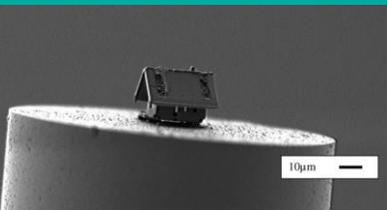




in-situ SEM Robotic-based Selection, Manipulation and Characterization of 3D Microscale Particles

R. Hannouch, G. Colas, J-Y. Rauch, V. Reynaud, J. Agnus, O. Lehmann, F. Marionnet and C. Clévy

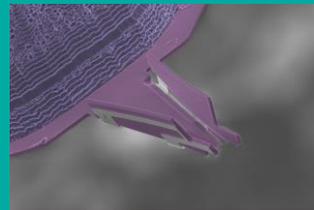
Cédric Clévy, Professor, FEMTO-ST, Franche-Comté University



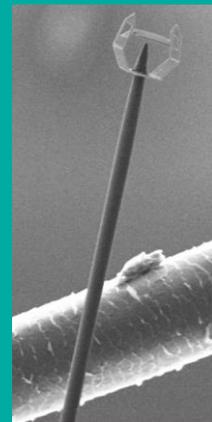
[J. Vac. Sc. 2018]



[Opt. Cont. 2022]



[Adv. Mat.. 2021]



[RA-L. 2021]

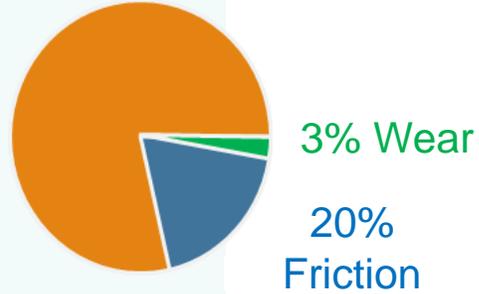
Part of the **DyNaBot** project, funded by the ANR.



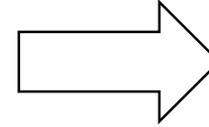
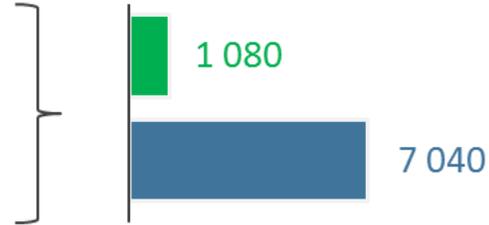
Context & motivations of the works

Total energy consumption worldwide

Holmberg K, Erdemir A.
Friction 5 (2017) 263-284



CO₂ emissions
(MtCO₂)



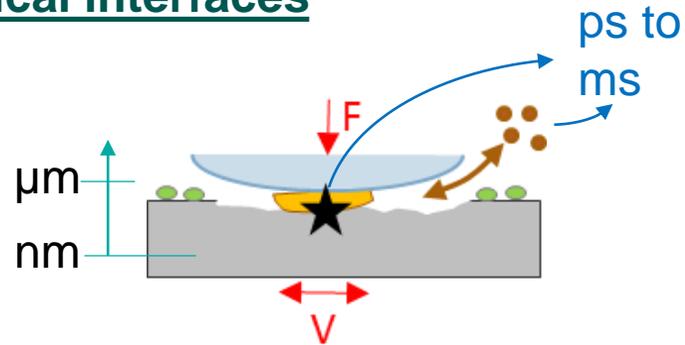
Energy saving and greenhouse gas reduction ?

Contact issues and tribological interfaces

2 bodies in contact
+
an interphase is created during friction

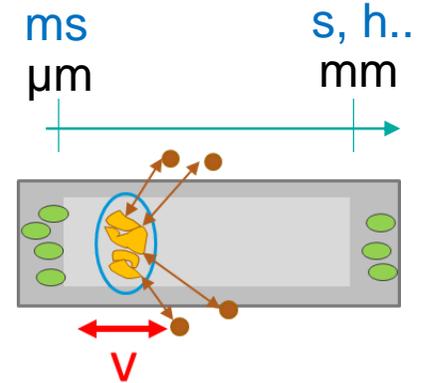
Mechanical and physicochemical properties influenced by

- interactions with the environment
- particle detachment and wear



Spatial scale

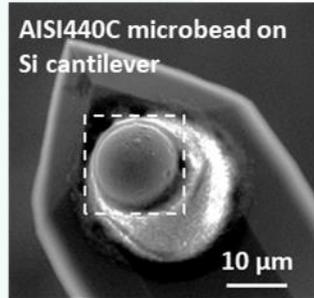
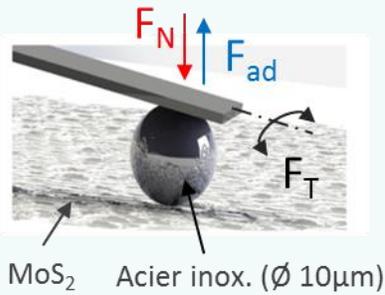
Time scale



Context & motivations of the works

=> Surfaces coated with MoS₂

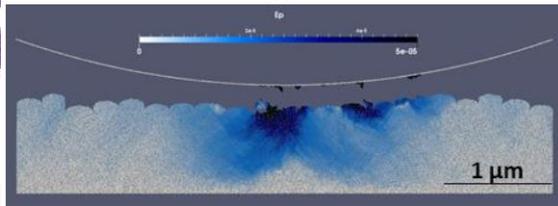
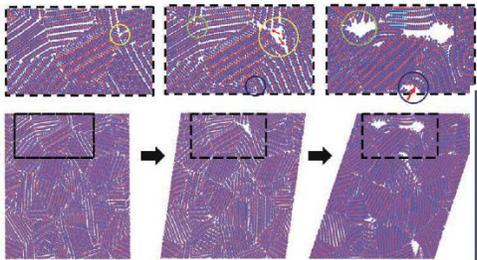
➤ Nano-tribology



[S. Pajovic, Adv Eng Mat (2017), P. Serles Adv Mat Inter (2020), T. Arif Adv Mat Inter (2019) & Trib Int (2021)]

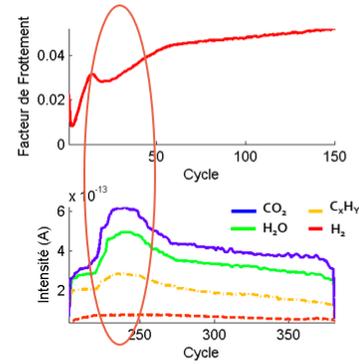
➤ Molecular dynamics

➤ & DEM

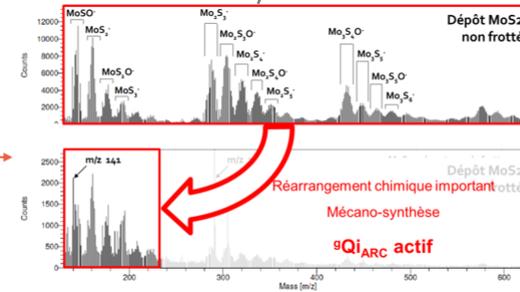
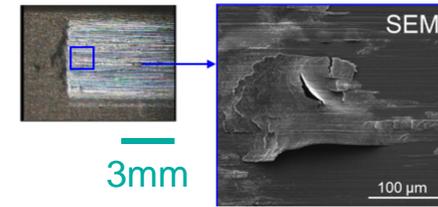


[Colas, ESMATS (2017), P. Serles Adv Func Mat (2022)]

