error <	configure the
method						30%	algorithms; the
	Ma et al. [38]	2018	\mathbf{LSTM}	Constant load	Stack level	RMSE = 0.0040 and	prediction results
	-					MAPE = 0.0013	are deterministic;
	Mezzi et al. [55]	2018	ESN	Constant load	Stack level	Average RUL error $= 30$	sometimes
						hours	encounter
	Li et al. $[30]$	2018	ESN	Automotive	Stack level	Within the confidence in-	over-fitting issues;
				dynamic cycle		terval of 95%	time and
	Chen et al. $[51]$	2019	Neural network	Constant/dynar	niStack level	MAPE < 1.04%	computation
				load			consuming.
	Hua et al. $[56]$	2020	ESN	Constant load	Stack level	RMSE = 0.0110	
	Vichard et al. [42]	2020	ESN	Automotive	Stack level	Normalized $RMSE$ =	
				dynamic cycle		0.098	
	Yue et al. $[31]$	2020	ESN	Automotive	Stack level	Average $RMSE = 0.07$	
				dynamic cycle			
	Wang et al. [40]	2020	Stacked LSTM	Constant load	Stack level	Normalized weighted-	
						sum error $= 0.9633$	
	Pan et al. $[57]$	2020	Stacked LSTM	Constant load	Stack level	RMSE < 0.01	
	Meraghni et al. [58]	2020	Stacked LSTM	Constant load	Stack level	Relative accuracy > 0.9	
	Xie et al. $[37]$	2020	PF-LSTM	Constant load	Stack level	$R^{2} > 0.91$	
	Xie et al. $[59]$	2020	DBN-ELM	Constant load	Stack level	$R^{2} > 0.91$	
	Chen et al. $[60]$	2020	Wavelet neural	Dynamic load	Stack level	MAPE = 5.18%	
	-		network	\$			
	Ma et al. [39]	2020	Stacked LSTM	Constant load	Stack level	Relative accuracy $= 0.95$	
	Zuo et al. [33]	2021	LSTM and GRU	Automotive dvnamic cvcle	Stack level	RMSE < 0.0040	

based on EIS measurements by linear regression. A similar approach has 1 been found in [63]. Besides, EIS measurements are also applied to fuel cell 2 component degradation analysis because different operating conditions and 3 degradation degrees will lead to the derivation of the arc shapes, as shown 4 in Figure 7. By extracting features from the EIS measurements, predictions could be performed [64]. For example, an identification method to find the 6 low-frequency resistance, i.e. the rightmost intersection with the real axis 7 of the EIS arcs, has been proposed in [65], which can estimate the fuel cell 8 degradation with only small disruptions. Pivac et al. [66] have used the g same parameter on the EIS arcs as the indicator of stack degradation and 10 built an equivalent circuit model to represent the degradation of the catalyst 11 laver. 12

However, PEMFC systems are dynamic, time-varying and nonlinear elec-13 trochemical systems, and the internal reactions and failure modes are very 14 complicated, which change under different operating conditions. Therefore, 15 it is not easy (even impossible) to find precise physical models or mathemat-16 ical models to describe detailed fuel cell degradation mechanisms and failure 17 modes. Even if the physical model is available, it is hard to represent it in the 18 analytic form and the model built for one application cannot be transferred 19 to another application. Moreover, although efforts have been made to find 20 accurate and dynamic degradation models, the difficulties in measurements 21 have limited the development of model-based prognostics methods. For ex-22 ample, a degradation model has been proposed in [67] to simulate the pinhole 23 24 formation process on the membrane during the chemical degradation. The required measurement is conducted on the microscale. Other degradation 25 modelling works may even be performed on the nanoscale [68]. It is techni-26 cally and economically infeasible to install micro-sensors (nano-sensors) on 27 the stack in order to catch its degradation without specific needs. These 28 models are not favourable for industrial employment. Typical model-based 29 PEMFC prognostics methods are summarized in Table 2. 30

31 2.4.3. Hybrid method

Rather than finding the exact relationship using multiple physical pa-32 rameters, research has been conducted to use hybrid methods to perform 33 prognostics on the PEMFC. The hybrid methods combine the two previous 34 types of prognostics methods, which develop models to describe the degra-35 dation process mathematically, while the model parameters changing over 36 time are estimated by learning algorithms. This kind of method avoids the 37 complicated process to study the internal degradation mechanisms regard-38 ing different fuel cell components and uses a substitute way to construct 39

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	Publication	Year	Method	Load profile	Prognostics scale	Prediction accuracy	Pros and Cons
	Zhang et al. [16]	2014	Pt catalyst degradation model	Constant load	Component level	Within the confidence in- terval of 95%	Pros: good accuracy once the model is adanted
	Lechartier et al. [62]	2015	Semi- mechanism	Constant load	Stack level	RMSE = 0.5103	to a certain system; less training data;
Model-based method	Polverino et al. [17]	2016	uegradation model ECSA degrada- tion model	Constant load	Component level	Not applied	tess computation burden. Cons: nearly imnossible to find
	Kim et al. $[63]$	2016	EIS feature ex- traction	Constant load	Stack level	Average weighted-sum er- ror =5.32e-6	precise degradation model due to
	Hu et al. [43]	2018	Semi- mechanism degradation	Automotive dynamic cycle	Stack level	Predicted voltage devia- tion of 1%	complex parameters to be defined; models
	Pivac et al. [66]	2018	EIS feature ex- traction	Accelerated stress test	Component level	Not applied	system can hardly be transferred to
	Pei et al. [69] Pan et al. [44]	$2019 \\ 2020$	Empirical model EIS feature ex-	Constant load Constant load	Stack level Stack level	Not applied Average weighted-sum er-	another system with different
			Uraction			For $=3.9409e^{-0}$ for one stack and $=8.2021e^{-6}$ for the other stack	operating conditions; some measurements
	Halvorsen et al. [65]	2020	EIS feature ex- traction	Accelerated stress test	Component level	Not applied	needed in the model are not
	Ao et al. [70]	2020	ECSA degrada- tion model	Automotive dynamic cycle	Component/sta level	ckRelative error $= 8.18\%$	economically or technically feasible.
	Ou et al. [71]	2021	Semi-empirical model with	Automotive dynamic cycle	Stack level	Within the confidence in- terval of 95%	
			recovery identi- fication	5 5			