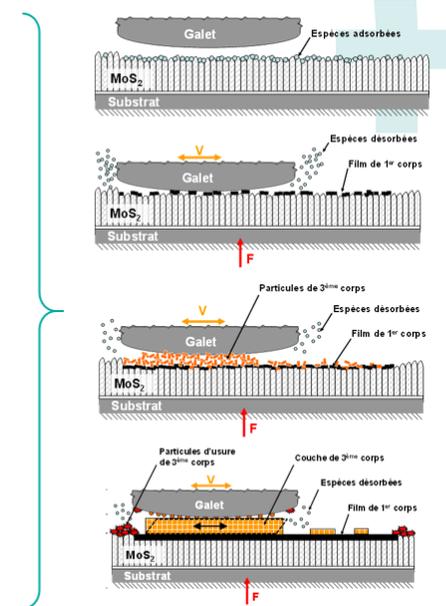
➤ Macro-tribology



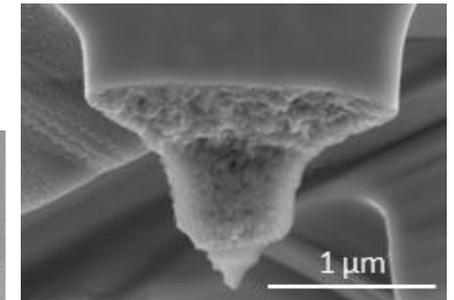
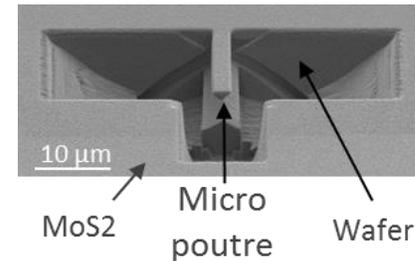
ToF-SIMS
Top surface chemistry



[G. Colas, et al Trib Int (2013), Wear (2013) & (2015), ACS Appl Mat Interf (2018)]



➤ Indentation ; AFM based bending test



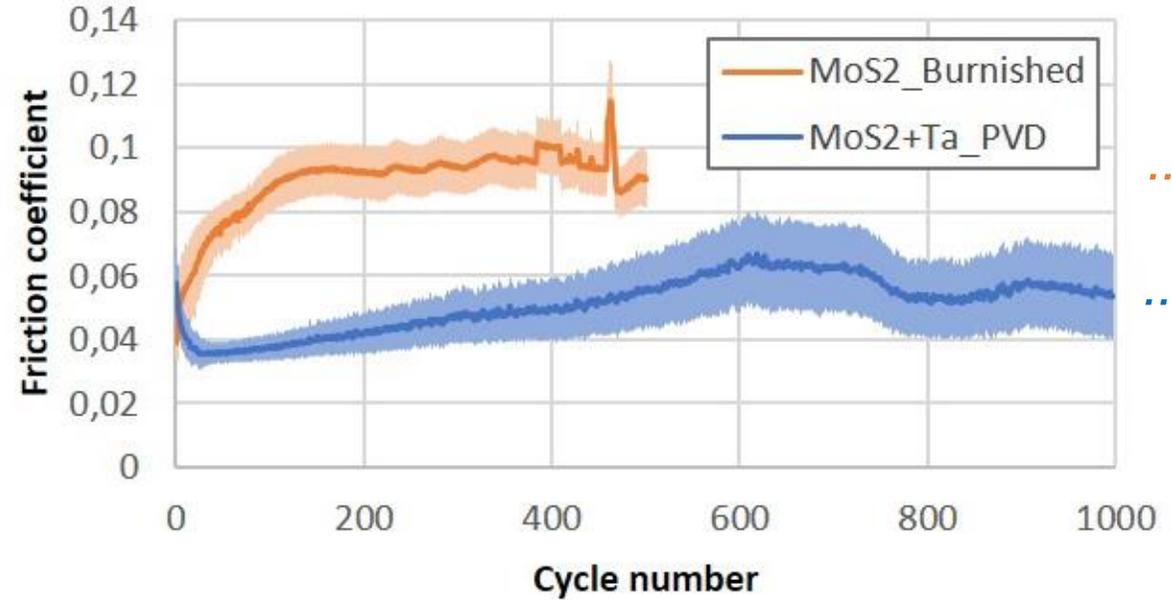
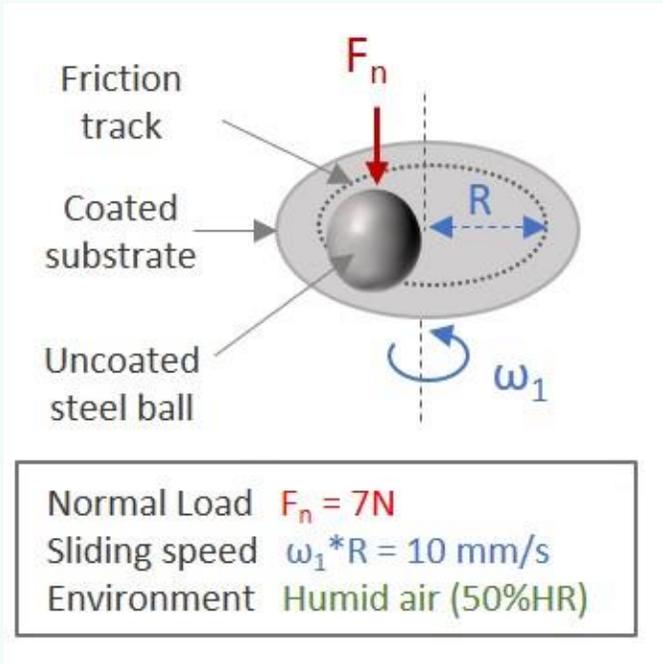
[G. Colas, et al Jour Phys Solids (2019)]

➤ Mechanical properties of 3rd bodies & particles : missing

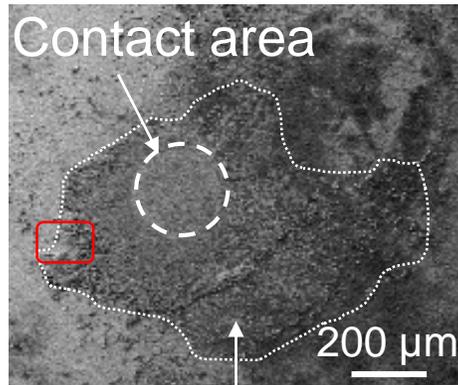
Context & motivations of the works

=> Surfaces coated with MoS2

Macroscale Friction tests

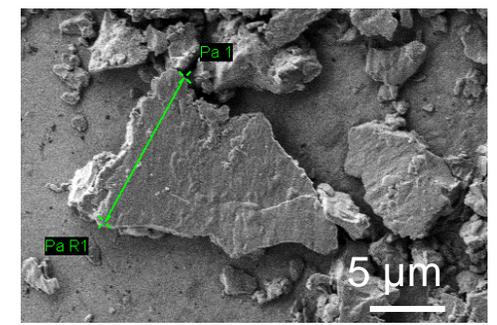
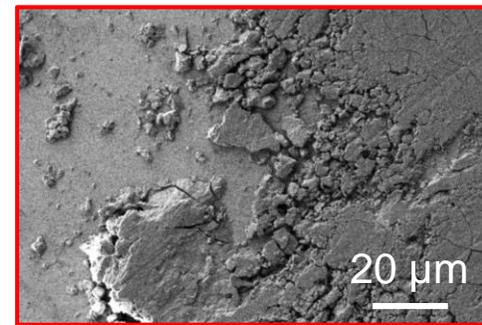


Particle...
..stiff & brittle
..soft & ductile

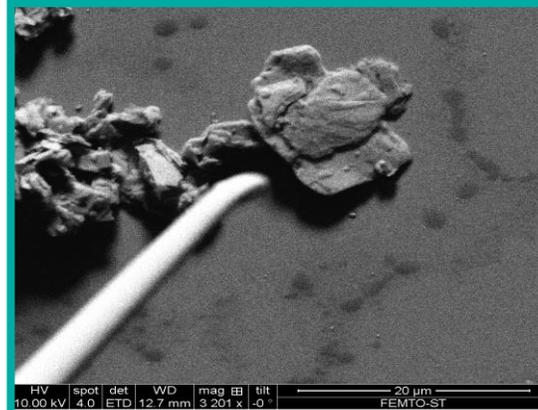


Ejected particles

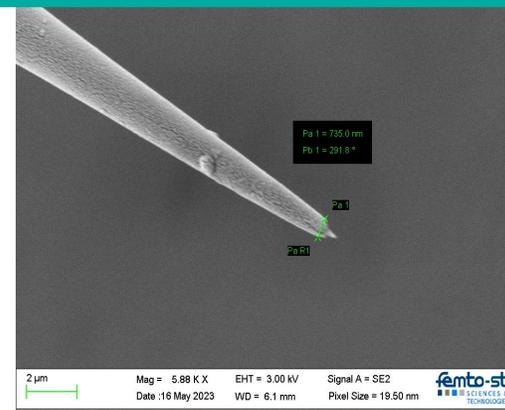
SEM analysis / particle selection on the ball