Table 2: Summary of model-based PEMFC prognostics studies

behaviour models. Yuan et al. [7] have reviewed the model-based observers 1 that are used for fuel cell prognostics. To this end, the PEMFC is repre-2 sented by an equivalent circuit model and the prognostics is executed by 3 solving state space models through filtering algorithms: extend Kalman fil-4 ter (EKF) [48], unscented Kalman filter (UKF) [51, 72], particle filter (PF) [73, 23, 46, 74], etc. The prognostics is implemented by propagating the cur-6 rent estimated health state and its uncertainty to the future. The learning 7 process could be model-based, data-driven or a combination of both, be-8 cause both physical models and data can be integrated into the state vector g model [75]. 10

Hybrid prognostics methods are favourable for the good prediction per-11 formance and as they need only a few parameters to build the models, the 12 modelling process is simplified compared to model-based methods. Owing 13 to the learning process, the hybrid methods also share the advantage of good 14 generality from data-driven methods. Besides, the uncertainties are easy to 15 be represented when applying filtering-based hybrid prognostics methods so 16 that the prediction results tend to be more reliable by defining the confidence 17 level. Efforts have been made to improve the filtering-based hybrid prognos-18 tics methods, for example, in [76], instead of using the uniform distribution 19 for the parameter initialization of the PF, the initialization procedure has 20 been improved by the historical EOL data, which considers more parameter 21 uncertainties. 22

Hybrid methods are widely used in fuel cell prognostics and are of high 23 flexibility in applications, however, the implementation cost may get heav-24 ier. Although building physical models is not a primary condition for hybrid 25 methods, it still needs the expertise knowledge on the system degradation. 26 If the degradation process is complex, it will add to the calculation burden 27 of the training procedure. Therefore, it is very important to find a compro-28 mise between the model complexity and the training expense when applying 29 hybrid prognostics methods. Table 3 summarized the representative works 30 using hybrid prognostics for PEMFC applications. 31

32 2.5. Long-term experimental datasets

As discussed above, prognostics methods are developed to adapt the characteristics of the datasets, in other words, the datasets can affect the performance of prognostics methods. Currently, only a few available longterm experimental datasets dedicated to the PEMFC prognostics research are available. This section has reviewed these datasets and has pointed out the limitations by analysing the data quality.

	5T		T DITCATE TO A TERMINE	enneongoid O'TMET	eanna		
	Publication	Year	Method	Load profile	Prognostics scale	Prediction accuracy	Pros and Cons
	Zhang et al. [72]	2012	UKF	Constant load	Stack level	Within the confidence in-	$\mathbf{Pros:}$ high
	Jouin et al. [23]	2014	$\rm PF$	Constant load	Stack level	terval of 95% Relative accuracy > 0.9	accuracy; use more applicable model
	Kimotho et al. [73]	2015	PF	Constant load	Stack level	IEEE 2014 PHM Chal-	(grey model) with
						lenge score of 0.77	fewer physical
	Jouin et al. [24]	2015	$\rm PF$	Constant load	Stack level	MAPE = 0.33% - 5.06%	parameters; good
	Jouin et al. [77]	2015	$\rm PF$	Combined heat	Stack level	$R^{2} = 0.8$	generality.
Hybrid				and power pro-			Cons: need both
method							knowledge on the
	Ibrahim et al. [78]	2016	Wavelet trans- form	Constant load	Stack level	Kelative KUL error < 9 21 %	degradation mochanism and
				-		0/TO7	
	Bressel et al. [48]	2016	EKF'	Constant load	Stack level	Within $\pm 10\%$ error zone	training data;
						of the actual RUL	highly dependent
	Jha et al. $[74]$	2016	$\rm PF$	Constant load	Stack level	Relative accuracy $= 0.96$	to the initial
	Liu et al. $[29]$	2017	UKF	Constant load	Stack level	Within $\pm 10\%$ error zone	settings of model
						of the actual RUL	parameters.
	Mao et al. $[79]$	2017	$\rm PF$	Constant load	Stack level	Prediction error of 2.71e-	
						4 for constant load and	
						0.04 for dynamic load	
	Yang et al. [80]	2017	PF	Constant load	Stack level	RMSE < 0.01	
	Zhou et al. [81]	2017	NARNN model	Constant load	Stack level	RMSE = 0.069	
	Cheng et al. $[27]$	2018	$\rm PF$	Constant load	Stack level	Length of confidence in-	
						terval < 20 hours	
	Chen et al. [82]	2019	UKF	Automotive	Stack level	Average relative error $=$	
				dynamic cycle		2.03%	
	Zhang et al. [46]	2019	PF	Constant load	Stack level		

Table 3: Summary of hybrid PEMFC prognostics studies

¹ 2.5.1. Current situation

A survey on the available datasets used for performing prognostics is conducted. It is summarized in Figure 6. Most of the datasets are under privacy policy and not available but for project members, which has limited the production of research works.