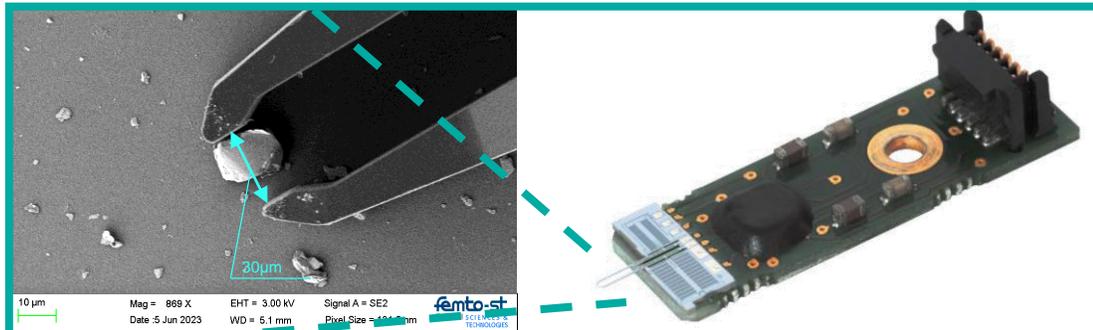
MAIN TOOLS AND TIPS



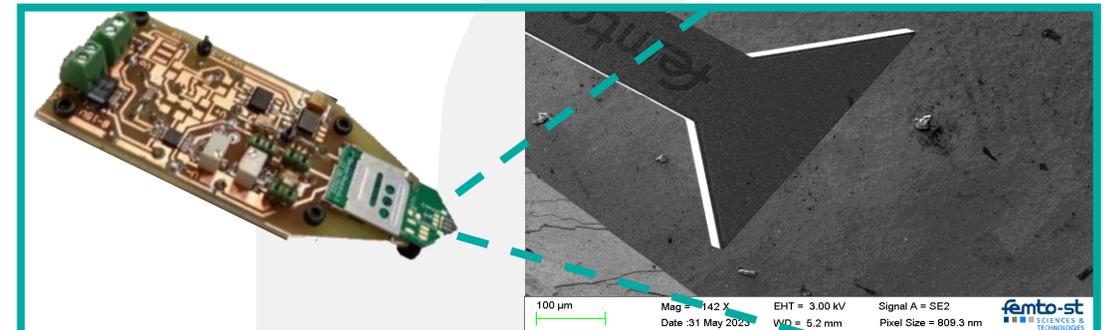
Metal-based probe
Diameter of 3μm



Metalized glass-based
fiber probe
Diameter of 0.7μm

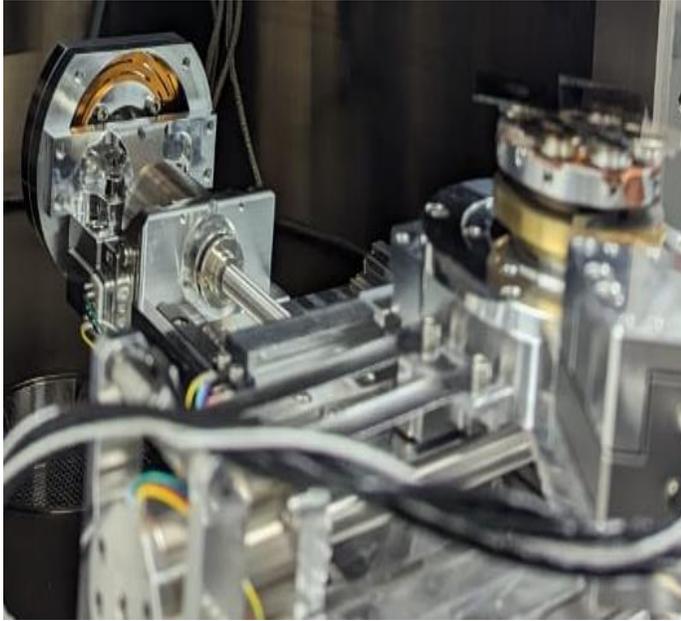


Femto-Tool Ft-G32 micro-gripper
(actuation and sensing)
Thickness of 50μm

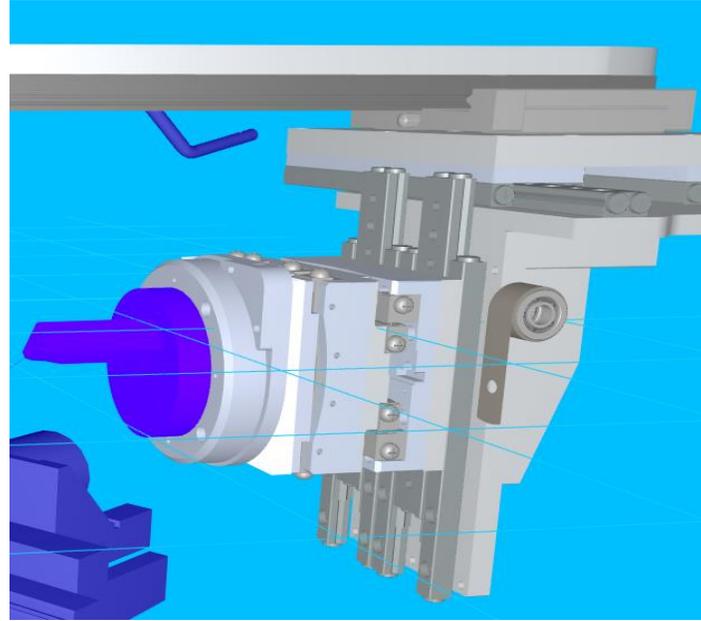


SENSITIPS micro-sensor
(resolution <1μN)
Thickness of 40μm

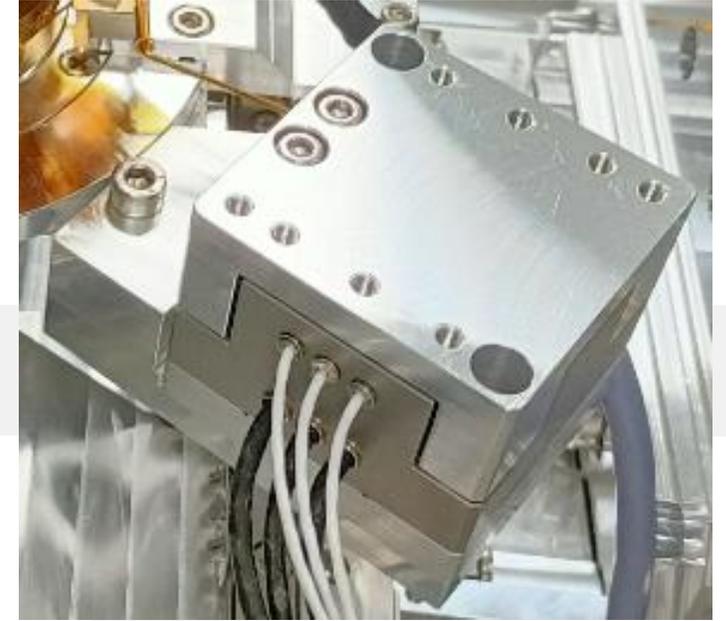
MAIN ROBOTIC SYSTEM USED IN THE SEM



5 DOF sample holder stage
3P2R (Precision of $1\mu\text{m}$, 0.1 m°)
Grain platform holding
(ZEISS)



6 DOF SEM Robot
3P3R (Precision 10nm , $1\text{ }\mu^\circ$)
Long ranged manipulation
(SmarAct)



3 DOF Nanopositioner
3P (Precision 2 nm)
Fine manipulation
(Piezosystem jena)

Objective and Strategies

Achieve a first quantification and manipulation of intricate 3D structured micro scaled particles in-situ (SEM), directly from the friction track vicinity

Particles resulting from friction of MoS₂ grains based coatings.

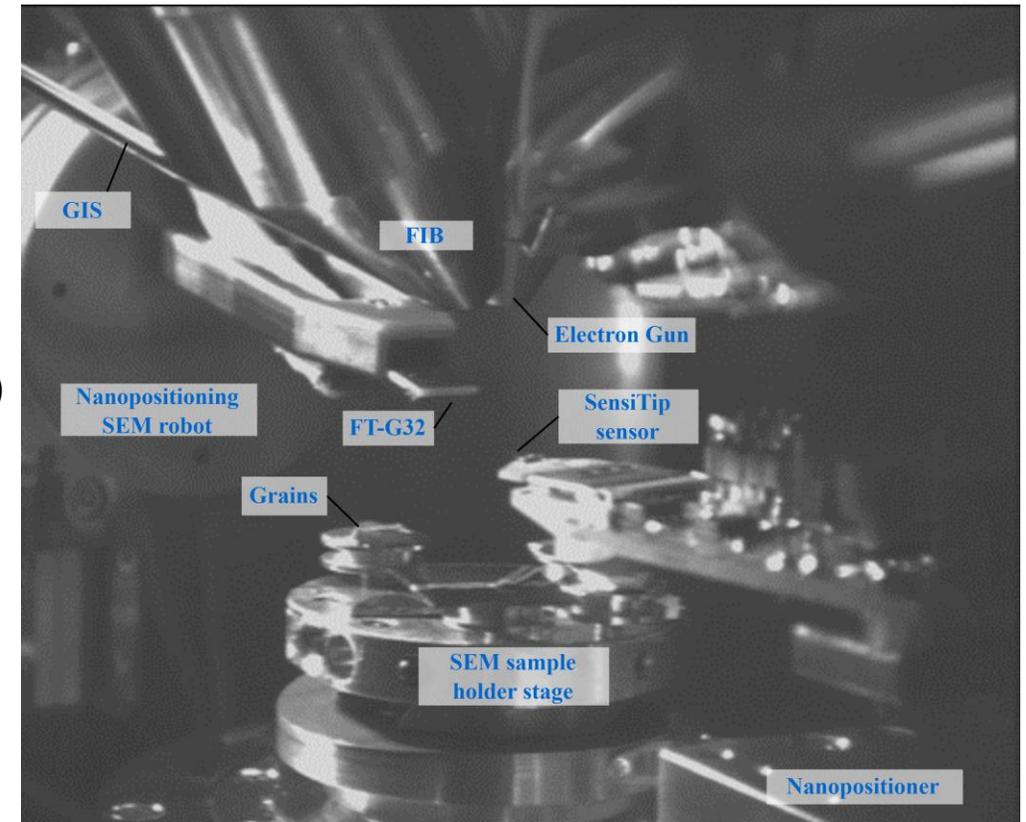
- 10 μm < lateral size < 25 μm
- 3 μm < thickness < 10 μm

Challenges:

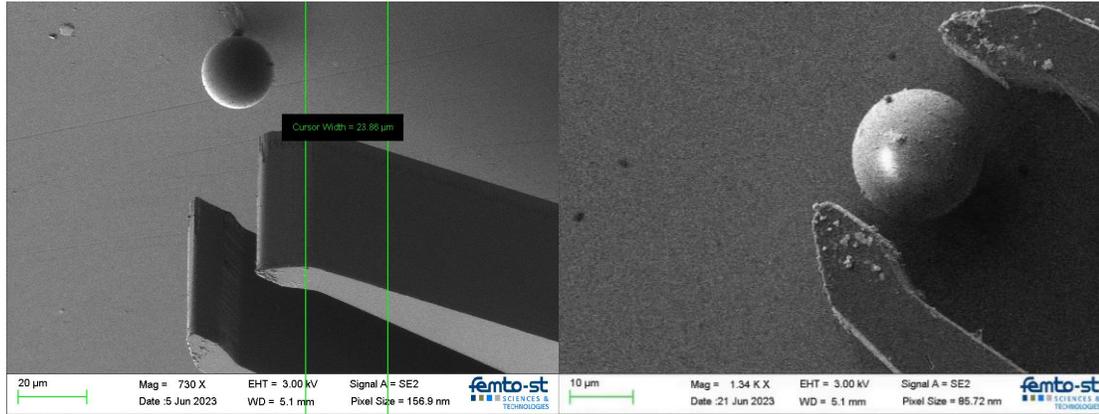
- Sequence of tasks (particle selection, isolation, grasping, testing)
- Grains are 3D with complex internal structure
- Force & displacements to be measured but what range?

Approach:

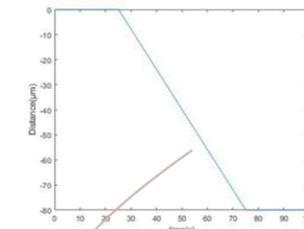
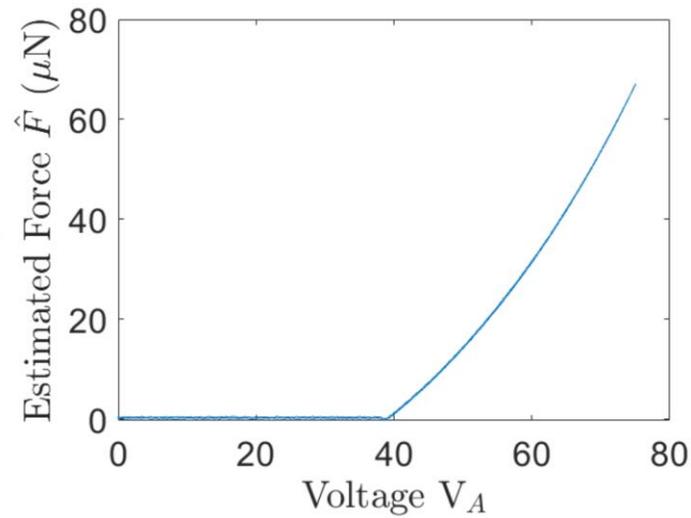
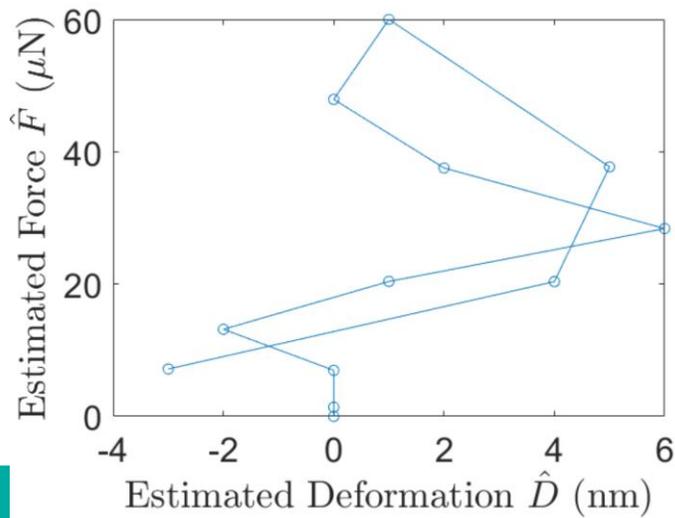
- Set of tools and methods that can be combined into a single sequence inside of a SEM
- Comparison of raw materials MoS₂ and MoS₂/Ta



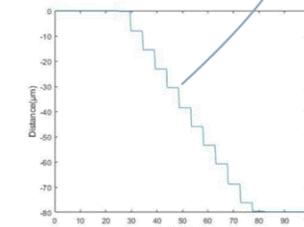
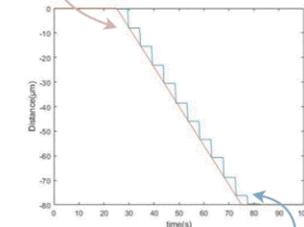
ALGORITHM TO EVALUATE FOR THE COMPONENT DEFORMATION