Figure 6: Statistics of datasets oriented for prognostics

The mostly used PEMFC degradation dataset for prognostics is an open-6 source dataset that was released during the event of the IEEE PHM 2014 7 Data Challenge launched by the IEEE Reliability Society, FCLAB research 8 9 federation, FEMTO-ST Institute, and the Laboratory of excellence AC-TION [83]. It was collected from the ageing experiments carried out by the 10 FCLAB Research Federation (FR CNRS 3539, France, http://eng.fclab.fr/) 11 on its test facilities. The assembled fuel cell are 5-cell stacks. Each cell has 12 an active area of 100 cm^2 . Two long-term ageing experiments were launched 13 with different operating conditions: constant and variable. The first stack 14 was operated under its nominal current density (0.70 A/cm^2), while the 15 second stack was tested with a ripple current (0.70 A/cm^2 with oscilla-16 tions of 0.07 A/cm^2 at a frequency of 5 kHz). To identify the degradation, 17 fuel cell characterizations were performed each week, i.e. every 160 hours 18 approximately, i.e. at time t = 0; 48; 185; 348; 515; 658; 823; 991h, which in-19 cludes polarization curves and EIS measurement. The polarization curves 20 are measured under a current ramp from $0 A/cm^2$ to $1 A/cm^2$ of 1000 sec-21 onds. The air and H_2 flows are reduced until the current value reaches 20 A 22 and are then kept constant. The EIS measurements are realized under differ-23 ent constant current: $0.70 \ A/cm^2$, $0.45 \ A/cm^2$, $0.20 \ A/cm^2$. A period of 15 24 minutes is used to stabilize the stack. The results are showed in the Nyquist 25

plots over a frequency range from 50 mHz to 10 kHz. Figure 7a and Figure 1 7b show examples of the characterization measurements, in which the shape 2 changes of the polarization curves and the EIS arcs are caused by the stack 3 degradation. By measuring the parameters from the measurements, models could be derived to study the stack ageing mechanism and conduct prognostics. To visualize directly the stack voltage degradation, historic voltage 6 curves are plotted. Figure 7c shows the stack voltage drop signal over time in constant operating conditions, while Figure 7d shows the stack voltage 8 drop signal in variable operating conditions with a ripple current.



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(a) Polarization curves of the 5-cell stack obtained overtime (b) EIS plots of the 5-cell stack before polarization at 0.70 A/cm^2 with current ramp from $0 A/cm^2$ to $1 A/cm^2$ of 1000s



(c) 5-cell stack voltage evolution under constant operating (d) 5-cell stack voltage evolution under dynamic operating condition condition

Figure 7: Fuel cell characterizations and voltage evolution

Similar experiments have been conducted within the framework of the 10 project PHM PAC [28] and the project PROPICE [48]. A micro combined 11 heat and power (μ -CHP) dataset was reported in the framework of project 12 SAPPHIRE [84], which come from a pilot project collaborated with the 13 Electricity of France (EDF). The applied μ -CHP load profile simulates the 14 behaviour of a stationary PEMFC application during a complete year. Rel-15 evant prognostics works are developed based on PF [77] and EKF [34], re-16

spectively. To demonstrate the on-board degrading performance of the fuel 1 cell stack, two experiments are conducted in [30] and [42] in the framework 2 of project PRODIG and project Asdecoeur, in which the stacks are deployed 3 to dynamic load profiles and the prognostics strategies are developed based 4 on data-driven methods. A similar dataset is released in [33] where a single PEMFC is conducted to the New European Driving Cycle (ECE R15) to test its durability. A 1000-hour data profile is produced. Ou et al. [71] have 7 conducted stack durability tests for two PEMFCs with 15 cells and 30 cells, 8 respectively, using a locomotive profile and generated 505-hour degradation g data. Vichard et al. [85] have launched a long-term ageing experiment of 10 an open-cathode PEMFC under an accelerated postal delivery driving cycle, 11 which showed the considerable influence of the ambient temperature on the 12 stack degradation. Moreover, there is another on-road fuel cell degradation 13 dataset from the MobyPost project, where the fuel cell system acts as a 14 range extender. It has operated 10 fuel cell hybrid electric vehicles for the 15 real-world commercial postal delivery, which integrated lithium-ion batteries 16 in the vehicle powertrain in order to deal with the transient power demand. 17 and therefore, to avoid frequent startups and shutdowns of the fuel cell. This 18 dataset has recorded the operating conditions including the load current and 19 voltage, hydrogen pressure, temperature, relative humidity, state of charge 20 of the battery and the hydrogen tank. A prognostics method based on neu-21 ral networks has been developed using this data in [51]. Another similar 22 dataset obtained from a fuel cell city bus in China is described in [43]. 23

24 Other datasets conducted for fuel cell prognostics are obtained from accelerated stress tests, which are designed to target the electrocatalyst 25 degradation. They are mostly used to estimate and predict the fuel cell 26 degradation on the component level [65]. This kind of test is usually per-27 formed on a membrane-electrode assembly (MEA) in a single cell, which is 28 operated under a potential cycling profile. The DoE's recommended cycling 29 profile for electrocatalyst degradation is between 0.7V and 0.9V, while a 30 degradation diagnostic study in [66] has accelerated the degradation process 31 by cycling between 0.6V and 0.9V. Those tests focus on tracking the evo-32 lution of the MEA's internal parameters, which are conducted to develop 33 degradation models but not to predict the RUL. 34

35 2.5.2. Quality of data

For the datasets as the one shown in Figure 7c, the degradation is not monotonous due to the monitoring characterizations. The most common characterization methods for PEMFCs in the laboratory are polarization curves and EIS measurement. When the operation is stopped for charac-

terization, recoveries on the stack voltage could be observed, which indicate 1 the reversible phenomena during the PEMFC ageing process. In practice, 2 these reversible phenomena may be due to the changing operating conditions 3 that affect the gas and water diffusion within the cells, i.e. starvation and flooding [13]. However, compared to the long-term irreversible performance decay of the fuel cell, these reversible phenomena can be recovered when the 6 stack is brought back to its normal operation, i.e. quasi-static regime. 7

Efforts have been made to improve the prognostics performance with 8 the existence of reversible degradation. Morando et al. [28] have proposed 9 to divide the observed signal into static part and transient part and per-10 form prognostics separately. To deal with the recoveries in the stack volt-11 age, Kimotho et al. [73] have introduced a self-healing coefficient into the 12 degradation model and used particle filtering to adapt the model with the 13 observed data after each characterization. Jouin et al. [24] have proposed 14 a combined degradation model including both irreversible and reversible 15 degradation and used an ensemble of particle filters to estimate the model 16 parameters and predict the RUL. Moreover, Zhang et al. [86] have used an 17 equivalent circuit model to describe the polarization resistance and brought 18 an idea of multi-level prognostics. 19

2.6. Partial synthesis

Recent years have seen rapid development in PEMFC prognostics in terms of prognostics methods and degradation modelling and estimation. More publications come out in recent five years, as shown in Figure 8. This survey is conducted by searching terms "PEM fuel cell" or "PEMFC", "prognostics" and/or "degradation prediction" in the title, abstract and keywords of all peer-reviewed articles in the major academic research databases.

Although more studies start to focus on solving PEMFC durability prob-27 lems, some key issues have not been fully addressed. Based on the Table 1 -28 Table 3 and the previous analysis, the current prognostics works are mostly 29 based on limited finished experimental datasets, operating conditions are 30 rarely considered. Only a few works have developed prognostics methods 31 for the PEMFCs operating under dynamic load. Although there is no pref-32 erence in selecting the prognostics methods as each method has its pros and 33 cons, we should consider the user requirement, data availability and degra-34 dation conditions. Besides, there is not a uniform performance evaluation 35 criterion which is lacking for the moment and should be important in the 36 prognostics-based decision-making process. 37

Prognostics and RUL are not the goals of PHM as how to use RUL 38 to implement control and management and how to improve the PEMFC 30

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Figure 8: Yearly evolution of publications from 2010 to date containing terms "PEM fuel cell" or "PEMFC", "prognostics" and/or "degradation prediction". The search was made on the 20th February 2021.

durability are where the research orients. Post-prognostics and decisionmaking technologies are underdeveloped for the moment. They are discussed
in the next section.

4 3. Post-prognostics: decision-making

As the ultimate objective of PHM is not to predict the RUL, but to take actions to prolong the lifetime of PEMFC systems. It exists in three levels: control, management and maintenance. In this section, four aspects of the post-prognostics decision-making phase are discussed. They are degradation tolerant control, multi-stack control, energy management and maintenance scheduling.

11 3.1. Degradation tolerant control

The majority of PEMFC control studies have focused on enabling power 12 tracking capability on the system level, e.g., to control the oxygen flow rate 13 in the cathode to protect it against reactant starvation. However, degra-14 dation tolerant control subject to address its durability issue is of scarcity. 15 Deng et al. [87] have proposed a linear parameter varying (LPV) state space 16 model which is oriented to design a fast linear controller for the PEMFC sys-17 tem. A model predictive control (MPC) strategy is proposed in [88] for the 18 PEMFC system using a similar LPV model, on one hand, to track the power 19 demand, and on the other hand, to ensure the maximum working efficiency 20 and maximizing the stack durability. To enable MPC strategy on different 21

scales, Jouin et al. [89] have proposed a combined prognostics method based 1 on PF that can achieve accurate predictions on both short-term and long-2 term. Polverino et al. [90] have proposed a physical model-based control 3 algorithm aiming at mitigating the stack degradation on ECSA. Similarly, 4 a non-linear model predictive control strategy has been proposed in [91] to maximize the active catalytic surface area at the cathode catalyst layer and 6 to avoid starvation at the catalyst sites. Moreover, Bressel et al. [49] have 7 proposed a multi-physical LPV model for the PEMFC in the electrochemical 8 macroscopic representation formalism. The degradation-related parameters 9 are considered in the model to realize the ageing tolerant control. It allows 10 regulating the required PEMFC power in presence of the performance decay. 11 Cheng et al. have proposed in [92] that the degradation can be mitigated 12 by managing the PEMFC air supply system. The control is realized based 13 on the exhaust gas recirculation function included in the air supply system 14 model, which can reduce the oxygen ration in the inlet air, and therefore, to 15 mitigate the fuel cell output voltage degradation. Besides, the degradation 16 tolerant control can also be conducted on a hybrid system. Kong et al. [93] 17 have developed an interconnection and damping assignment-passivity based 18 control strategy for a fuel cell/supercapacitor hybrid system, in which the 19 degradation information is given by filtering state estimation. With the ex-20 istence of fuel cell degradation, this method ensures the normal operation 21 of the system, while avoiding overload. 22

Degradation tolerant control is very important to guarantee the integrity 23 and the continuous operation of the fuel cell system without faults and shut-24 downs. The RUL information provided by prognostics algorithms should be 25 combined with the control strategies as it should be taken into consideration 26 not only the current degradation state but also the RUL corresponding to 27 the system's EOL. Research on this issue still needs to be resolved and more 28 efforts are needed. 29