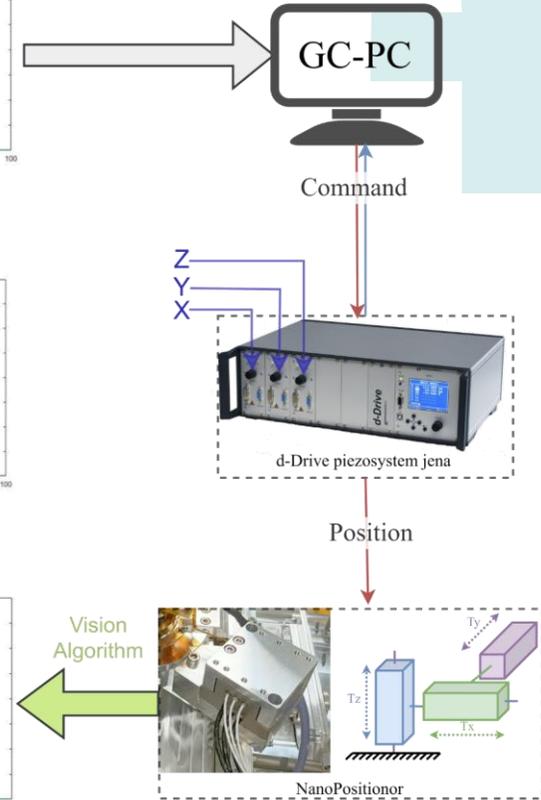
Rigid Si beads application



Input displacement in X direction

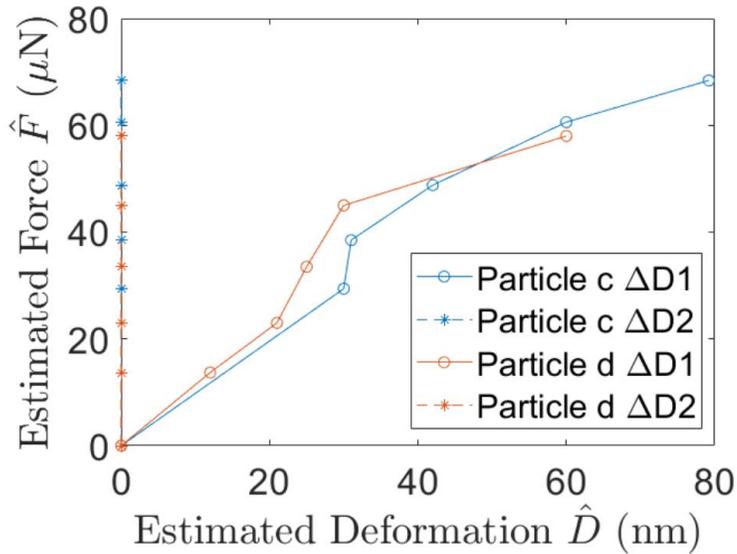
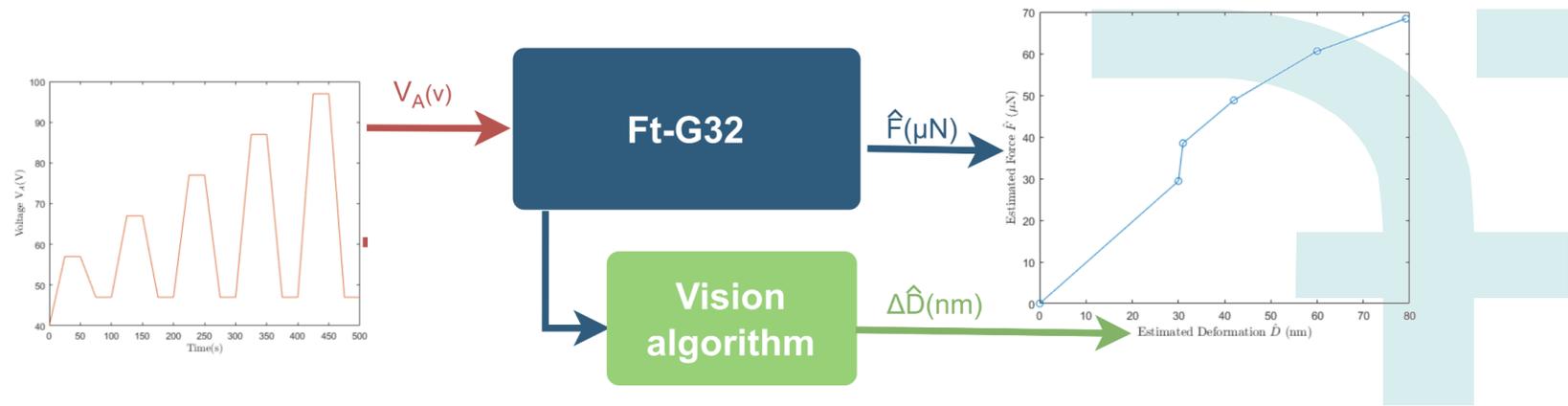