3.2. Multi-stack control

The durability of a multi-stack fuel cell system depends not on the RUL 31 of any single stack but the co-working mechanism of the stacks, which may 32 contribute differently to the demanded power. Therefore, to maximize the 33 lifetime of a fuel cell system composed of multiple stacks needs a control 34 strategy to alter the operations between stacks. It could be regarded as an 35 assignment optimization problem and optimization algorithms are deployed 36 in the literature to find optimal solutions. Chretien et al. [94] have applied 37 two convex optimization algorithms, i.e. the Mirror-prox for Saddle Points 38 method and the Least Absolute Shrinkage and Selection Operator principle. 30

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The optimization problem is solved by formulating a mathematical expres-1 sion which minimizes the output power error and at the same time, adding 2 the RUL of each stack as the constraint. A multi-stack control algorithm 3 based on mixed-integer programming has been proposed in [95]. The control 4 is realized owing to the successive optimal resolutions based on a fuel cell stack behaviour model considering the wear and tear process. Moreover, an 6 optimal power allocation method considering the degree of PEMFC degra-7 dation in each stack has been proposed in [96], in which the degradation is 8 considered by a virtual resistance model. The developed strategy can assure g the normal operation of the multi-stack system even if one of the stacks fails. 10 To date, the multi-stack control strategies are developed for constant 11 load demand case, while for variable load demand profile, the problem be-12 comes complicated as not all the stacks should be used in low demand period. 13 This needs the addition of a start-and-stop operation scheme. Besides, the 14 well-developed prognostics strategies described in Section 2 have not been 15 used for the multi-stack control. The existing methods are based on degra-16 dation models rather than online degradation prediction results. 17

18 3.3. Energy management

When using multiple power sources at the same time to supply a cer-19 tain load, an energy management strategy (EMS) is developed to govern 20 the energy distribution in the hybrid system. The performance of a hybrid 21 system can be highly affected by the design of EMSs [64]. Based on non-22 23 exhausted bibliography research, for fuel cell hybrid systems, various EMSs have been developed to take power sources' degradation into consideration 24 and therefore, to prolong the lifetime of the fuel cell or the overall system 25 [97]. To be health-conscious, most researchers tend to develop degradation 26 models for the PEMFCs to quantify performance degradation and to get 27 the optimal solutions by designing rule-based and optimization-based EMSs 28 [98]. The degradation models are integrated into the objective functions to 29 minimize the overall cost or the hydrogen consumption. For example, fuel 30 cell degradation origins such as low humidification and frequent and rapid 31 voltage changes are considered in the EMS in [99] to mitigate the fuel cell 32 degradation by setting key parameters. A robust fuzzy MPC method is 33 proposed in [100] to coordinate the fuel cell degradation and energy storage 34 system scheduling by formulating rule-based strategies. A deterministic dy-35 namic programming strategy and a rule-based strategy have been developed 36 in [101] to minimize the cost and at the same time, respect the operation 37 limits to avoid degradation. A linear time-varying MPC strategy is proposed 38 in [88] for the PEMFC system, which is, on one hand, to track the power 39

demand, and on the other hand, to ensure the maximum working efficiency and maximizing the stack durability. Moreover, an equivalent consumption minimization strategy has been developed in [102], which considers the fuel cell degradation in the objective function.

However, existing researches usually consider fuel cell degradation by 5 setting constraints or using fitting degradation models in the strategies, 6 which are less accurate and cannot assess the real degradation state of the 7 system. The developed prognostics technologies such as those discussed in 8 Section 3 are rarely applied to the energy management of HEV applications. 9 To complete the PHM cycle for a hybrid fuel cell system, the decision-making 10 process turns out to be a part of the EMS. As the degradation of the fuel cell 11 leads to its reducing efficiency and therefore, high fuel consumption. Two 12 control strategies have been proposed in [103]. The maximum power strategy 13 requires larger fuel systems, while the fuel cell operated with maximum 14 efficiency strategy consumes less hydrogen. However, the optimal point is 15 shifted regarding a degraded fuel cell, i.e. the actual power provided by the 16 fuel cell is lower than the required value based on the following equations: 17

$$P_{actual} = P_{required} \cdot (1 - D_{fc}) \tag{1}$$

$$D_{fc} = \frac{V_{actual}}{V_{rated}} \tag{2}$$

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where D_{fc} is the degradation degree of the fuel cell. It can be represented as a ratio of the actual voltage to the rated voltage. Therefore, to obtain the corrected power value required in an energy management problem, the degradation degree of the fuel cell should be determined and the corrected value is written as:

$$P_{corrected} = \frac{P_{actual}}{1 - D_{fc}} \tag{3}$$

As the degradation degree can be predicted by prognostics, the remain-23 ing work should be developing a decision-making process that can make use 24 of the prognostics information and generate appropriate commands on the 25 system. Yue et al. [104] have proposed a health-conscious EMS by devel-26 oping a prognostics-enabled decision-making process, which integrates the 27 prognostics results into the design of the fuzzy logic controller. The results of 28 prognostics are used to determine the degradation level of the power sources 29 and the EMS is designed based on fuzzy logic control whose parameters 30 are refined based on the degradation level using a decision fusion algorithm. 31 A MPC-based energy management strategy has been proposed in [105], in
 which the durability of the fuel cell has been considered by the output power
 slope of constraints.

4 3.4. Maintenance scheduling

In most industrial applications, to ensure the continuous and reliable 5 operation of the system, the preventive maintenance is performed regularly, 6 whether it is needed or not [106]. It is designed periodically based on the 7 usage conditions of the equipment and the severity of the component degra-8 dation. However, to some extent, it causes over care which is a waste of time 9 and money, especially when it needs to send technical personnel to remote 10 operation area. Therefore, if the degradation status of the system can be 11 predicted, maintenance can then be scheduled whenever it is needed, i.e. 12 to be upgraded to the predictive maintenance, which is more dynamic. It 13 automatically assesses the current health state of the system and predicts 14 future failure. In this way, the maintenance interventions can be scheduled 15 beforehand, and if the degradation can be regulated by the control mod-16 ule, the operation of the system can be improved, and the lifetime can be 17 prolonged. 18

Predictive maintenance is attracting the favourable attention in the re-19 cent years in different applications, e.g. pump systems, aircraft and space-20 craft, batteries, micro-electro-mechanical systems, etc., however, few predic-21 tive maintenance methods for PEMFC systems have been investigated yet 22 23 [107, 108, 109]. Predictive maintenance methods proposed for other applications may inspire the development of predictive maintenance for PEMFC 24 systems. For example, in the literature, Meng et al. [110] have reviewed the 25 maintenance methods for lithium-ion batteries and have proposed that an 26 optimal management/schedule strategy is necessary for reducing the down-27 time and minimizing operation cost for the battery system. Linear program-28 ming models have been used in [111] to include battery degradation process 29 in the optimization and have achieved fewer battery replacements to reduce 30 the maintenance cost. Moreover, Nguyen et al. [41] have proposed a new 31 dynamic predictive maintenance framework based on an LSTM classifier. 32 Based on the intelligent classification results, they have constructed an opti-33 mal decision model to determine whether to replace the engine and the time 34 to order spare parts. A tree-based classification method has been proposed 35 in [112] to implement predictive maintenance for the railway switches and 36 the marginal benefit of usage has been proposed in [113] as the metric for 37 the lithium-ion battery system operation and maximizing the total life-cycle 38 benefit. Moreover, the Internet of Things (IoT) technique has been deployed 39

in many industrial applications for the predictive maintenance owing to its smartness and advanced automatic process [58]. Those approaches have been applied to the industrial machinery monitoring, which are not necessarily applicable for PEMFC systems [114].

3.5. Partial synthesis

Even though research on PEMFC prognostics has seen significant progress, 6 it is still not sufficient to be integrated into PHM as the post-prognostics 7 decision-making phase has not been sufficiently investigated. Four aspects 8 have been proposed in this section, i.e. degradation tolerant control, multi-9 stack control, energy management and maintenance scheduling, in which 10 the degradation prediction of PEMFCs plays an important role. The first 11 three aspects have seen recent advances in developing control and optimiza-12 tion strategies, however, prognostics should play a more important role in 13 their further development. Predictive maintenance of PEMFC systems is 14 actually undeveloped and requires more efforts in research. Methods like 15 combinatorial optimization techniques, IoT, digital twin, case-based rea-16 soning, knowledge-based modelling, etc., that have been applied to other 17 applications could be migrated to the field of PHM on PEMFCs and inspire 18 the development of predictive maintenance method for the fuel cell systems. 19

4. Challenges and perspectives

As stated above, the PHM process adopted in PEMFC applications is not completed due to its insufficient development in prognostics methods, 22 as well as the decision-making methods. This is also due to the limitations 23 in data, which influence the performance of prognostics methods, however, 24 have not been fully studied yet. The remaining challenges and perspectives 25 are revealed in this section. 26

4.1. Challenges and perspectives on data

4.1.1. Data volume and observability

To perform prognostics or implement post-prognostics decisions, suffi-29 cient data samples are necessary for the learning algorithms and modelling 30 process, as well as in the validation stage. Data collected for this purpose 31 is rarely found and the research is held behind by the limited data samples 32 [115]. To overcome the insufficient data volume, methods have been investi-33 gated in an attempt to increase the data volume by duplicate or randomly 34 generating data, i.e. grey forecasting, feature extraction, and virtual sam-35 ple generation [106, 116]. Limited data also results in increasing uncertainty 36

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[117]. Methods should be investigated to manage and reduce the uncertainty
in the prognostics. On the other hand, the quality of data and the amount of
information in the monitoring data may also influence the implementation
of the prognostics. Different inspection policies considering the variation of
degradation states must be investigated [118].

On the other hand, some developed prognostics models are based on 6 specific physical parameters of the PEMFC system, while some of which are 7 not easily accessed or measured without characteristic sensors, e.g., micro-8 sensors and nano-sensors. Although the technique of advanced sensors is g on the way of developing, it increases the capital cost of the system and 10 slows down the process of commercializing the application of PHM in en-11 gineering domains [110]. The possible measurements in a PEMFC system 12 are summarized in Table 4, which are categorized according to their tech-13 nical and economical feasibility. Developing reliable prognostics approaches 14 with technically and economically observable data is one of the challenges 15 faced by the researchers and the goal is to use a minimum number of actual 16 sensors to monitor the degradation state change. 17

18 4.1.2. Data availability

Compared with other prognostics applications, such as batteries, power 19 electronics, pump bearings, engine and turbine degradation, available datasets 20 for PEMFC prognostics is very limited. This is due to the high requirements 21 in the experimental capability of performing long-term fuel cell degradation 22 tests and the high cost on the equipment. Moreover, few laboratories have 23 published their experimental data for research, while most of them are pri-24 vate or not ready for publication. Open data service is very important to 25 accelerate the development of PHM engineering on PEMFCs. In addition 26 to *in-situ* experiments, pilot projects that can gather and distribute online 27 operation data in the real world. They must be supported by the admin-28 istration of the company and the government to simplify the data sharing 29 30 procedure.