output estimated displacement in X direction

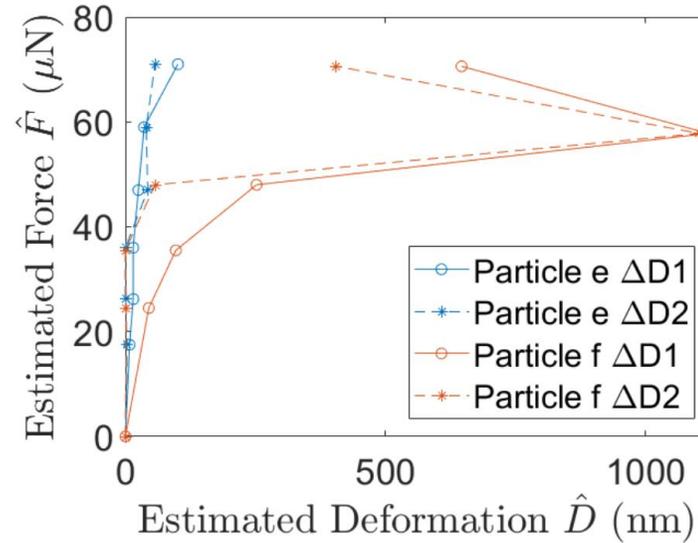


Vision algorithm and nano stage test

COMPARING THE DIFFERENT MATERIALS



3^{ed} Body pure MoS₂

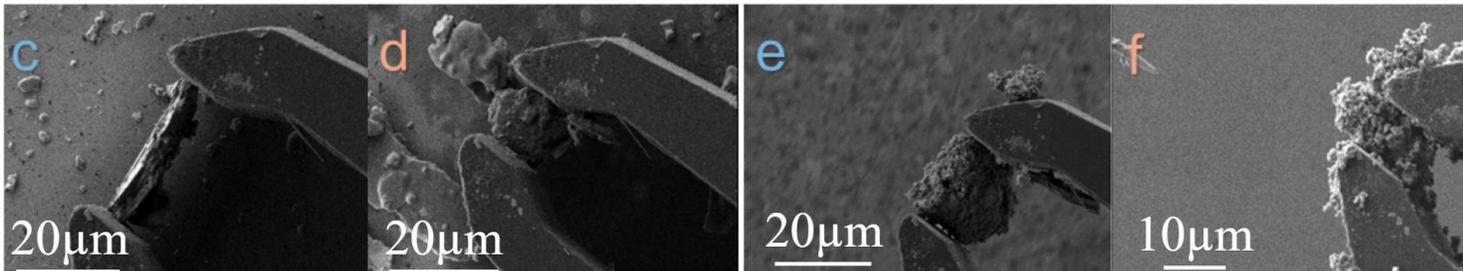


3^{ed} Body MoS₂+Ta

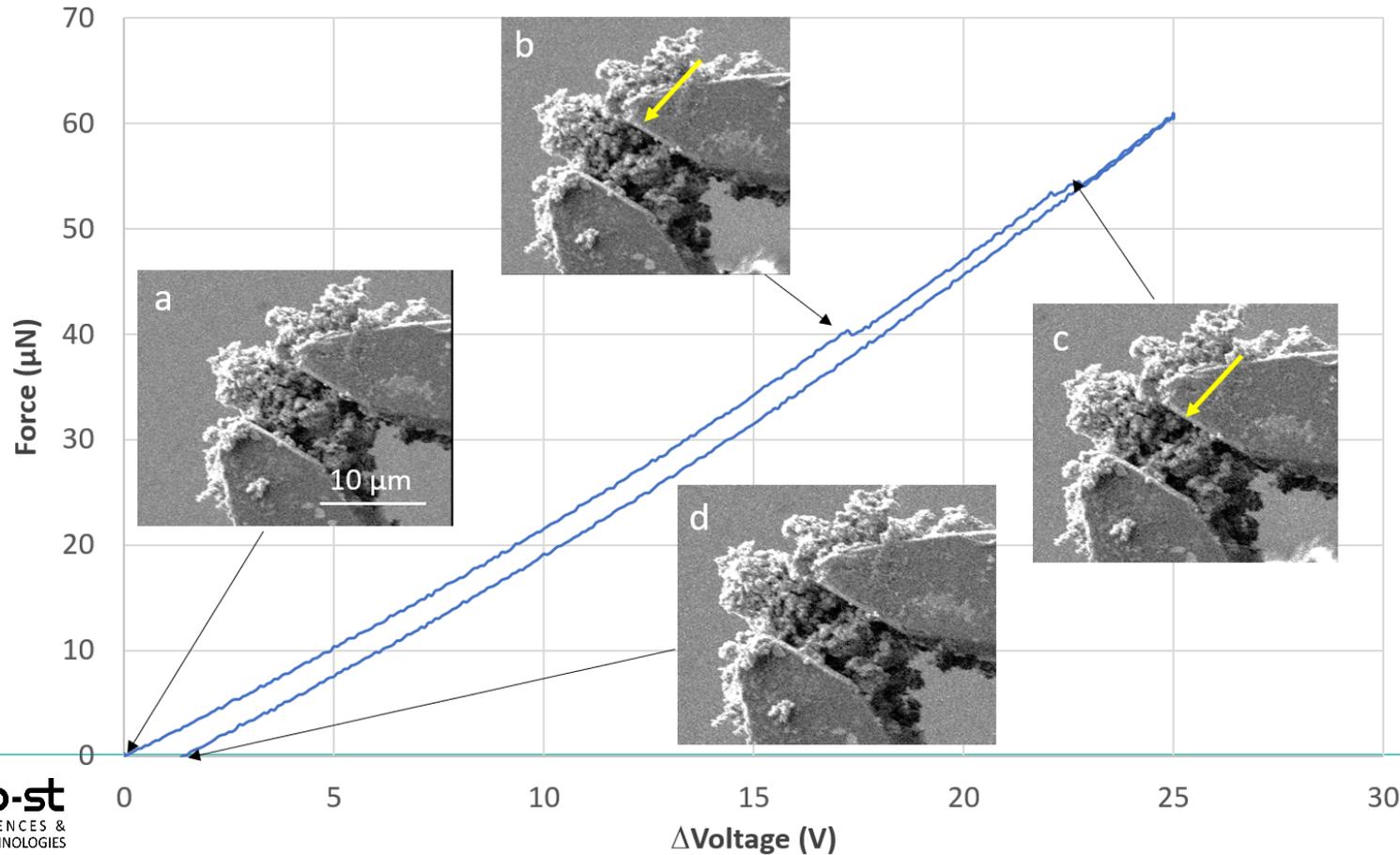
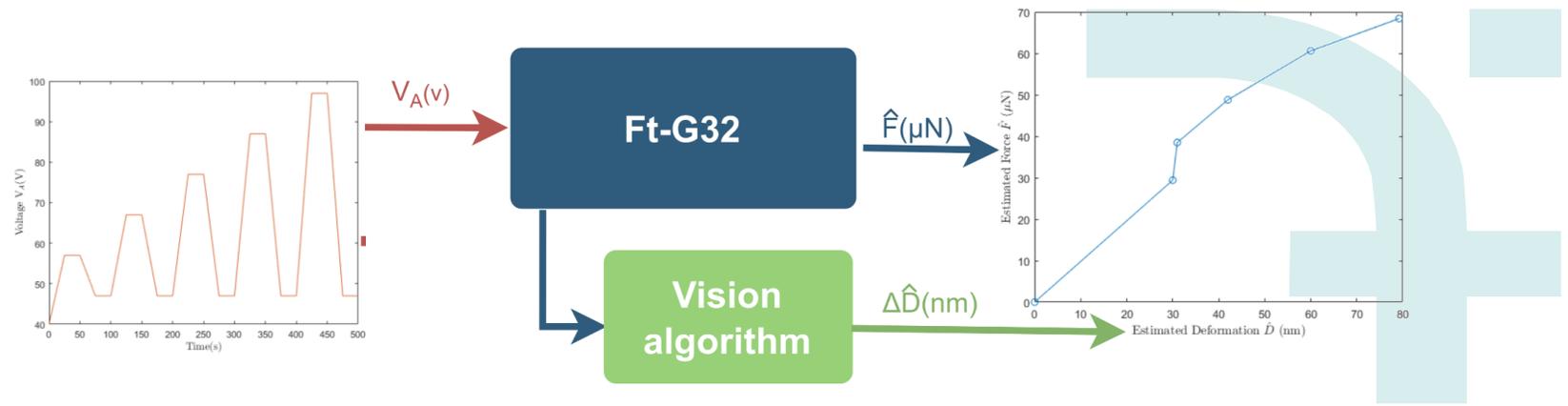
In the range of loading force

⇒ MoS₂ based particles is stiff and elastic

⇒ MoS₂+Ta particles demonstrates different stiffness but always plasticity



COMPARING THE DIFFERENT MATERIALS



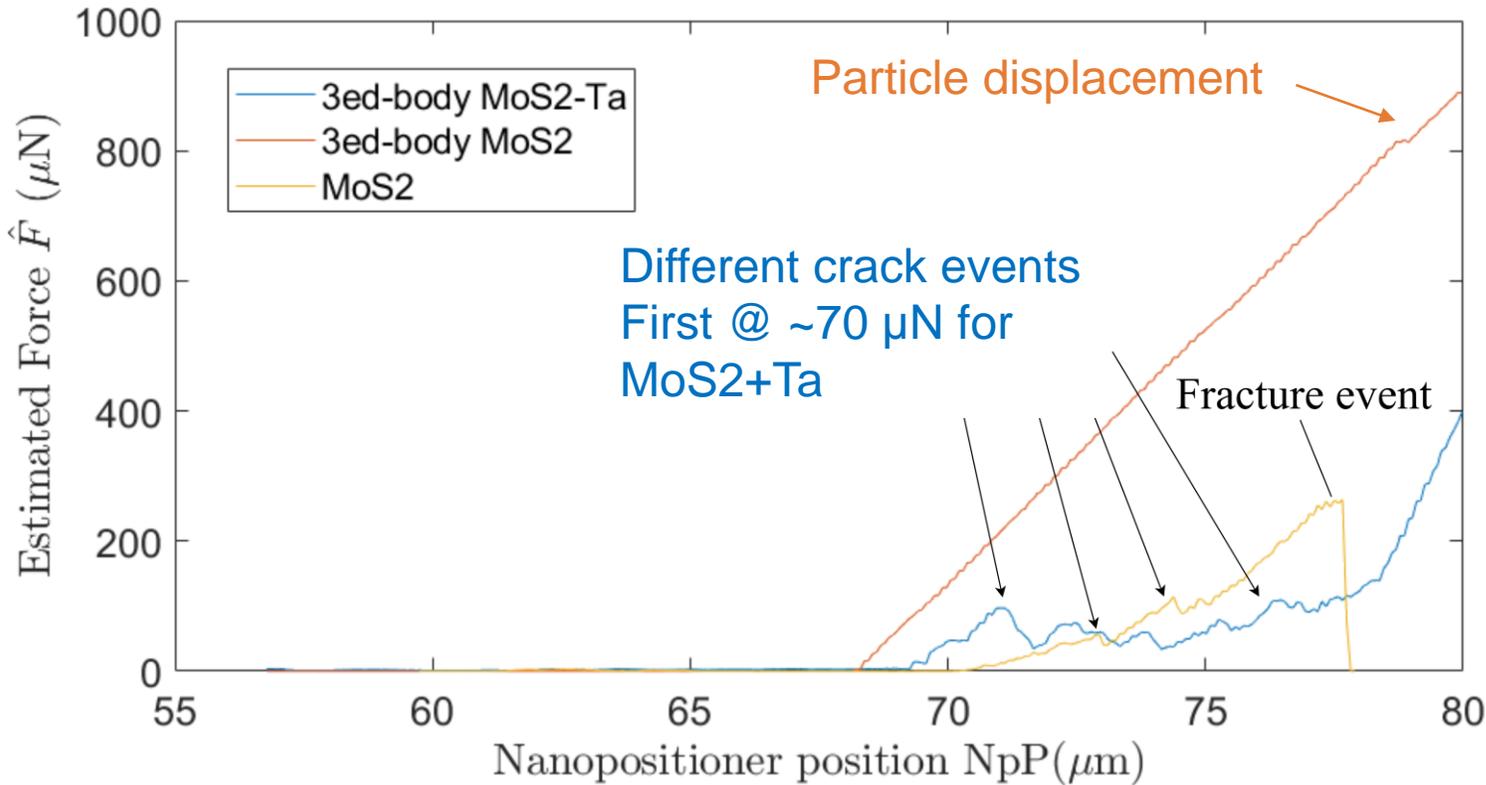
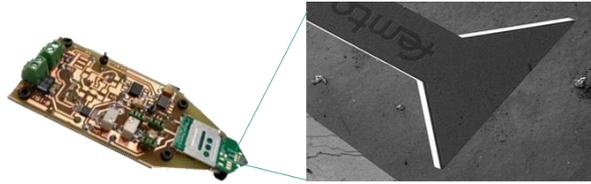
In the range of loading force