31 4.2. Challenges and perspectives on prognostics

32 4.2.1. Prognostics time scale

The degradation of PEMFCs, to its very nature, is a long-term phenomenon. In the light of the monitoring cost and the information level, the inspection intervals greater than one hour are usually considered in PEMFC prognostics [35]. However, the time scales of the related control, management, maintenance scheduling problems that are concerned in the postprognostics decision-making phase may change. For example, the scheduled

Feasibility	Measurements
	-System and stack voltage
	-Single-cell voltages
	-System and stack current
Faacible	-System and stack temperatures
reasible	-Cooling water temperature
	-H ₂ and air temperatures (inlet/ outlet)
	-H ₂ and air pressures (inlet/ outlet)
	-Air compressor speed
Possible but not technically	-Stack impedance
or aconomically feasible	-Stack internal resistance
of economically leasible	-Stack internal temperatures
	-Local current density
	-Membrane thickness
	-Active catalyst area
Technically or economically	-H ₂ and air flows (inlet/ outlet)
unfoogible	-Cooling circuit mass flow
umeasible	$-H_2$ and air hygrometry rate
	-Water content in PEM
	-Inlet gases composition
	-Outlet effluents composition

Table 4: Feasibility of measurements in PEMFC systems

maintenance based on prognostics cannot be implemented immediately if ¹ the fuel cell system is under operation. The maintenance schedule should ² also be adapted to the order time. Oppositely, the control and management ³ strategies acting directly on the fuel cell system can modify the control signal immediately or in a short period. An illustration of decision policies ⁵ regarding spatial and time scales is shown in Figure 9. ⁶

To fulfil different post-prognostics decision-making missions, multi-dimensional and multi-scale models designed for PEMFC prognostics should be de-8 veloped. Moreover, another problem in the validation stage of the post-9 prognostics decision-making process is how to continuously supervise the sys-10 tem and conduct immediate controls to avoid and to mitigate the degrada-11 tion that appears as a long-term phenomenon. To solve this problem, multi-12 criteria optimization, operational research techniques, combinatorial opti-13 mization (heuristics and meta-heuristics), case-based reasoning and knowledge-14 based reasoning are the promising methods that are worth studying. Be-15



Figure 9: Spatial and time scales of post-prognostics decision-making process

sides, to implement control together with the scheduling and assignment
problems is another underlying problem and should be considered to contribute to an integrated decision layer of PHM.

4 4.2.2. Prognostics performance metrics

Another barrier holding behind the development of prognostics methods 5 is the lack of uniform performance evaluation metrics. Current prognos-6 tics research tends to evaluate the prognostics results by comparing the real 7 experimental data and calculating the accuracy and precision of the pre-8 dictions. However, the performance of the prognostics methods regarding 9 other properties of the results has rarely been investigated. Without specific 10 performance evaluation metrics, it brings difficulties for the researchers to 11 evaluate and distinguish one prognostics method from others and it is hard 12 to define the progress on method improvement. To standardize prognostics 13 performance metrics, three more aspects should be specified: the prognostics 14 horizon, the confidence level to the results and the EOL threshold. 15

The prognostics horizon is very important to evaluate the prognostics performance as it is related to how much information is available from the beginning to the current state. Some studies have evaluated the prediction accuracy with respect to prognostics horizon, however, no clear relationship has been derived between them [23]. As the goal of PHM is to continuously monitor the health state of the system and conduct appropriate actions regarding the system's health state, it is important to develop reliable prognostics methods by taking the prognostics horizon into consideration.

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Another scenario to evaluate the prognostics results is the confidence level. In some data-driven methods, deterministic values are used as the predicted RUL results, which are, to some extent, not reasonable. The prediction comes with uncertainty, therefore, it is necessary to evaluate the uncertainty when making predictions. The probability of the predicted RUL falling into the confidence interval is important to define the goodness of the prognostics results and to evaluate whether the prediction is early or late since late predictions may cause more serious problems than early predictions.

The last concern about performance evaluation is the EOL threshold. 12 Decision-makers use the predicted RUL to make decisions that are inte-13 grated into the lifecycle of the systems, in which the RUL is determined by 14 the definition of the system failure threshold. Current prognostics works 15 have assigned static thresholds to represent the failure of the PEMFC stack, 16 typically, a certain percentage of the initial voltage/power value. This value 17 is usually reported to be determined based on the data length, i.e., prior 18 knowledge of the dataset, which is unsupervised and contributes to the un-19 certainty of the predicted RUL [119]. But what if the prior knowledge does 20 not exist? A possible solution could be to set the thresholds dynamically 21 according to the operating conditions, the current degradation tendency 22 parameters and the available maintenance choices [120]. As proposed in 23 [121], integrating a classification method with online predictions is capable 24 to adapt the threshold values considering the real-time operation state of 25 the system. This kind of research can be migrated to the PEMFC appli-26 cations, with which researchers can take measures to make the following 27 post-prognostics decisions based on dynamic thresholds. 28

4.2.3. Method adaptability

Efforts have been made to improve the performance of prognostics with 30 the existing prognostics methods, as discussed in Section 3. However, if the 31 prognostics methods are to be used for the post-prognostics control strate-32 gies, several limitations of the methods appear. For example, internal stack 33 parameters cannot be accessed experimentally, therefore, these parameters 34 will be missing in the model-based approaches; while to be valid, data-driven 35 approaches must be fed with a wide range of data, covering all the opera-36 tion, degradation and ageing modes, which is very costly and sometimes not 37 affordable for some applications. Besides, the prognostics methods proposed 38 based on the characterization measurements are not applicable for real-time 39

applications due to the inconvenience of disrupted operations. Therefore,
to complete the PHM cycle of PEMFC applications, a probable way is to
combine all approaches into a larger model, comprising a supervision level,
where the processing consigns are sent to the appropriate model, and parameter exchange can flow in both directions depending on the limitation of
each one.