⇒ MoS2 based particles is stiff and elastic

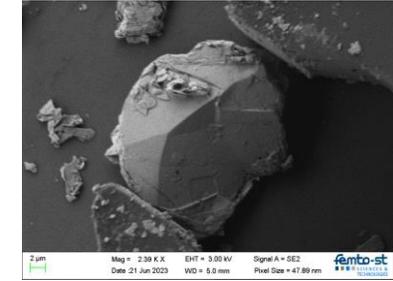
⇒ MoS2+Ta particles demonstrates different stiffness but always plasticity

⇒ Granular ; cracks and flows

COMPARING THE DIFFERENT MATERIALS

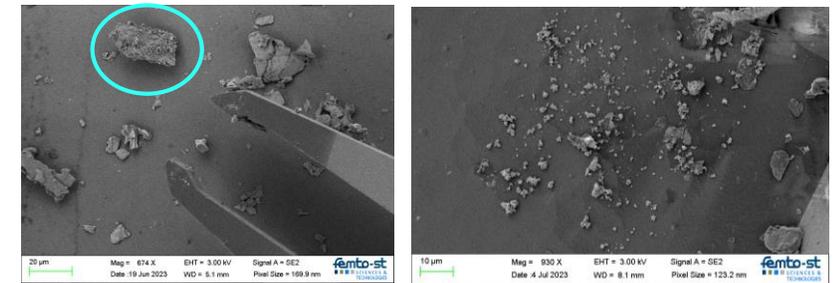


3rd body MoS₂ particle



Very high strength of the third body created from pure MoS₂.

3rd body MoS₂-Ta particle

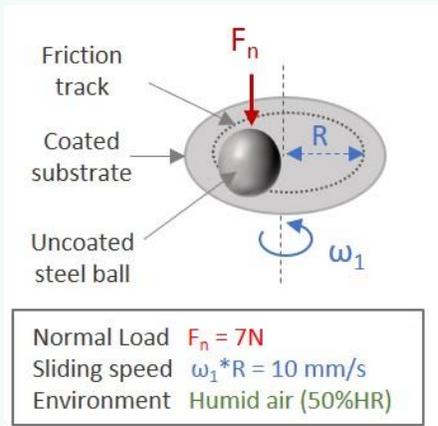


Cracks ; deformation ; destruction

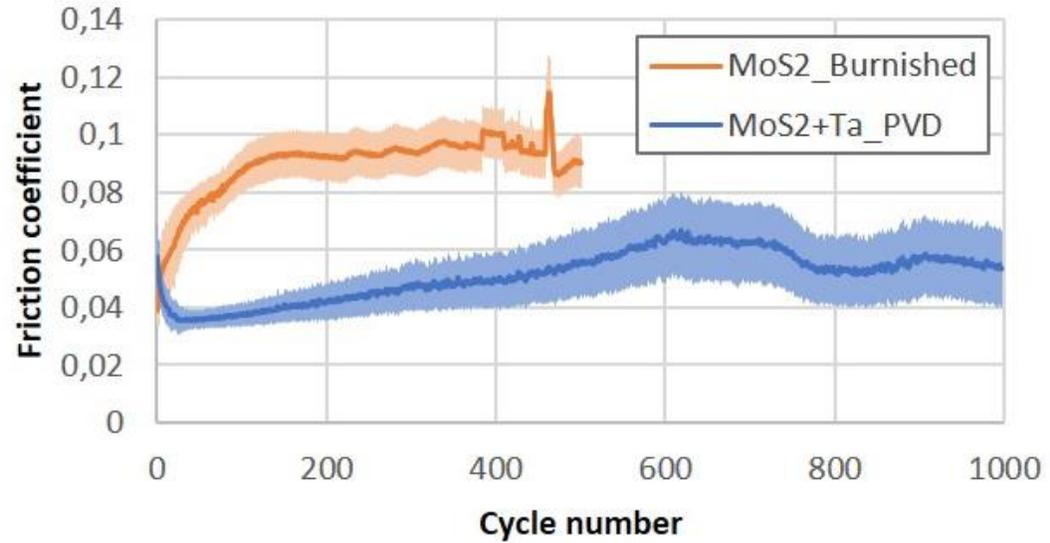
Conclusion

=> Surfaces coated with MoS2

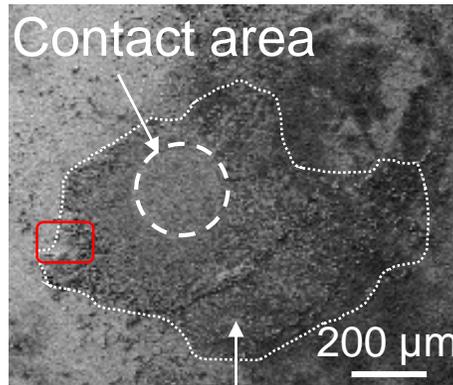
Macroscale Friction tests



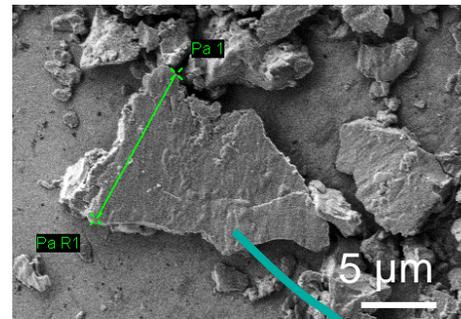
Micro-Nanoscale
microgripper compression
testing in-situ



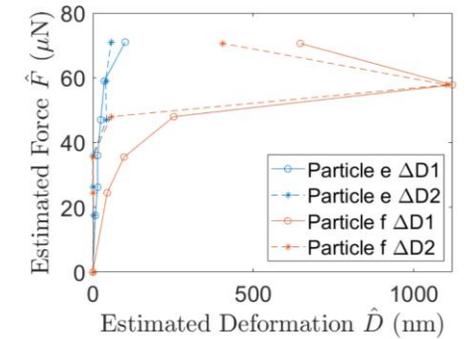
Particle...
..stiff & brittle
..soft & ductile