7 4.3. Challenges and perspectives on post-prognostics decision-making

8 4.3.1. Uncertainty treatment

First and foremost, the insufficient development of post-prognostics decision-9 making phase is due to the difficulties in managing the uncertainties. In fact, 10 the prognostics refers not only to the prediction of the RUL but also to its 11 uncertainty. The uncertainties existing along with the prognostics procedure 12 have a significant influence on the prognostics-based decision-making phase 13 The entire process of PHM indicates that prognostics is a closed-[122].14 loop procedure so that the uncertainties in each phase of this procedure 15 are accumulated along with the operation. These uncertainties may contain 16 uncertainty in the data, uncertainty in the prognostics algorithm and un-17 certainty in the post-prognostics decision-making process. An overview of 18 sources of uncertainties is summarised in Table 5. Some of the uncertain-19 ties can be avoided, while others cannot. For example, uncertainty in the 20 data can be eliminated to some extent as long as dedicated datasets can 21 be used for the prognostics purpose with adequate measurements, sampling 22 23 frequency, volume and normal operation. Uncertainties during the prognostics and decision-making process can hardly be avoided as they are due to 24 the nature of the adopted methods. For these uncertainties, one should be 25 able to quantify and manage them. 26

To deal with the uncertainty and to interpret it to facilitate the prognostics-27 based health management, efforts on its quantification and representation 28 are required. When applying statistics technique to quantify the uncer-29 tainty, it is important to consider the variance of the predicted RUL [123]. 30 Existing prognostics research using state-space models has considered the 31 uncertainty of the variables when propagating them to the future, and is able 32 to predict the future state uncertainty using probability distribution, how-33 ever, the state-space models are supposed to be linear ones, which cannot 34 represent the real-world nonlinear applications, e.g., fuel cell degradation, 35 so that they bring uncertainty to the system by themselves. Monte Carlo 36 sampling-based method should be one of the solutions to this problem by 37 using infinite samples [117]. Future research needs to continue the study also 38 on the applicability of the uncertainty management technique to PEMFC 39

prognostics applications. Moreover, robust decision models for the decisionmaking process are required to deal with all the uncertainty generated in models, predictions, operating conditions, etc., described in Table 5.

Uncertainty in data Uncertainty in prognostics Uncertainty in decisionmaking -Data observability -Model uncertainties -RUL uncertainties -Sampling frequency -Input uncertainties -Control and management -Data volume -Measurement uncertainties strategy uncertainties -External uncertainties -User uncertainties -Test interruptions

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Table 5: Sources of uncertainties in data, prognostics and decision-making process

4.3.2. Experimental validation

Present research on PEMFC prognostics is mostly based on finished ex-5 perimental datasets and the performance is verified and validated by the 6 pre-defined experimental results, i.e. precision, convergence, accuracy, etc. 7 However, this is not the goal of PHM. The goal of PHM is to use the RUL 8 predictions to perform continuous supervision and control actions on the 9 system and therefore, to mitigate the degradation and enhance the durabil-10 ity. The validation of the post-prognostics decision-making phase in PHM 11 is a quality assurance process [124], while it is lacking in most research due 12 to the difficulties in executing such an experimental platform for thousands 13 of hours and designing comparison experiments. Also, the high cost on the 14 equipment and hydrogen has limited the implementation of such long-term 15 experiments. Although some decision-related research has been conducted 16 in the literature, none of them has been validated with online prognostics re-17 sults. Moreover, appropriate protocols of testing the durability of PEMFCs 18 should be designed [125]. The ageing process of the PEMFC differs from 19 different operating conditions and the relationship between test protocols 20 and the degradation performance should be studied. 21

For the present, hardware-in-the-loop (HITP) and power HITP may 22 be the most favourable methods to validate the prognostics-based control 23 strategies as it can simulate the complex real-time embedded systems by 24 adding necessary mathematical representations. The prognostics and con-25 trol algorithms can be implemented based on the value of the electrically 26 emulated sensors in the system and changes in the control signals will act 27 back on the system. It increases the flexibility of the test as it can test the 28 system with different failure conditions, which is very important in the ver-29 ification of prognostics algorithms. Besides, it can provide an efficient and 30 safe environment for the researchers to test the controllers and increase the
scope of the testing. The benefits are exceptional as the test is implemented
with the closed-loop control.

4 5. Conclusion

As PEMFC systems are highly multiphysical and multiscale systems, the 5 behaviour of the stack is hard to catch due to the high difficulty to access the 6 internal parameters. Developing PHM methods is of prime importance for 7 the successful system design, control, diagnostics and optimization. This pa-8 per has reviewed the PHM research developed for PEMFC systems in terms g of the current status and perspectives of prognostics and decision-making 10 methods. Current prognostics methods have seen their progressive devel-11 opment in recent years, however, there are certain problems that have not 12 been clearly defined, e.g. prognostics horizon, failure threshold, evaluation 13 metrics, etc., which have been discussed in this paper and is expected be 14 standardized as the post-prognostic actuation is envisaged. The available ex-15 perimental datasets used for PEMFC prognostics studies have been reported 16 and the fact that most of the current prognostics studies were based on the 17 same open-source dataset and the limitations of the dataset have barriered 18 the development of the prognostics methods. Furthermore, methodologies 19 of developing post-prognostics decision-making issues have been described. 20 According to the findings, remaining challenges and perspectives regard-21 22 ing data, prognostics methods and prospective post-prognostics decisionmaking actuations have been proposed. A prerequisite for further progress 23 is to enhance the availability and the observability of the data used for the 24 prognostics purpose. Then, the development of prognostics methods should 25 rely on the improving performance metrics and adequate uncertainty treat-26 ment. Finally, importance should be paid to developing post-prognostics 27

control and management strategies by solving the difficulties in incorporat ing the prognostics information and experimental validation.

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