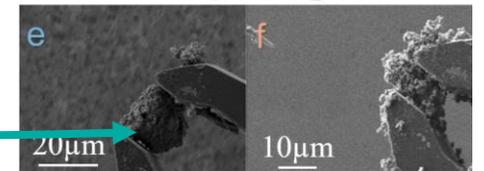
Ejected particles



SEM analysis



3rd Body MoS₂+Ta

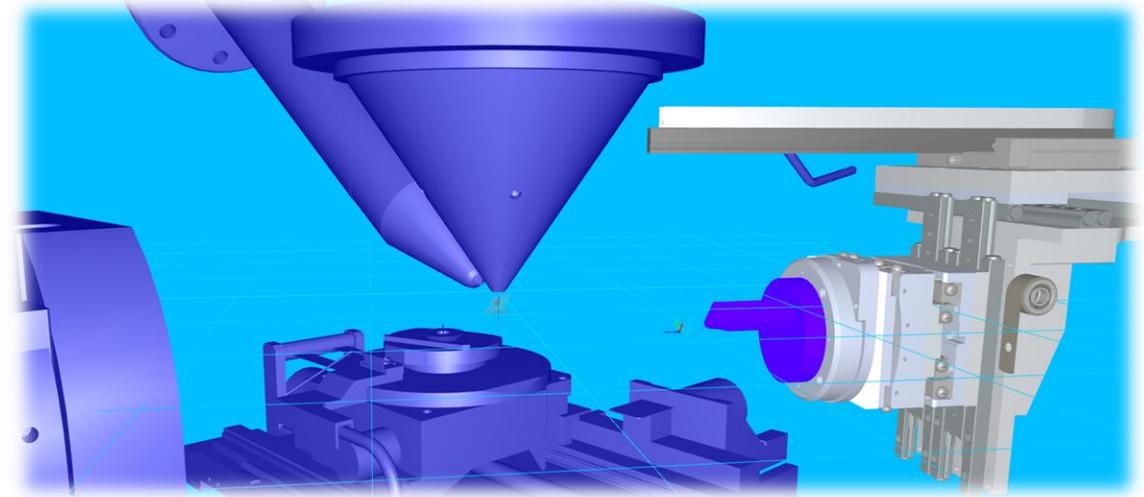


Conclusion

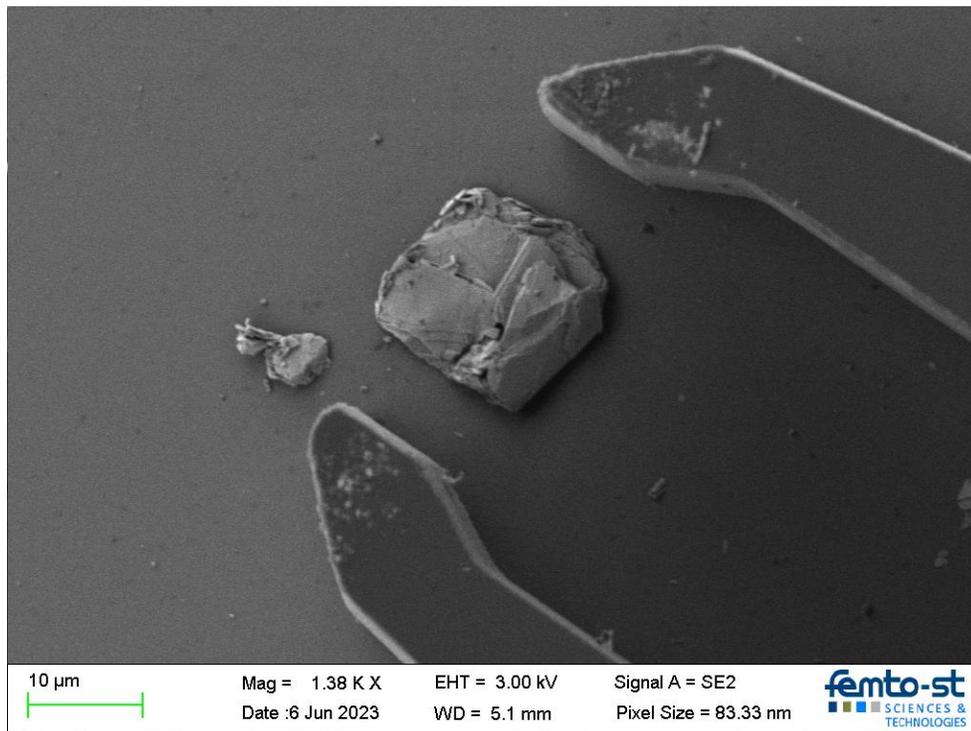
- Robotized system where tested and adapted to successfully work in-situ (SEM).
- Automated macro-scale movements and micro-analysis were successfully conducted.
- A teleoperated manipulation for fine micro-scale movement/gripping were successful.
- The first semi-quantification and manipulation of the selected grains in the micro scale were successfully done in-situ (SEM environment).

Future perspective

Using the Digital Twin that could facilitate the safe and accurate positioning of the robotic systems in different scales, and fully automate the categorizing operation.



Thanks for your attention



Objectifs du GDR :

- Établir un état des lieux des performances et des sources d'erreur des instruments
- Avancer vers la quantitativité des mesures
- Qualifier les mesures sur une échelle de maturité métrologique
- Croiser les compétences et créer du lien
- Coupler les instruments
- Développer et diffuser de nouvelles techniques de traitement des données
- Diffuser les bonnes pratiques

Animation et Contacts :

Direction :

Brice GAUTIER, INL (brice.gautier@insa-lyon.fr)

Axe mécanique :

Guillaume COLAS, FEMTO-ST (guillaume.colas@femto-st.fr)

Axe électrique :

Rosine COQ GERMANICUS, CRISMAT (rosine.germanicus@unicaen.fr)

Axe nano-bioparticules :

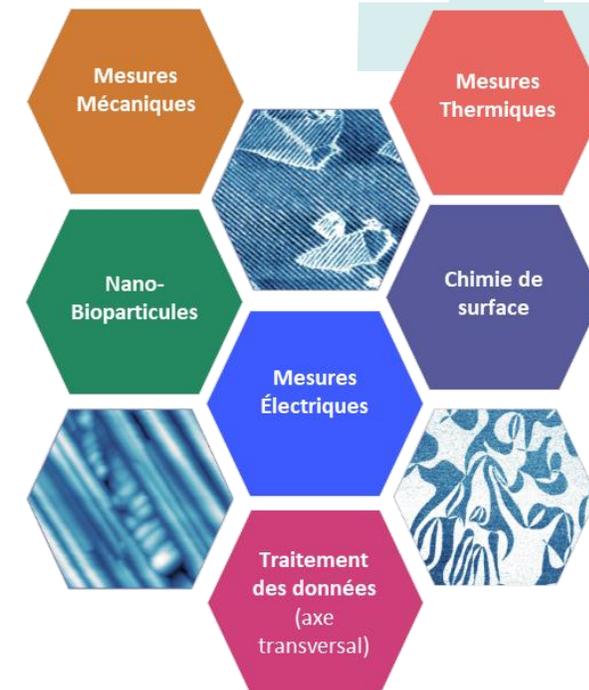
Céline ÉLIE CAILLE, FEMTO-ST (celine.elie@femto-st.fr)

Axe thermique :

Séverine GOMES, CETHIL (severine.gomes@insa-lyon.fr),

Axe chimie de surface :

Anthony SZYMCZYK, ISCR (anthony.szymczyk@univ-rennes.fr)



Pour nous rejoindre :

www.wooclap.com

Code : RRIXRH

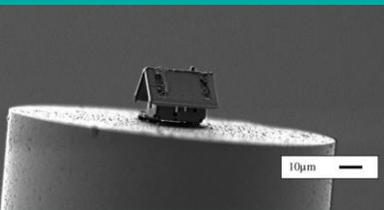




in-situ SEM Robotic-based Selection, Manipulation and Characterization of 3D Microscale Particles

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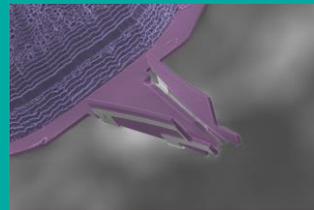
Cédric Clévy, Professor, FEMTO-ST, Franche-Comté University



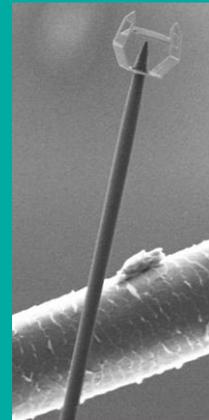
[J. Vac. Sc. 2018]



[Opt. Cont. 2022]



[Adv. Mat.. 2021]



[RA-L. 2021]

Part of the **DyNaBot** project, funded by the ANR.

